

How Does Batch Normalization Help Optimization?

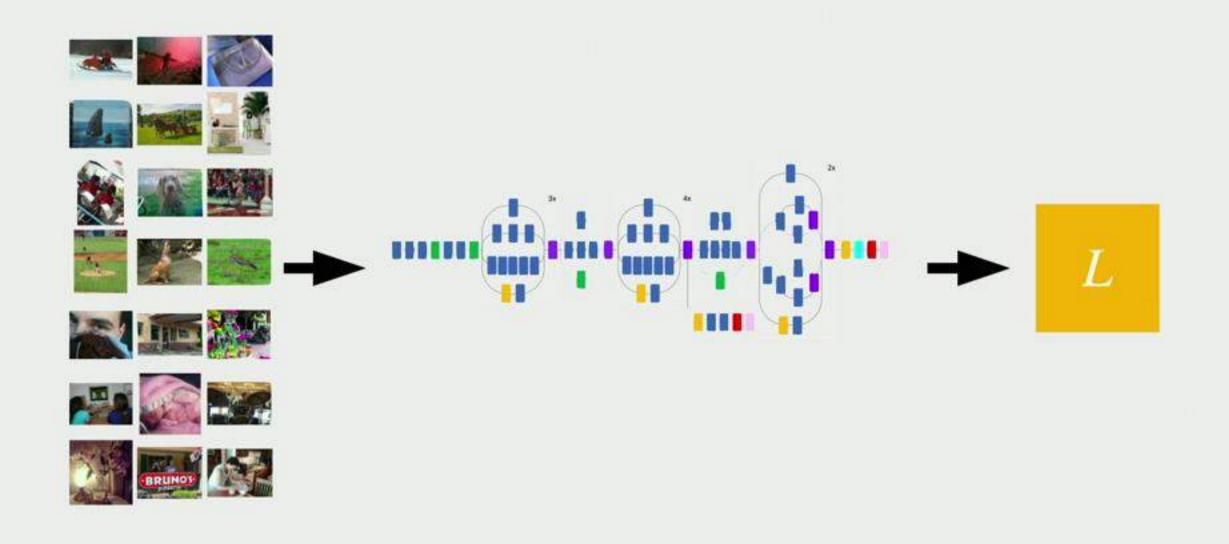
Andrew Ilyas

The Deep Learning Revolution

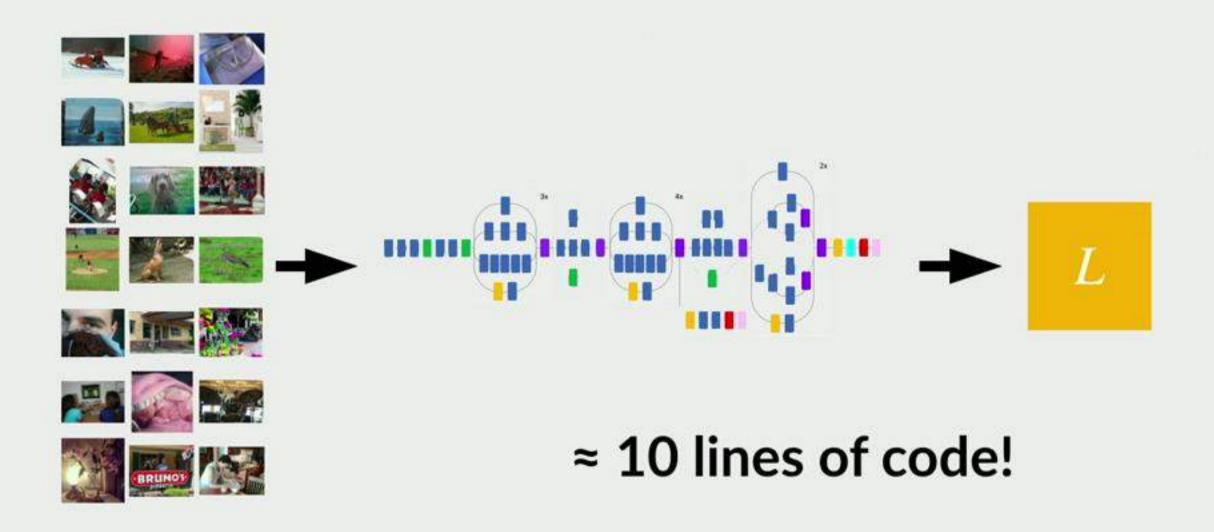


Advances in Hardware, Data and Algorithms

At the Core: Deep Neural Networks



At the Core: Deep Neural Networks



Behind the Scenes

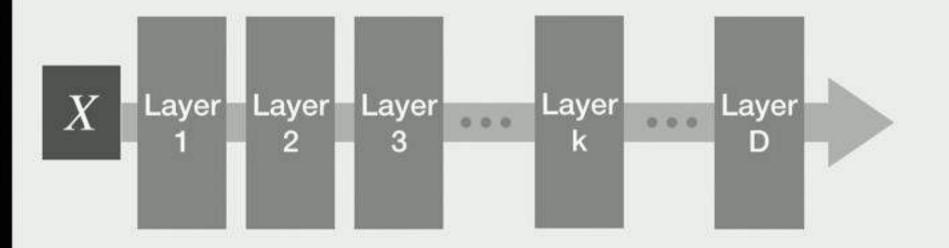
Training DNNs is simple, but difficult (we just have a toolkit!)

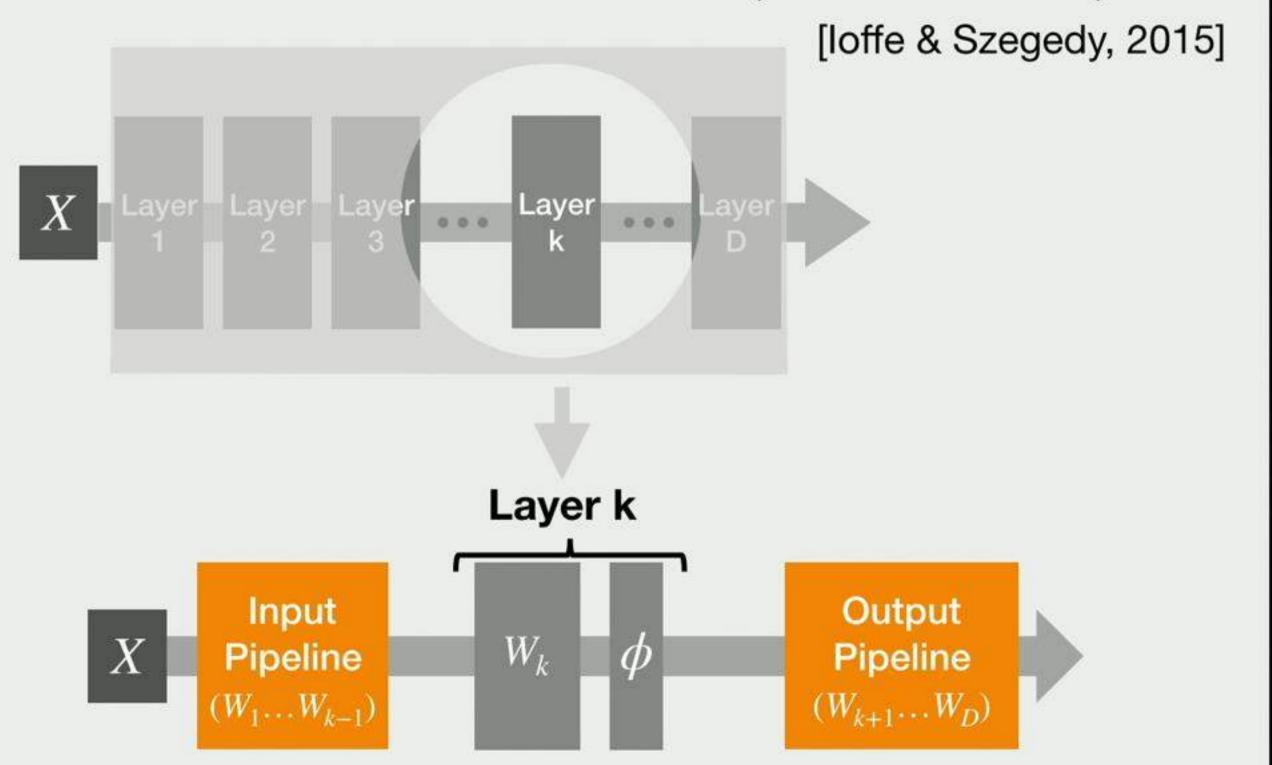
Many core components poorly understood (but do work)

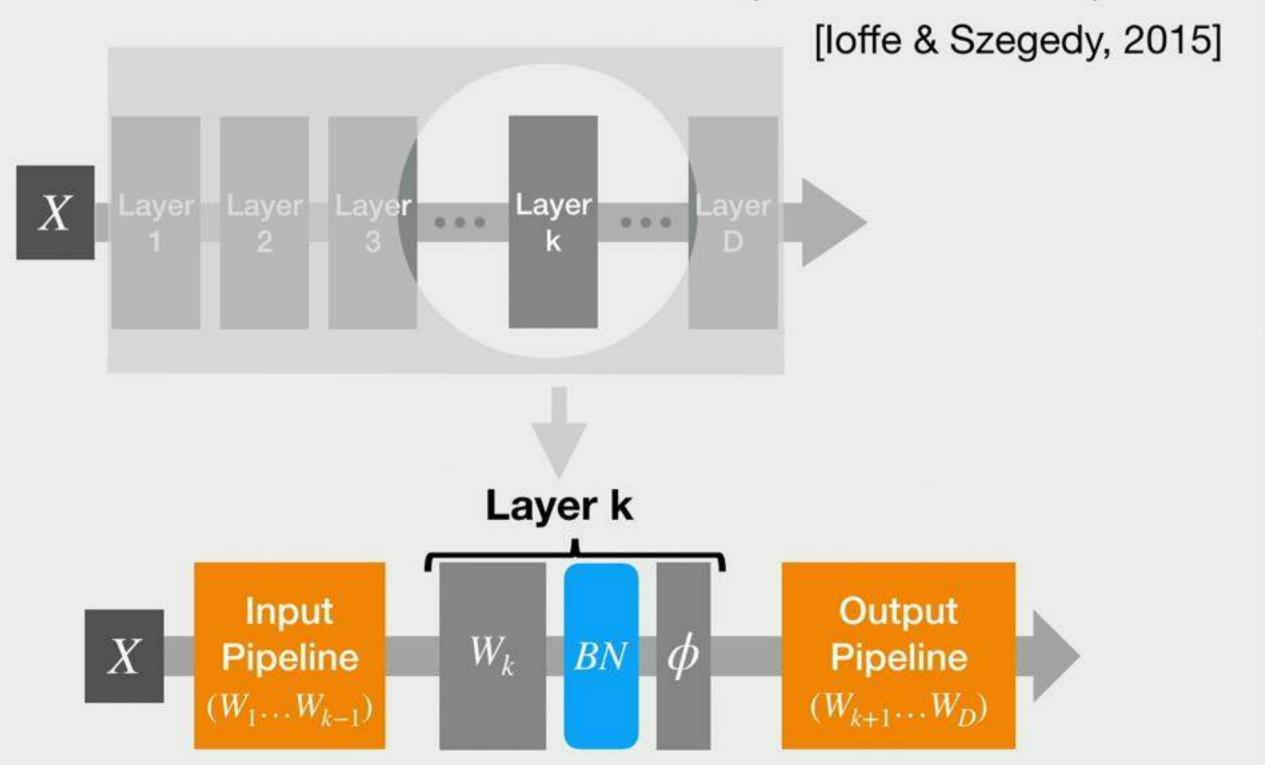
General goal: Build a better understanding of the modern machine learning toolkit

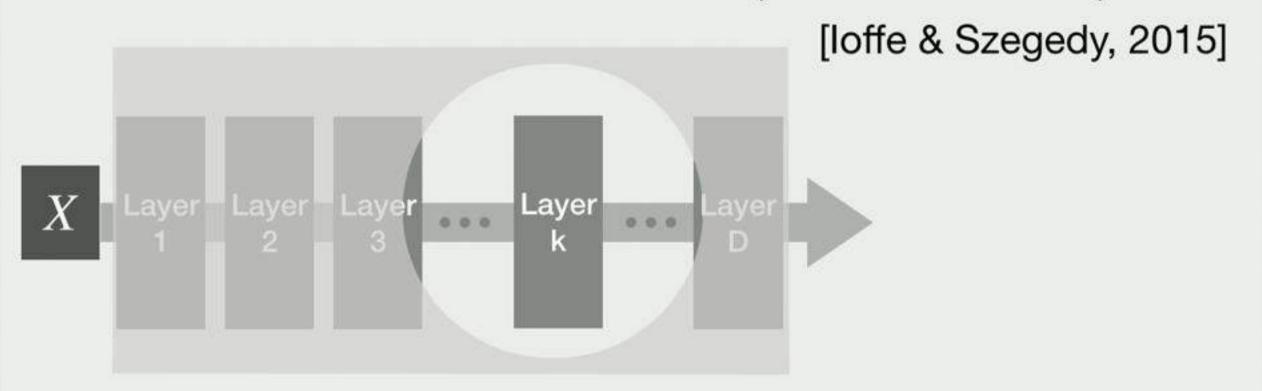
Today:

A closer look at Batch Normalization

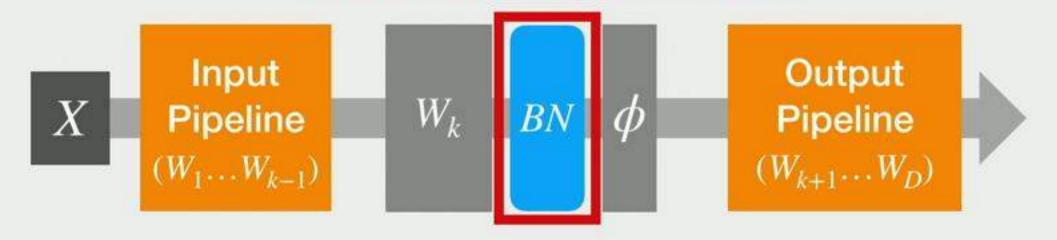


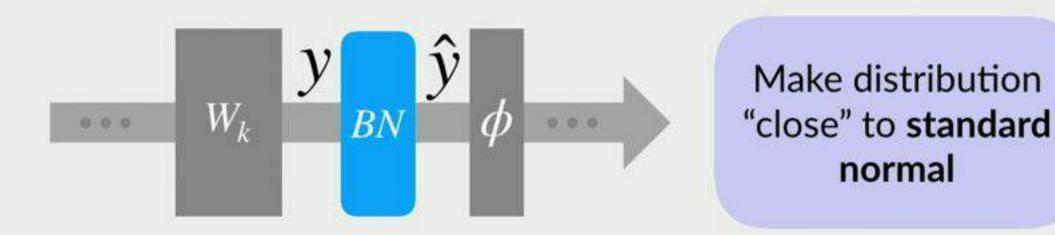




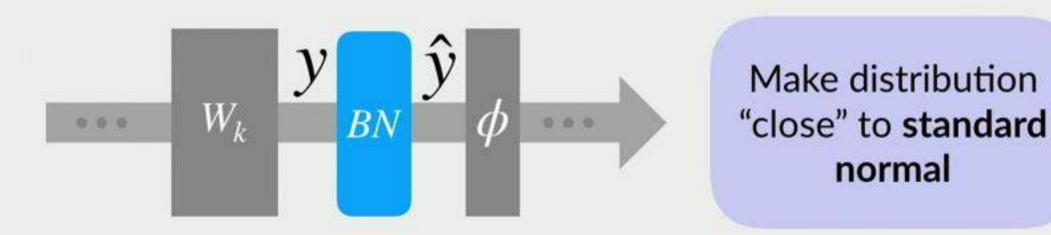


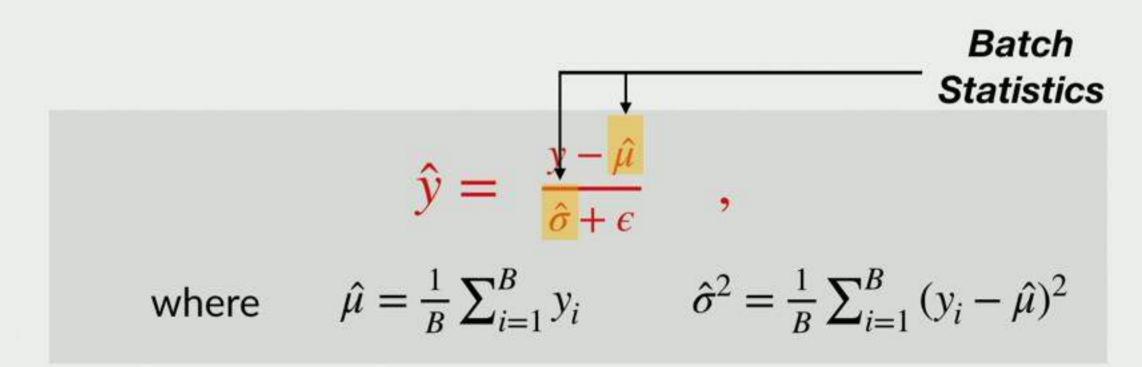
whitening transformation



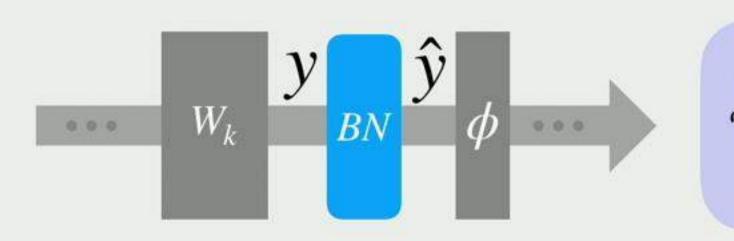


$$\hat{y} = \frac{y-\mu}{\sigma+\epsilon} \ ,$$
 where
$$\mu = \mathbb{E}[y] \quad \sigma^2 = Var(y)$$

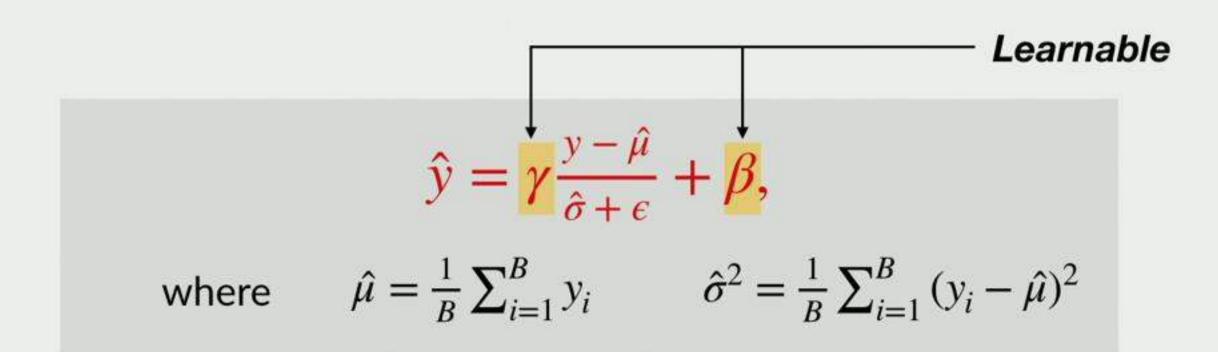




[loffe & Szegedy, 2015]



Make distribution "close" to **standard normal**



Why do we use BatchNorm?

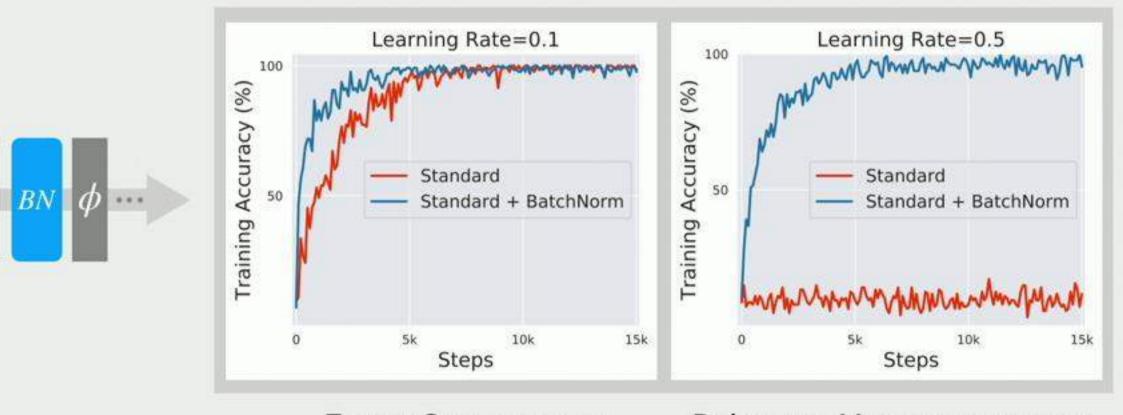
BatchNorm's Role in Optimization

Network without BatchNorm



BatchNorm's Role in Optimization

Network with BatchNorm



Faster Convergence

Robust to Hyperparameters

BatchNorm's Role in Optimization

Network with BatchNorm



Faster Convergence

Robust to Hyperparameters

One of the most influential techniques in DNN training

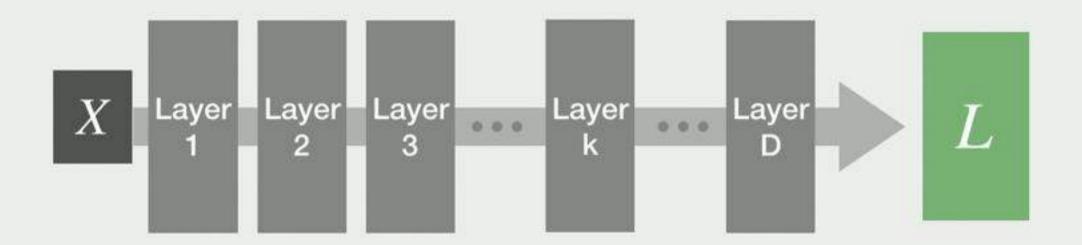
Default in almost all standard architectures

How does BatchNorm help?

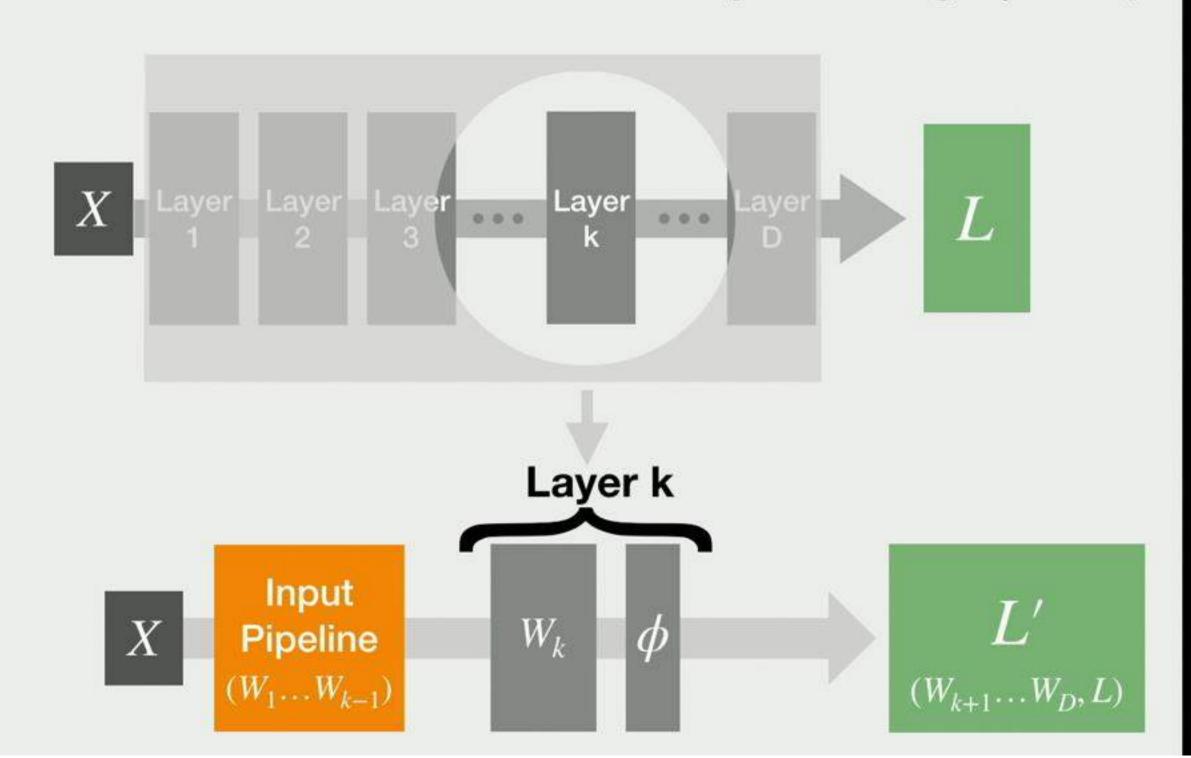
How does BatchNorm help?

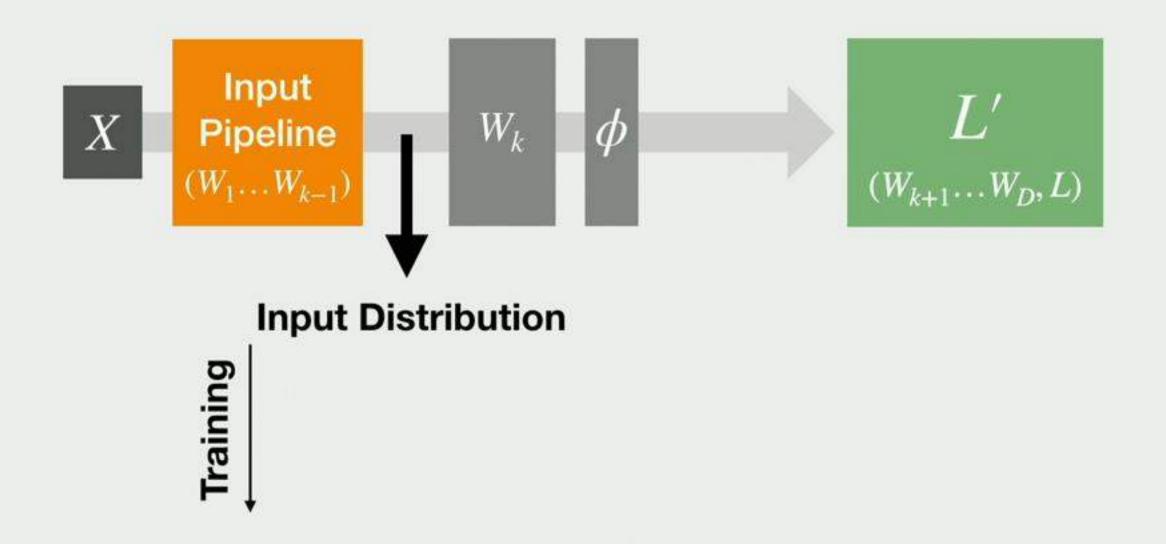
The story so far

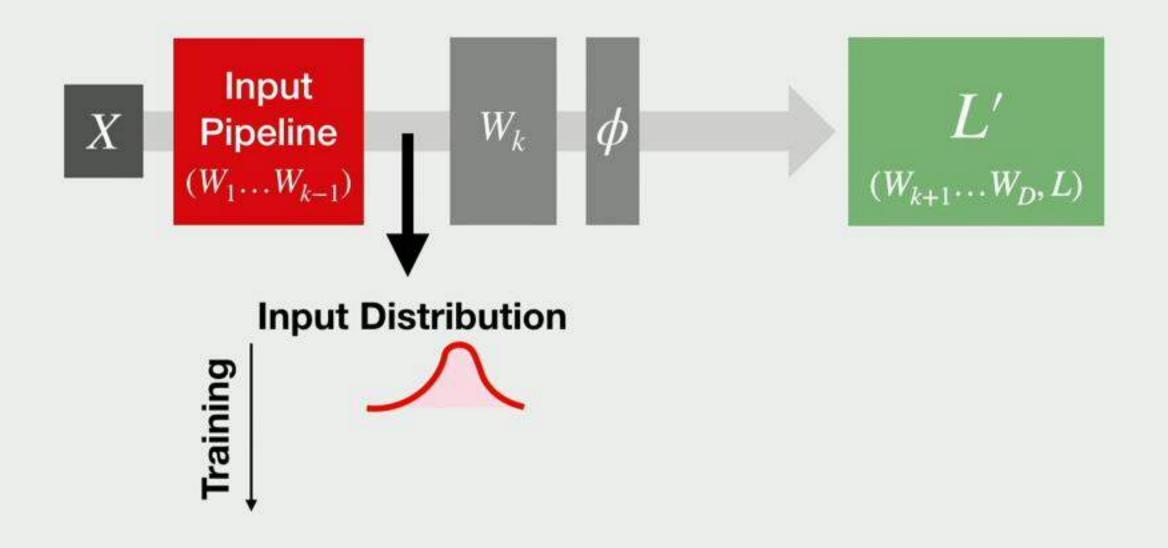
[loffe & Szegedy, 2015]

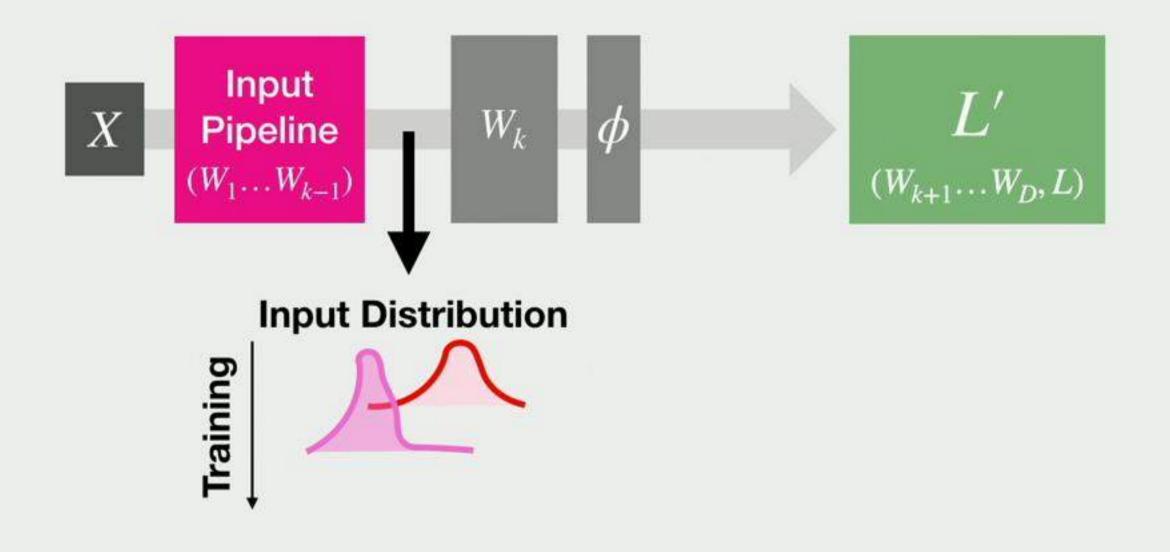


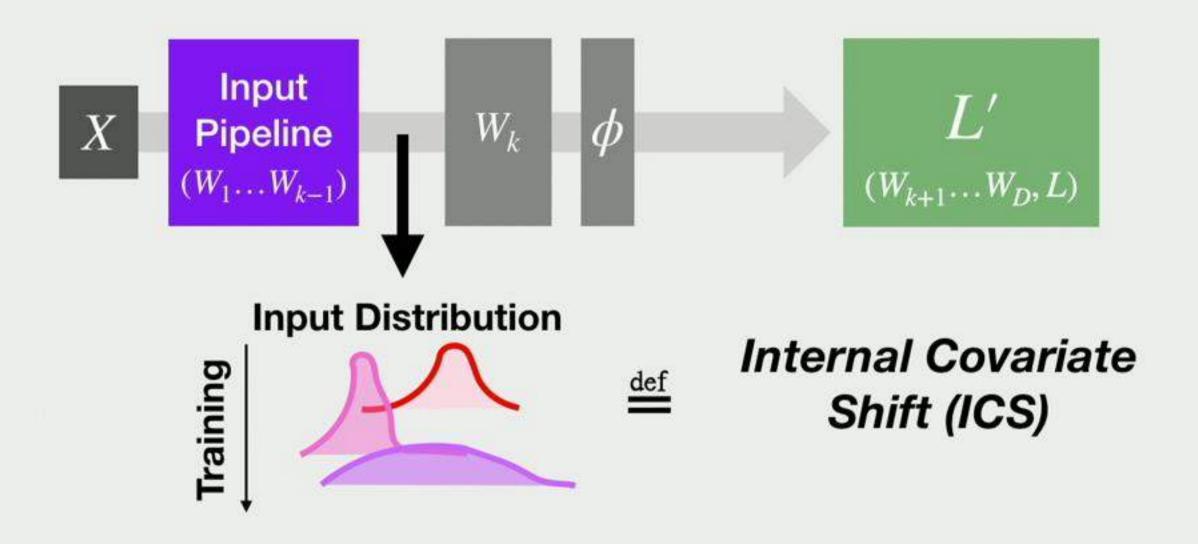
Training ≈ solving an optimization problem at each layer



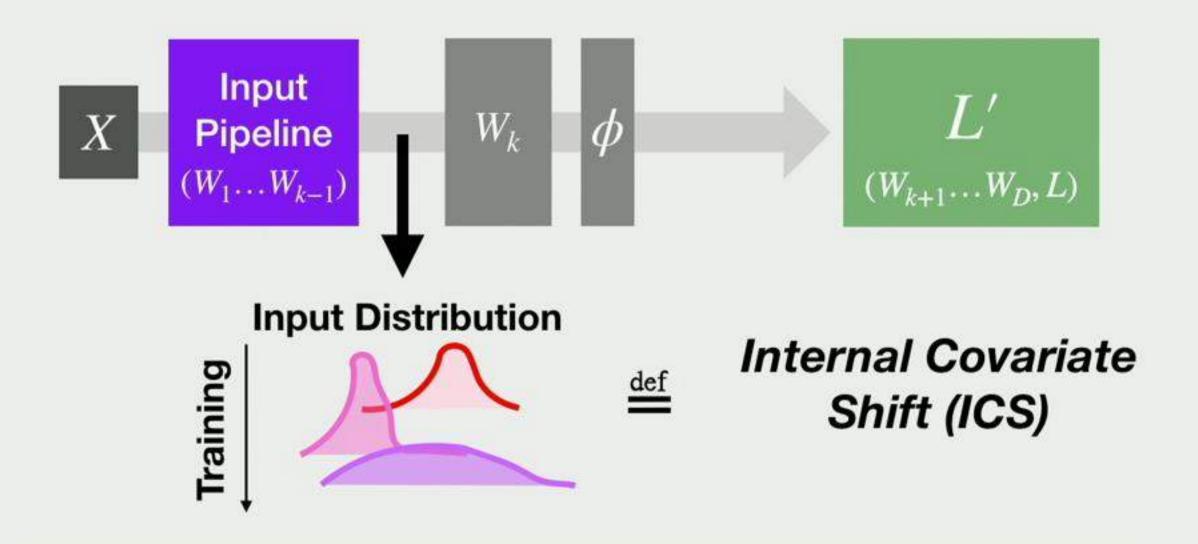




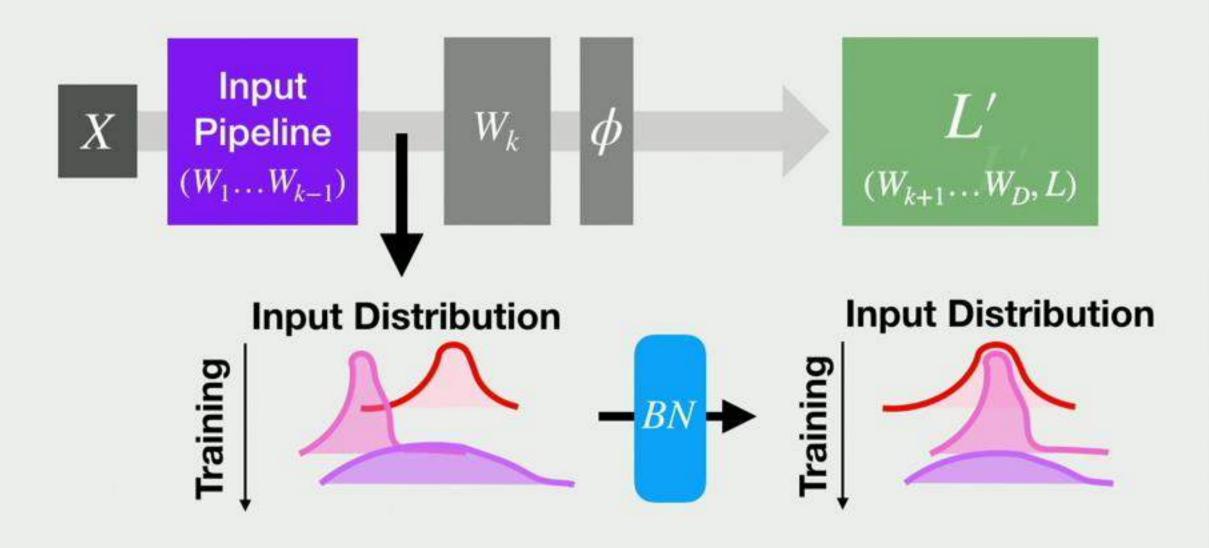




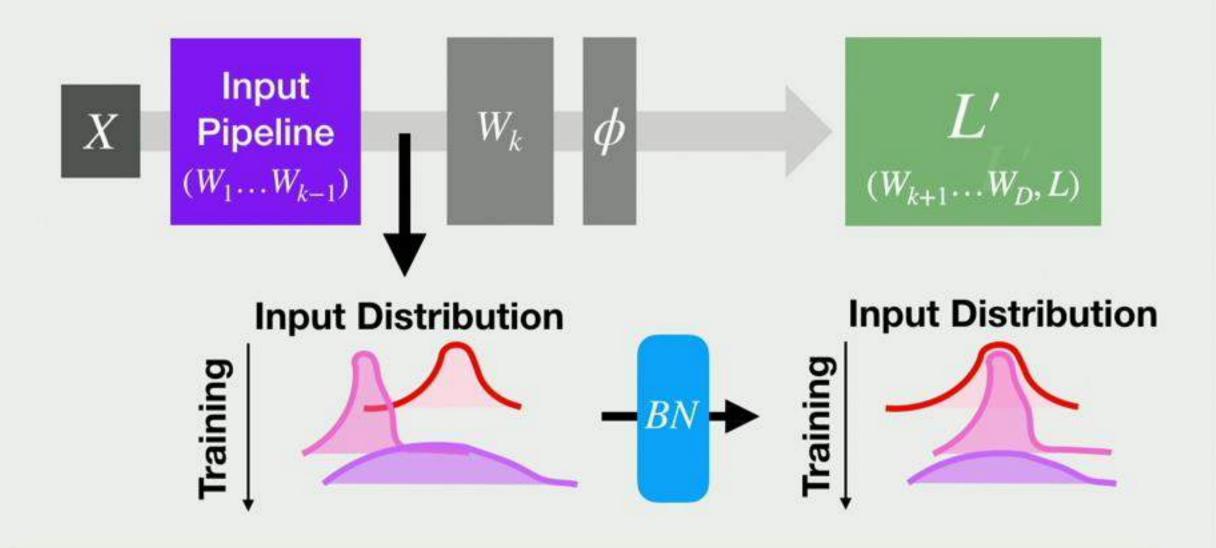
[loffe & Szegedy, 2015]



[IS15]: Layers need to continually adapt.



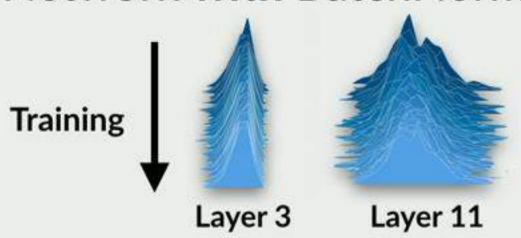
[loffe & Szegedy, 2015]

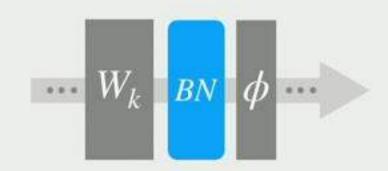


[IS15]: Reducing internal covariate shift is the key to BN's success

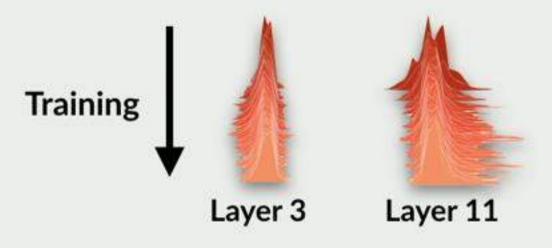
A Closer Look at Internal Covariate Shift

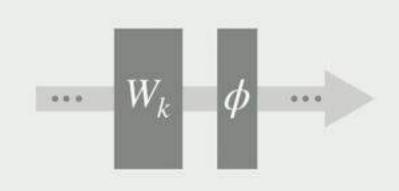
Network with BatchNorm:





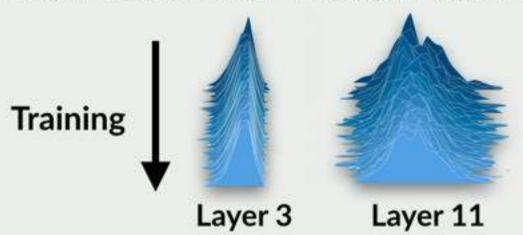
Network without BatchNorm:

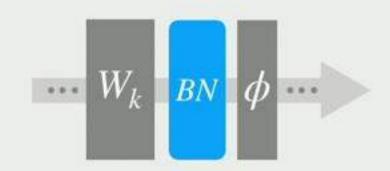




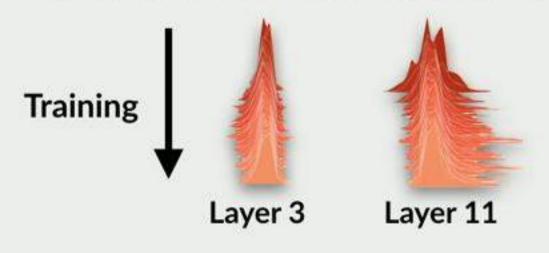
A Closer Look at Internal Covariate Shift

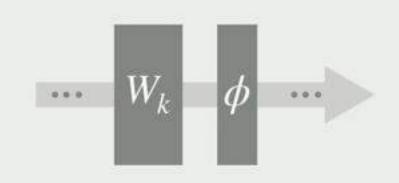
Network with BatchNorm:





Network without BatchNorm:

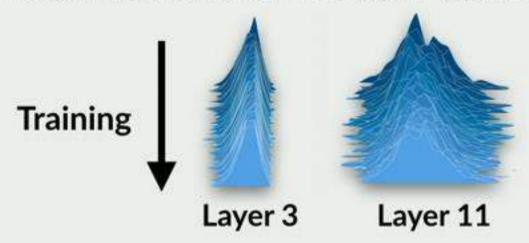




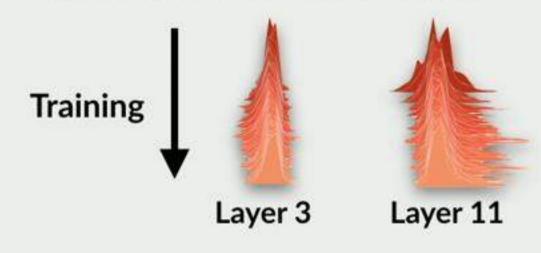
No difference in stability ...

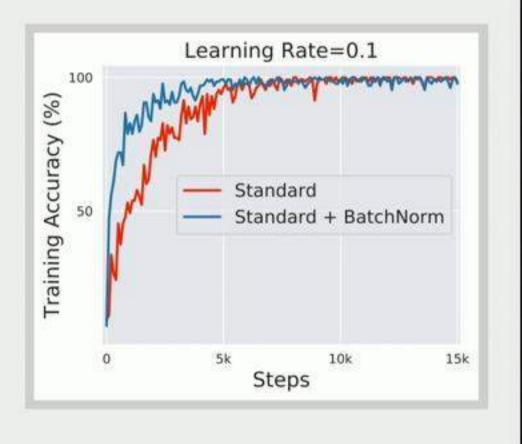
A Closer Look at Internal Covariate Shift

Network with BatchNorm:



Network without BatchNorm:





... despite large difference in performance

The Impact of Internal Covariate Shift

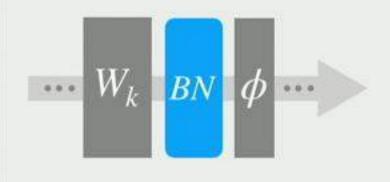
What happens if we increase internal covariate shift?



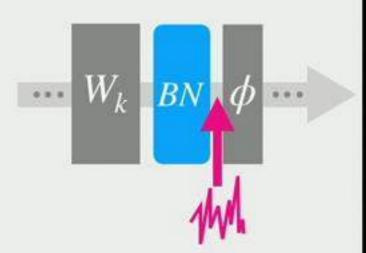
Network with BN

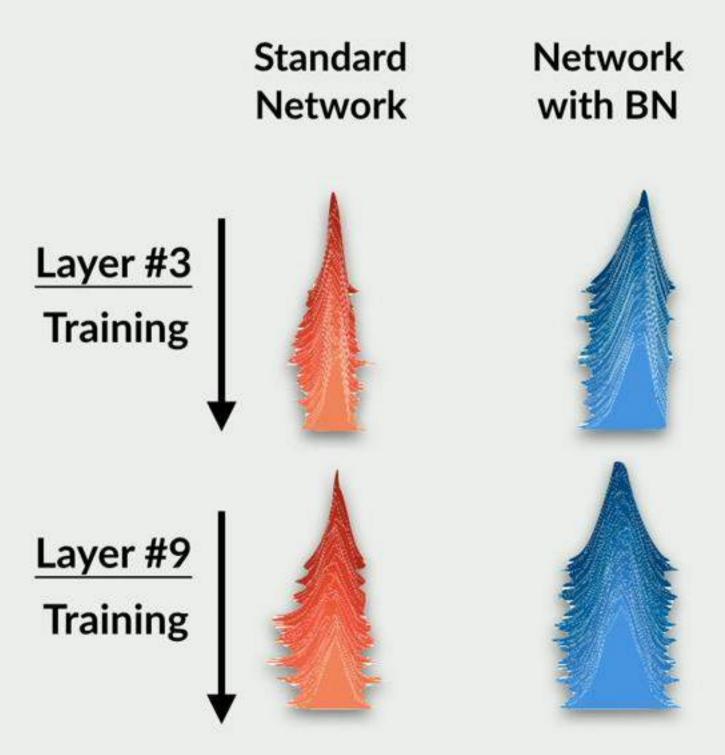
Non-stationary noise (non-zero mean and variance)

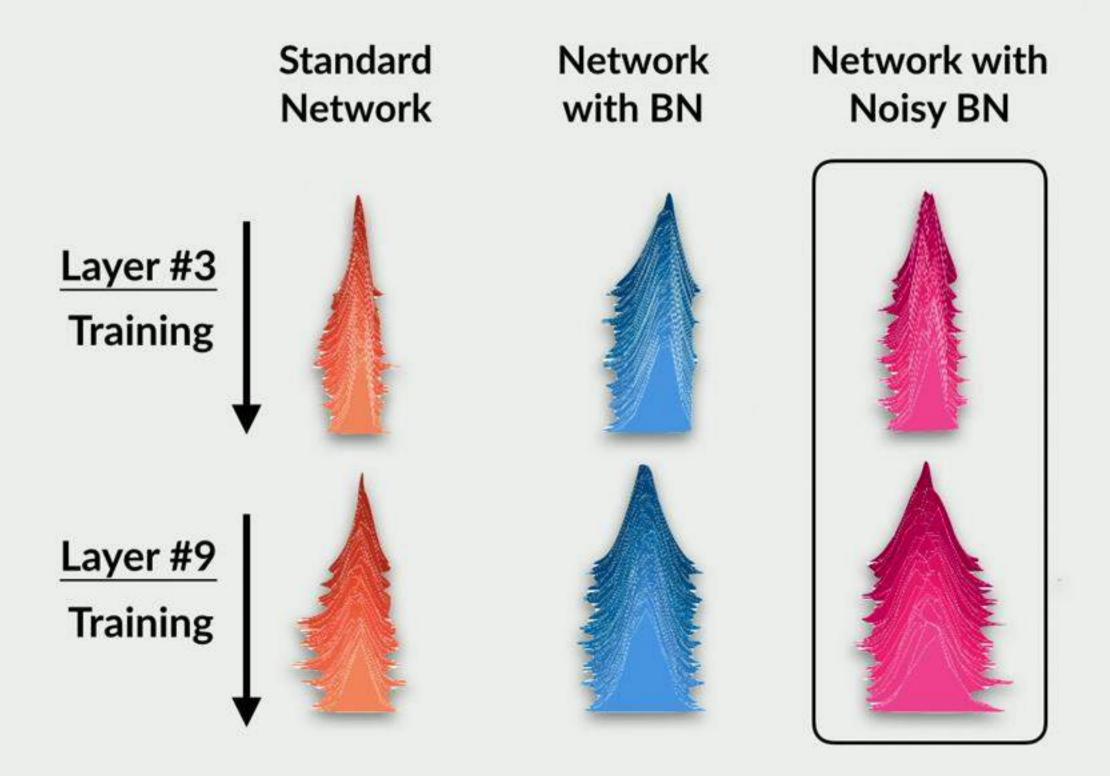
Network with "Noisy" BN



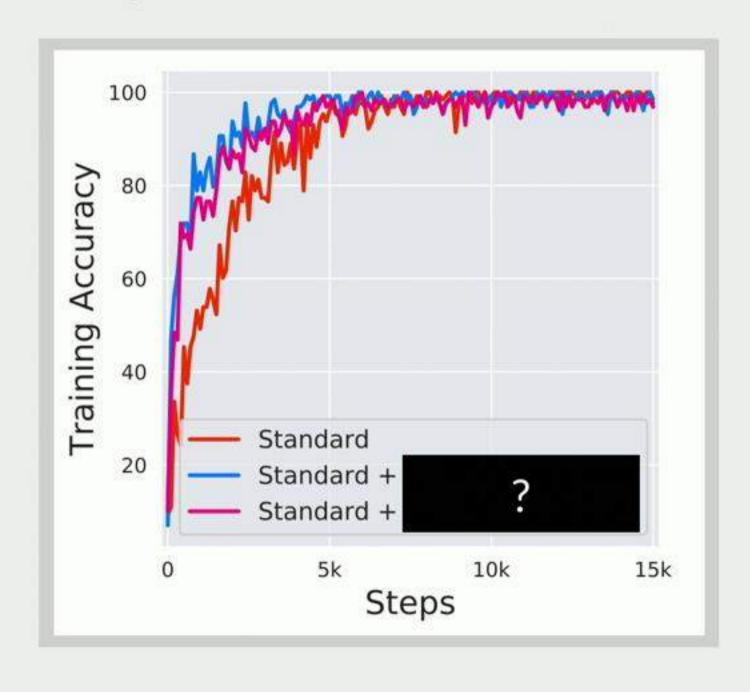




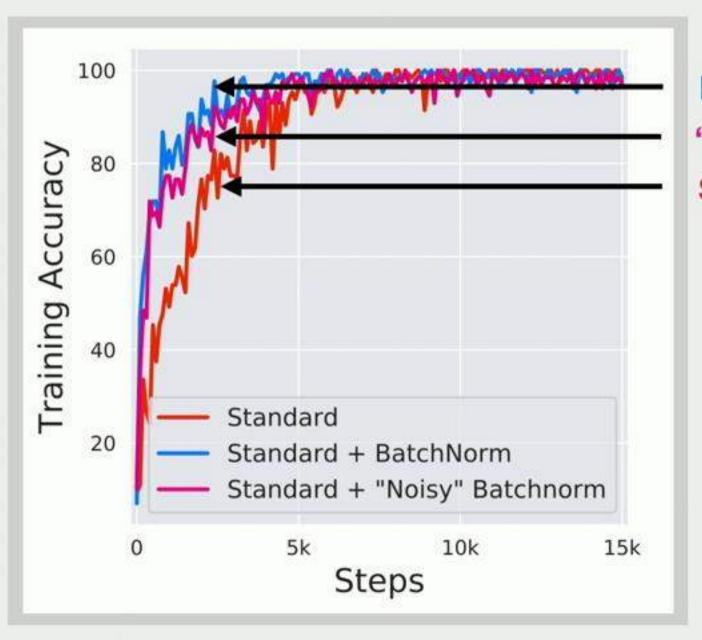






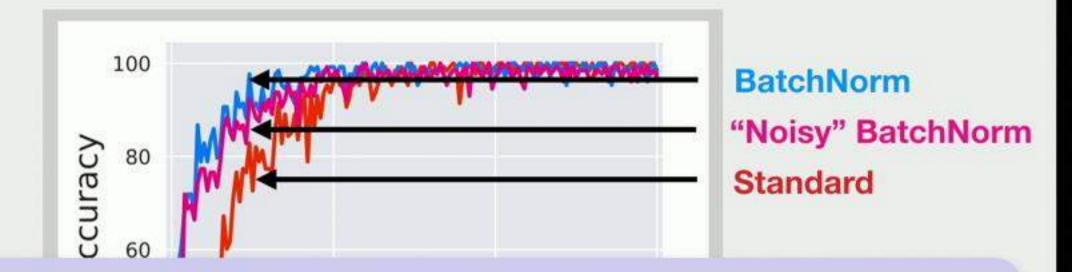


"Noisy" BatchNorm Activations

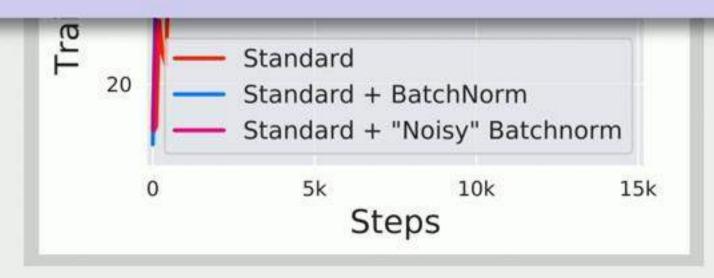


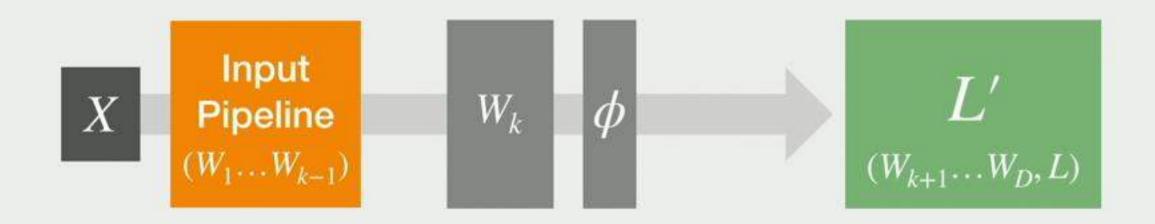
BatchNorm
"Noisy" BatchNorm
Standard

"Noisy" BatchNorm Activations



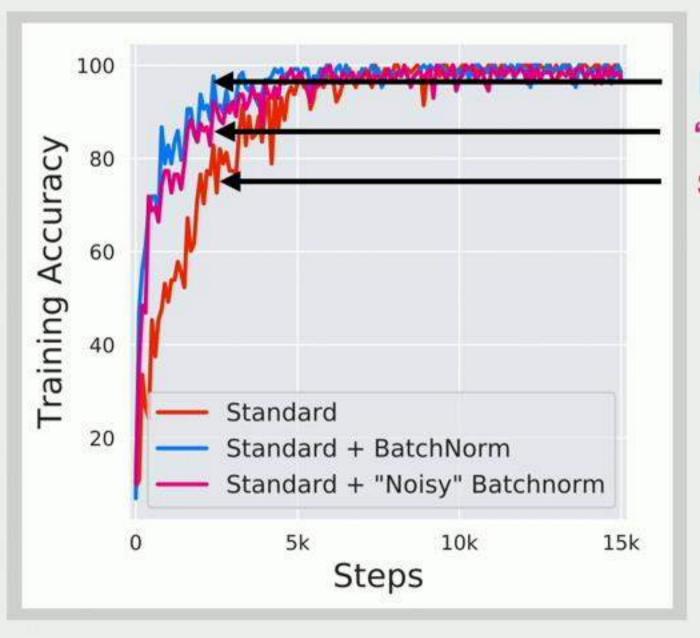
Distributional instability has almost no impact on performance!



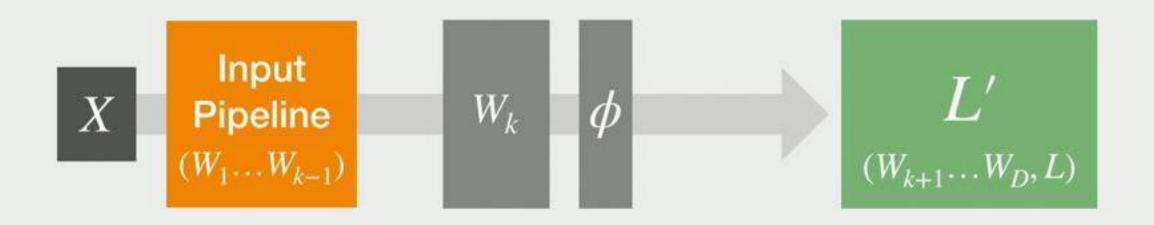


We train our models with first-order methods

"Noisy" BatchNorm Activations

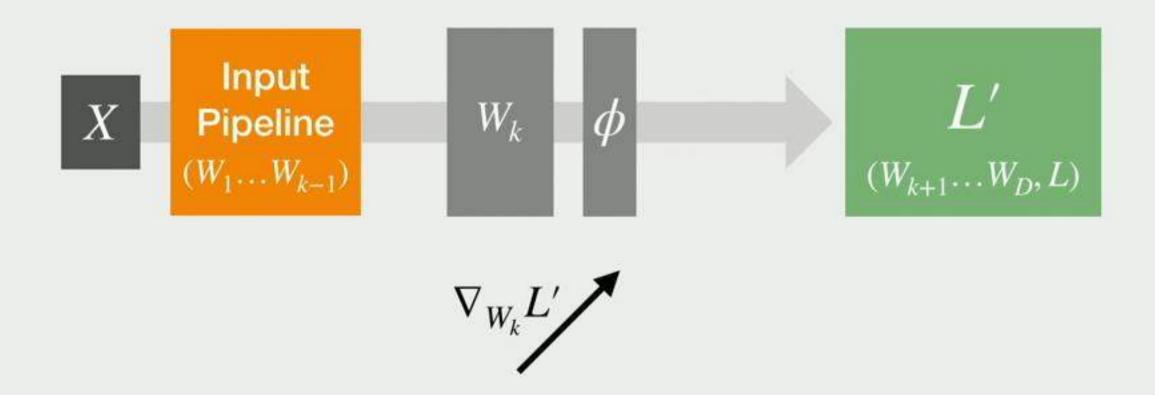


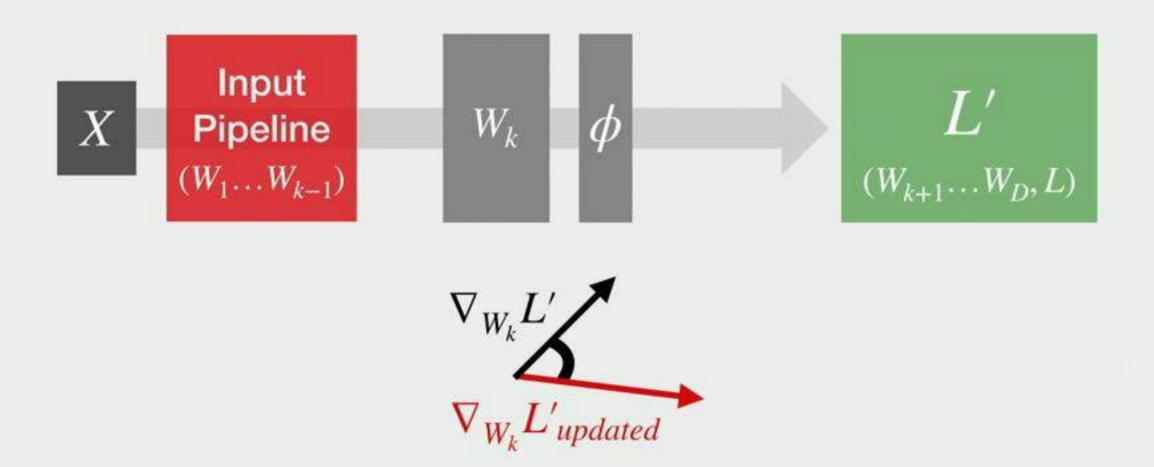
BatchNorm
"Noisy" BatchNorm
Standard



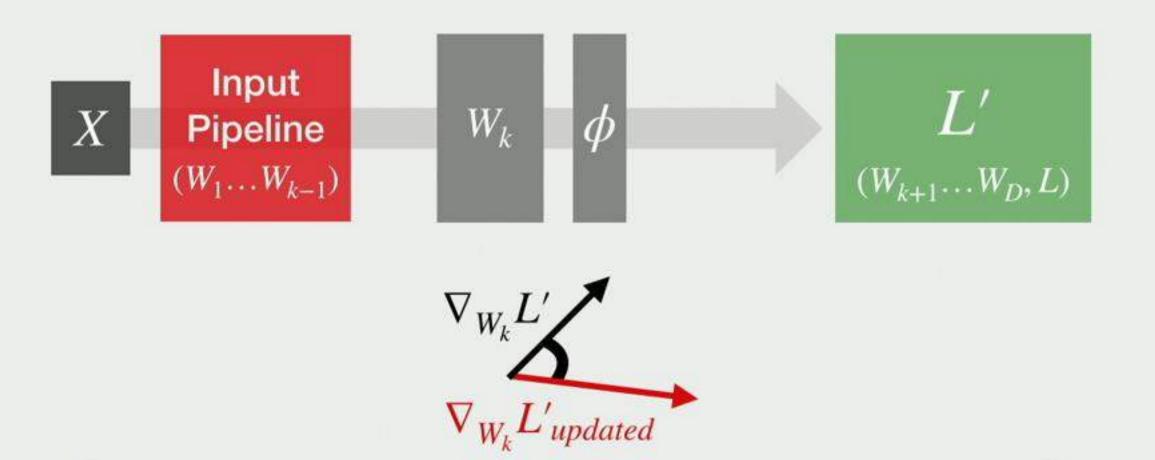
We train our models with first-order methods

How do updates to previous layers affect the **gradient** for this layer?

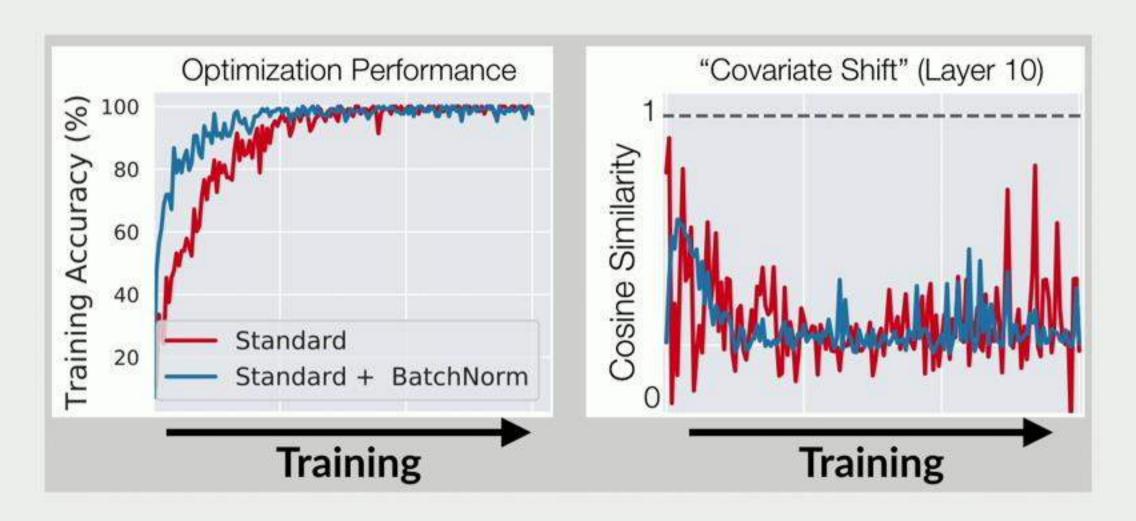


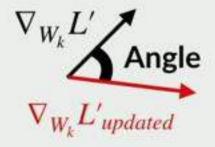


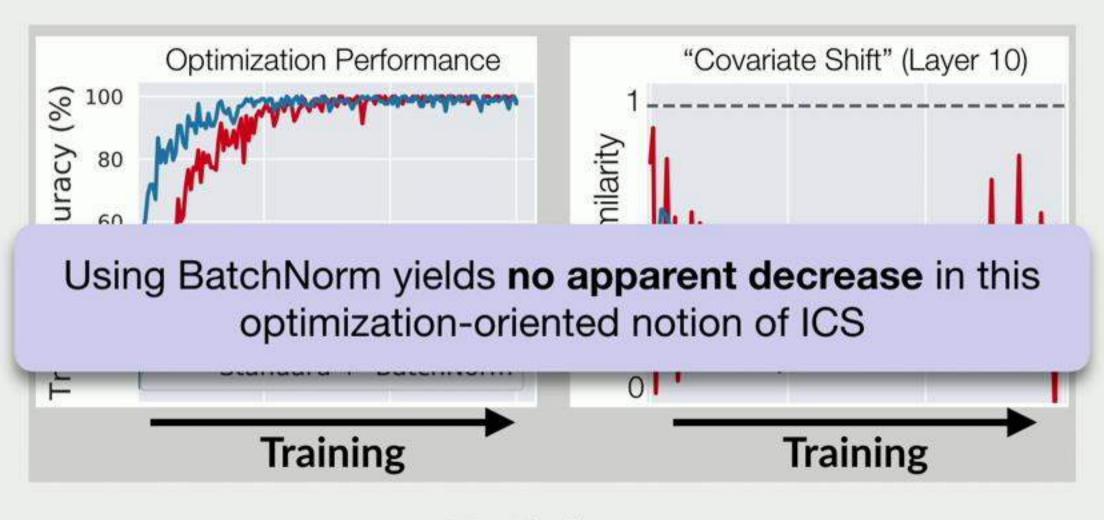
Change in gradients ← change in optimization problem



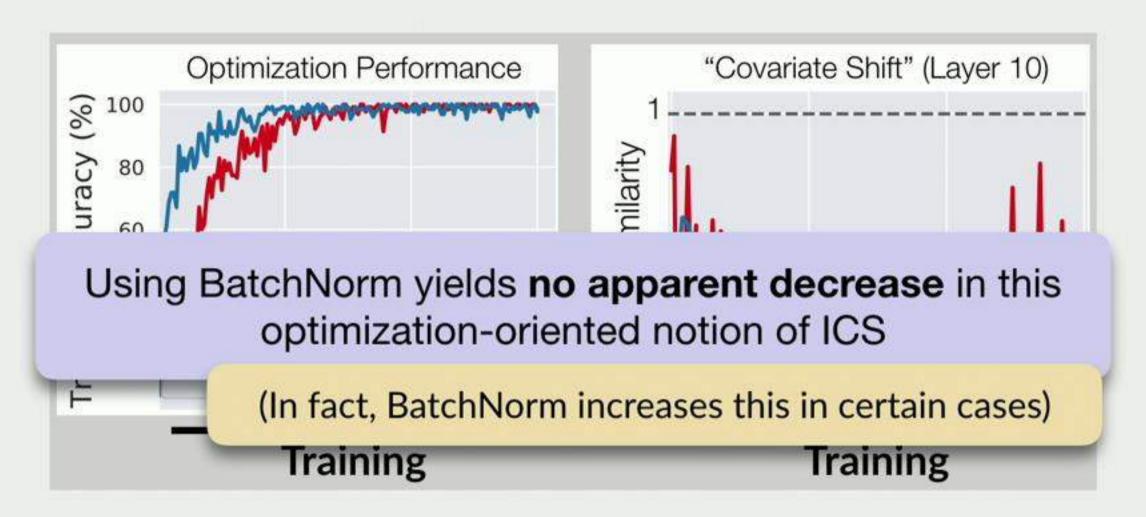
Does BatchNorm increase this notion of stability?

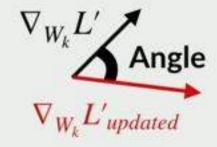












How does BatchNorm help?

How does BatchNorm help?

So far: Internal covariate shift connection unclear

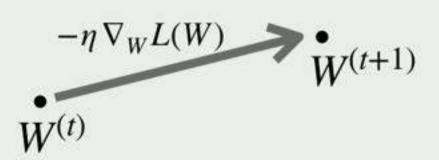
But BatchNorm is effective: Why?

Recall: We use first-order methods in practice

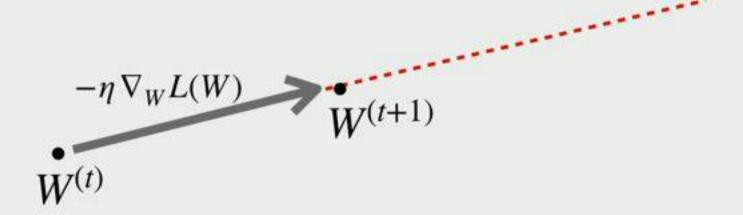
Recall: We use first-order methods in practice



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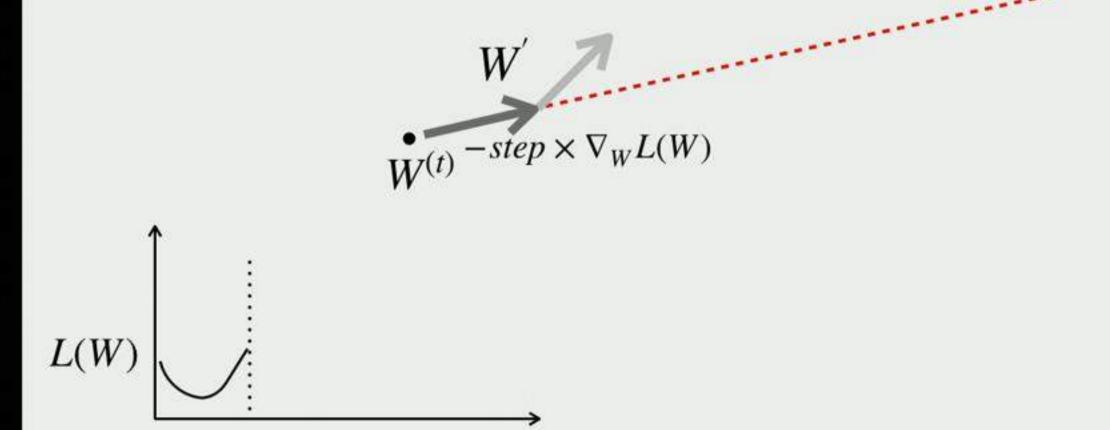
Recall: We use first-order methods in practice

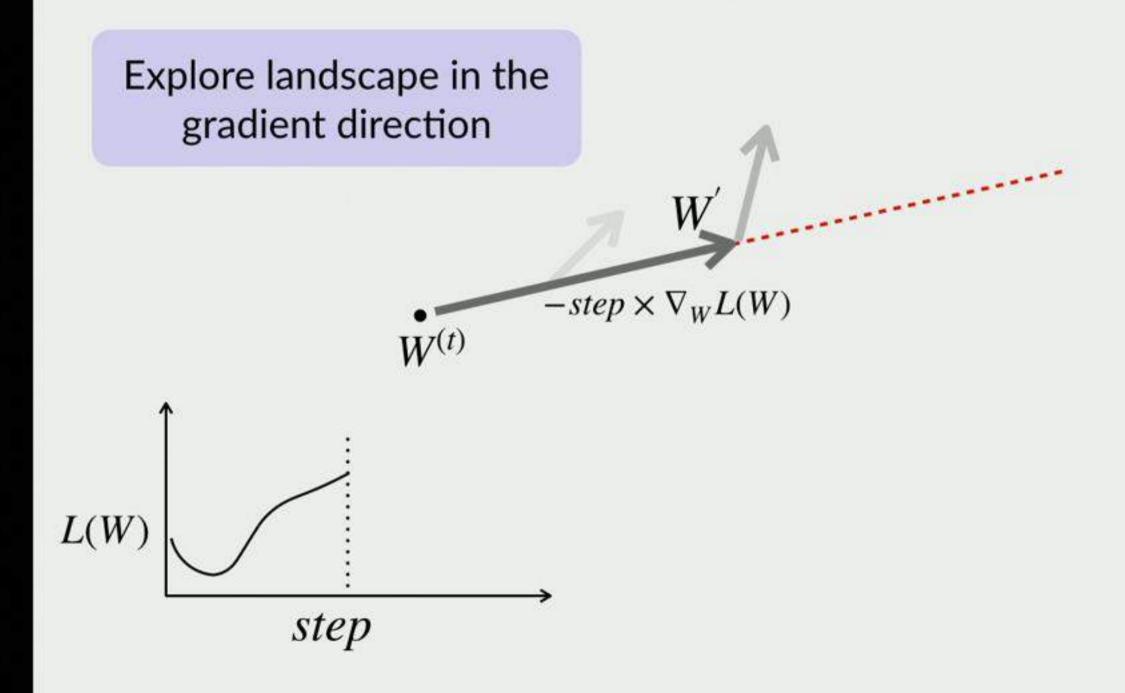


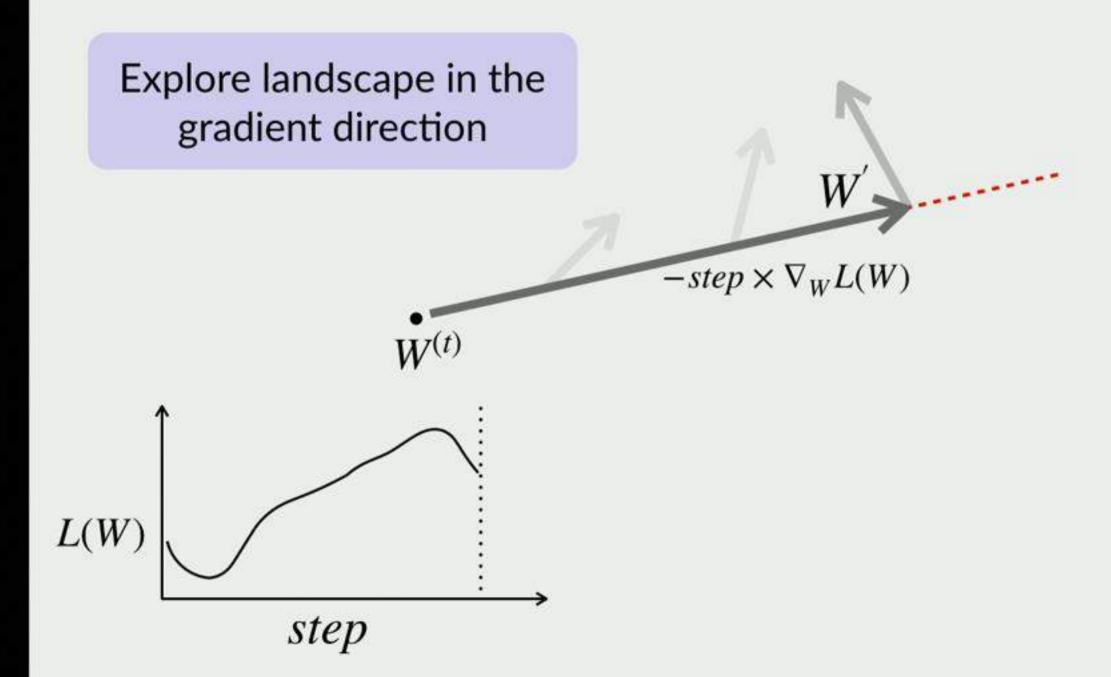
We rely on our loss being locally well-behaved

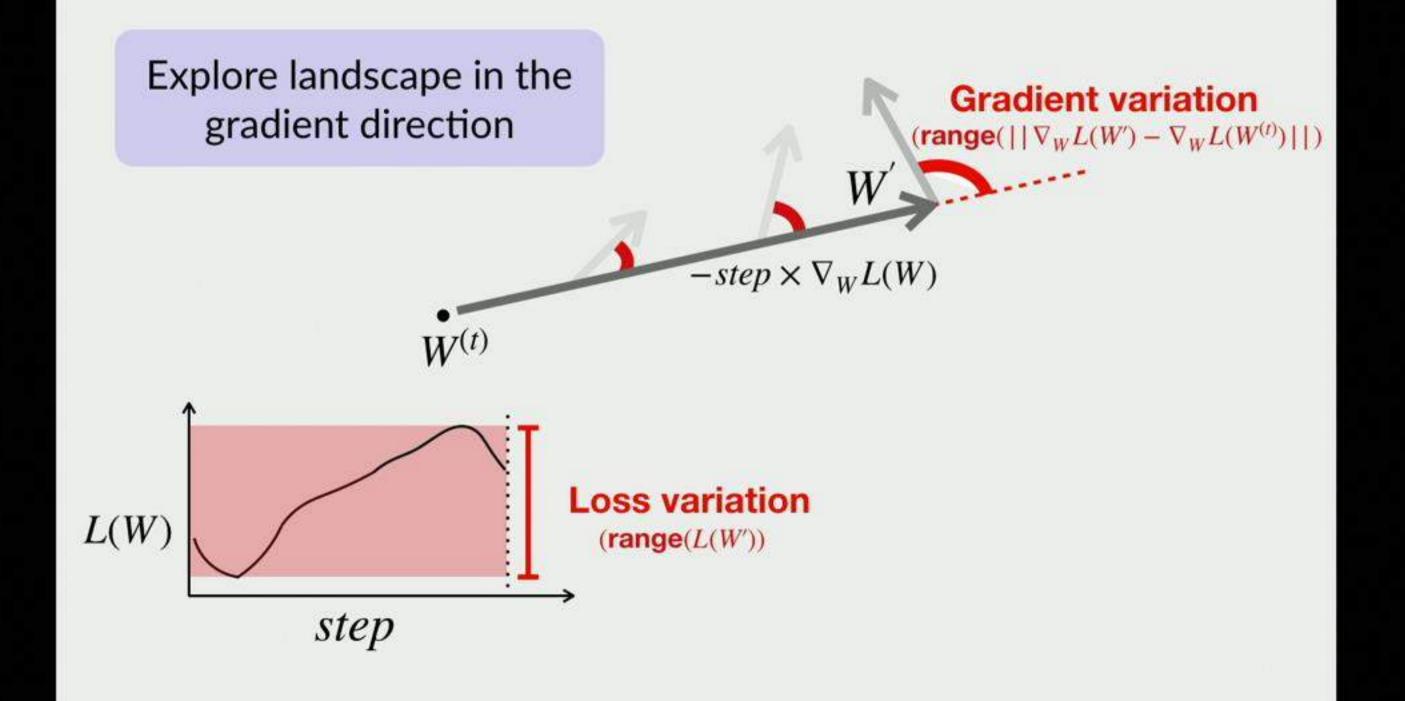
Explore landscape in the gradient direction

step

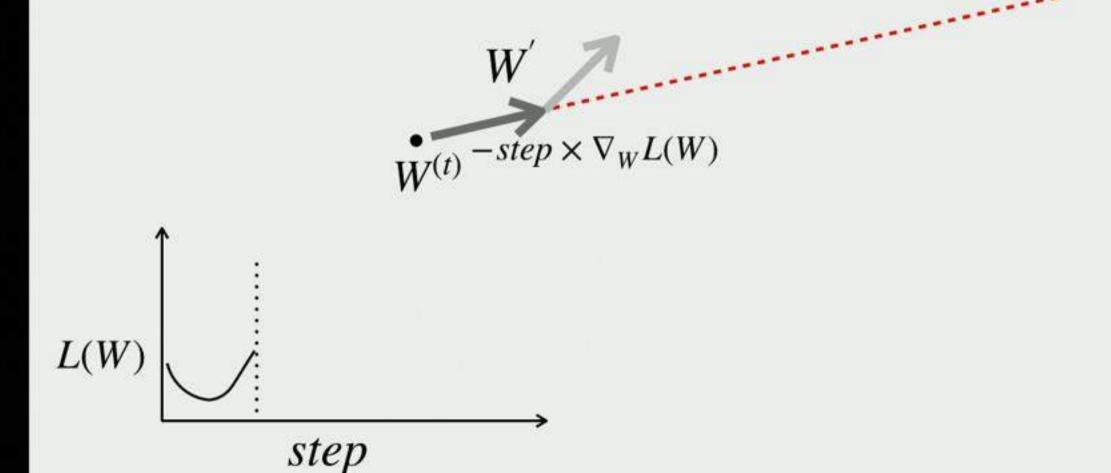


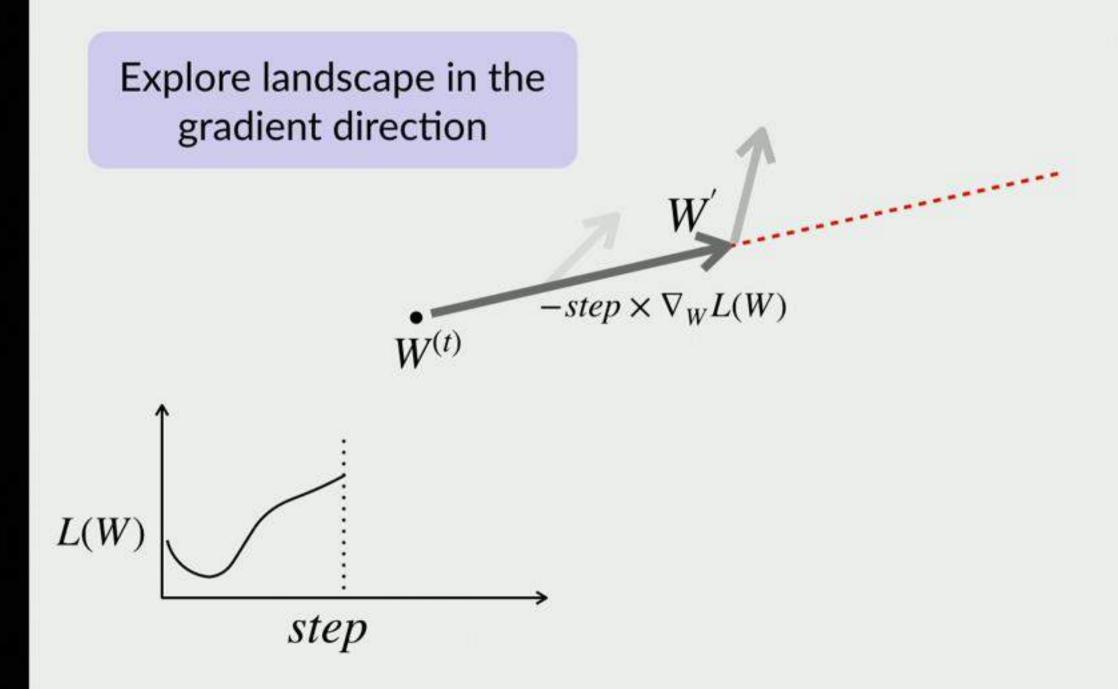


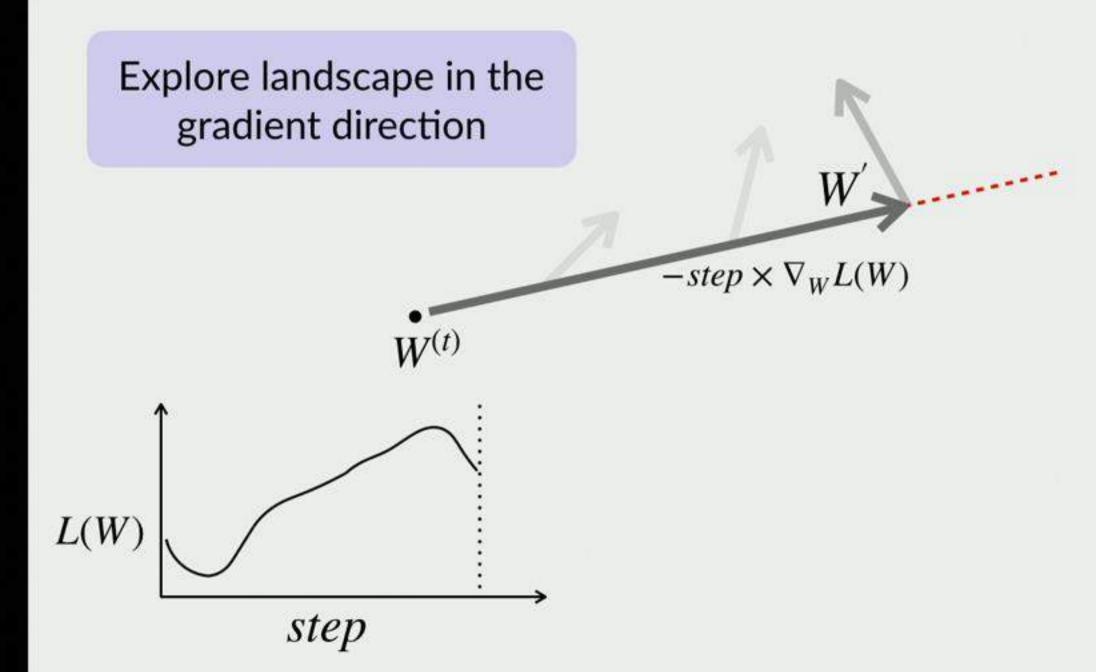


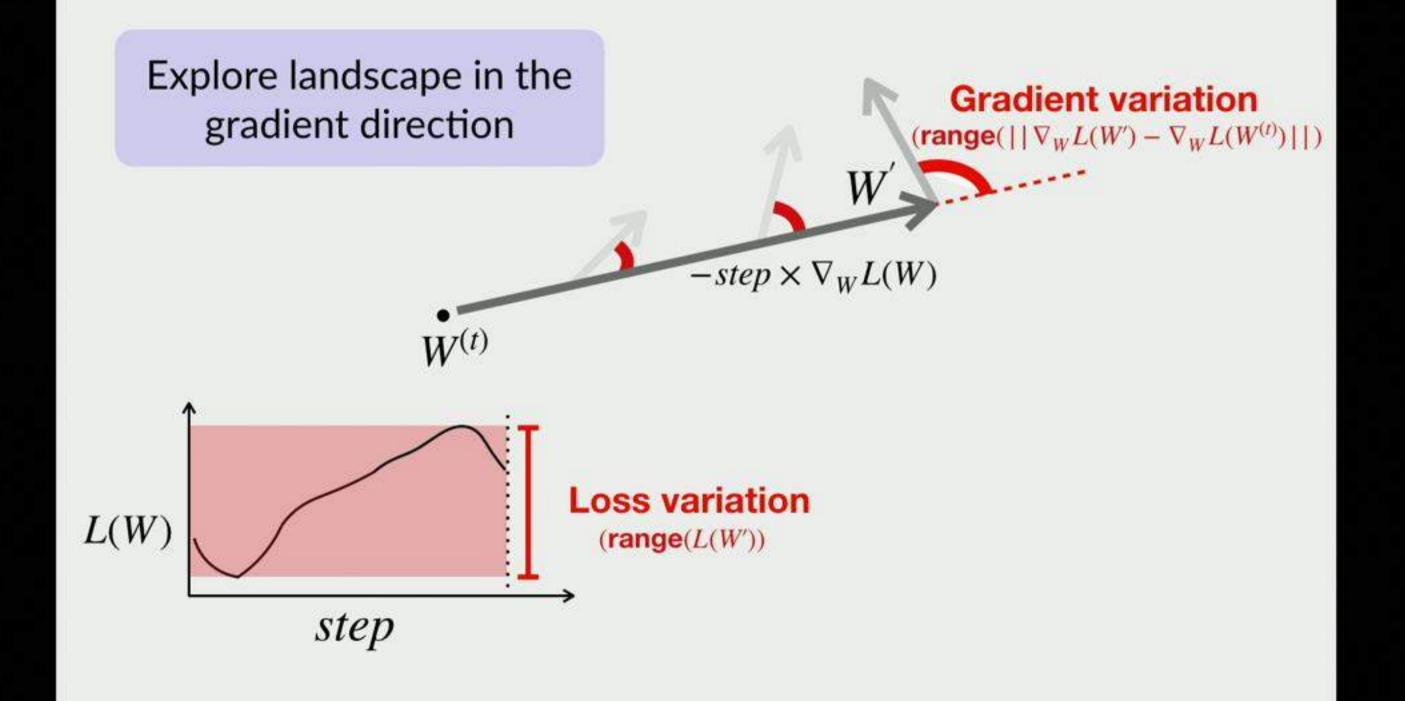


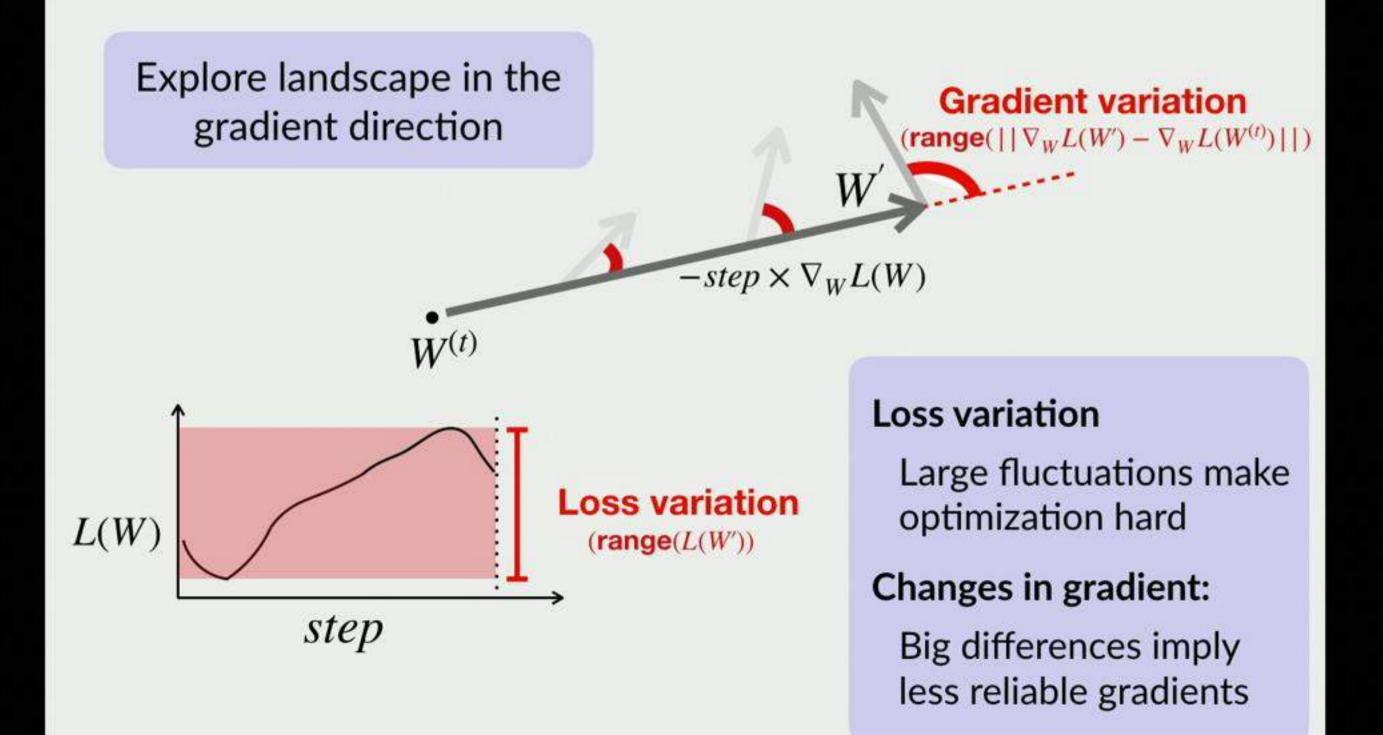
Explore landscape in the gradient direction







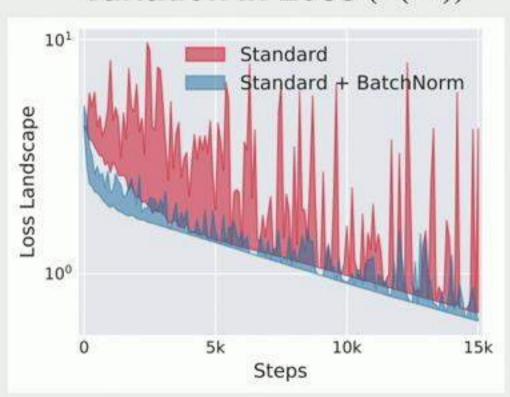




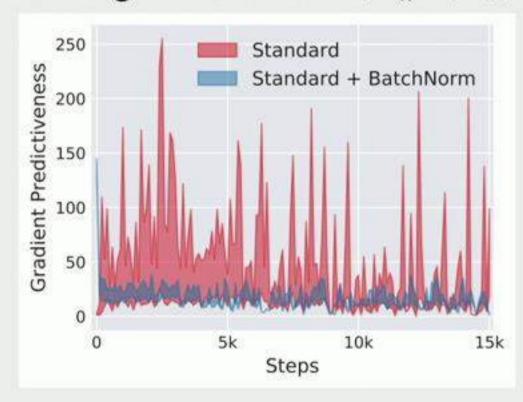
Landscape Induced by BatchNorm

Measure this variation at different points during training

Variation in Loss (L(W))

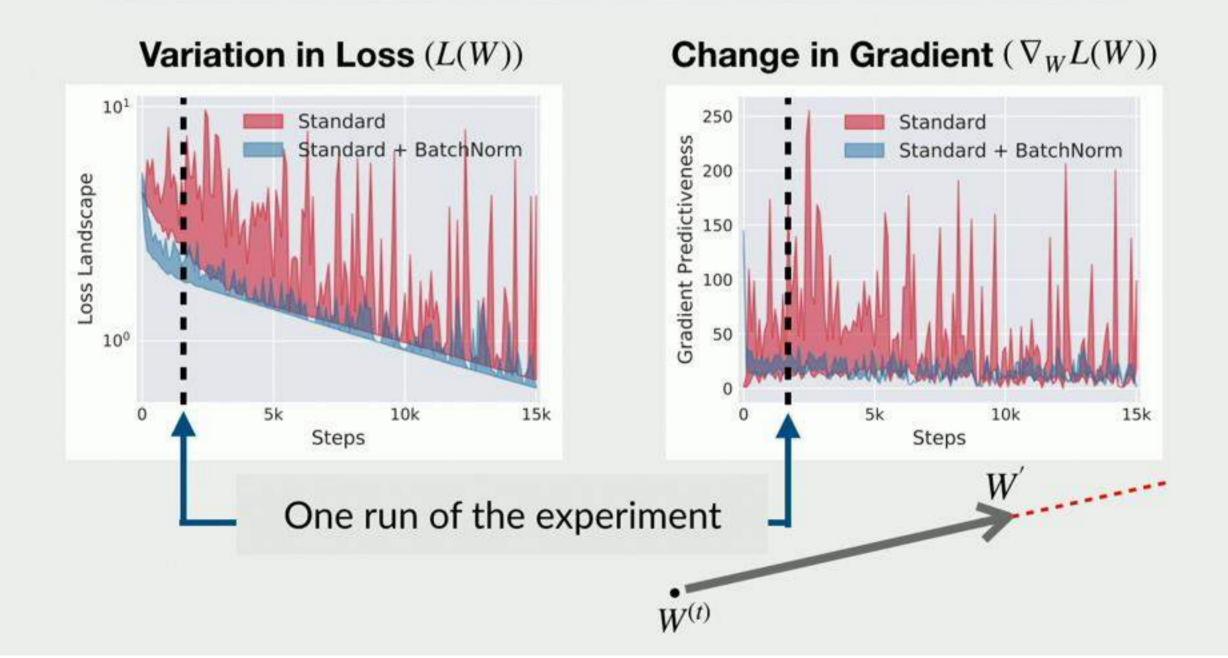


Change in Gradient $(\nabla_W L(W))$



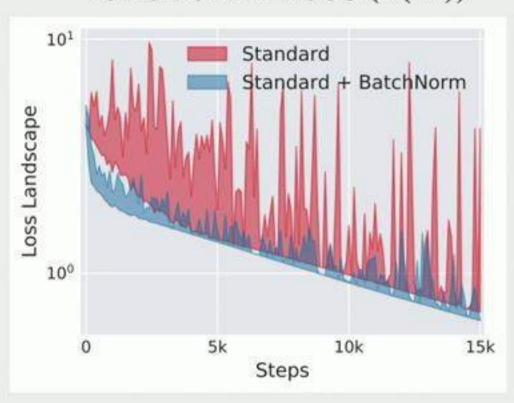
Landscape Induced by BatchNorm

Measure this variation at different points during training



Landscape Induced by BatchNorm

Variation in Loss (L(W))



Change in Gradient $(\nabla_W L(W))$



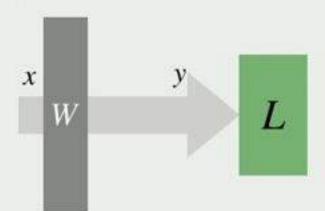
Result:

BatchNorm has **profound** effect on the landscape

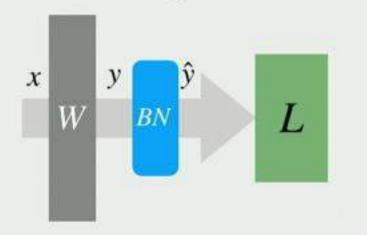
(Makes it **smoother** and **easier to navigate**)

What is the effect of a **single** BatchNorm layer on the optimization problem?

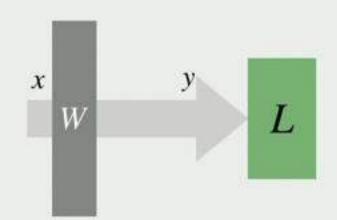
Network without BatchNorm



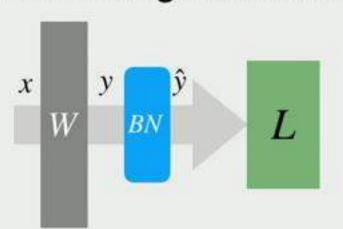
Network with a single BatchNorm layer



Network without BatchNorm



Network with a single BatchNorm layer

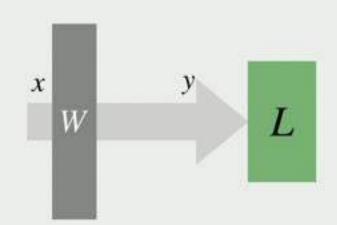


Theorem (Effect of BatchNorm on the Lipschitzness of the loss)

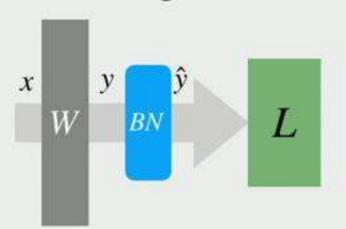
For any weights W and loss function L, we have:

$$||\nabla_{y_{j}}L_{BN}||^{2} \leq \frac{\gamma^{2}}{\sigma_{j}^{2}} \left(||\nabla_{y_{j}}L_{Std}||^{2} - \mu(\nabla_{y_{j}}L_{Std})^{2} - \frac{1}{m}(\hat{y}_{j}^{\mathsf{T}}\nabla_{y_{j}}L_{Std})^{2}\right)$$

Network without BatchNorm



Network with a single BatchNorm layer

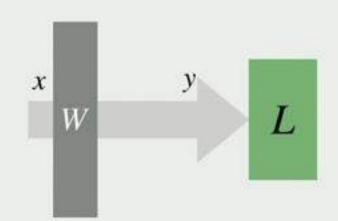


Theorem (Effect of BatchNorm on the Lipschitzness of the loss)

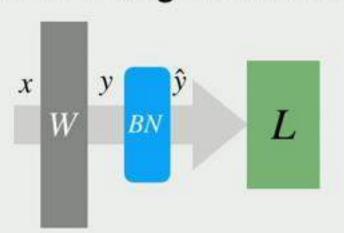
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Network without BatchNorm



Network with a single BatchNorm layer



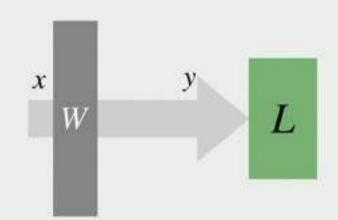
Theorem (Effect of BatchNorm on the Lipschitzness of the loss)

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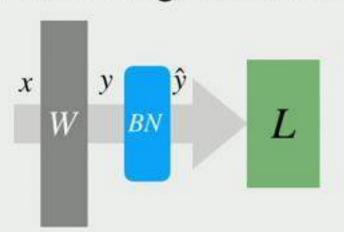
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Multiplicative ↓

Network without BatchNorm



Network with a single BatchNorm layer

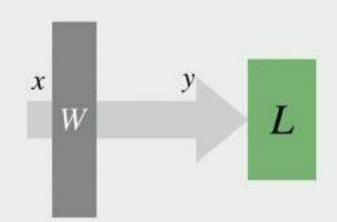


Theorem (Effect of BatchNorm on the Lipschitzness of the loss)

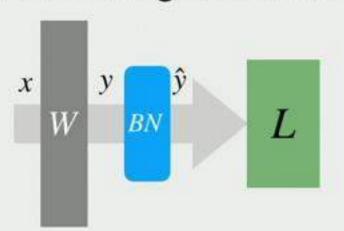
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Multiplicative \(\psi\)
Additive \(\psi\)

Network without BatchNorm



Network with a single BatchNorm layer

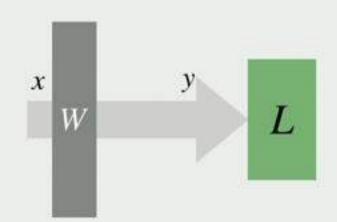


We also show:

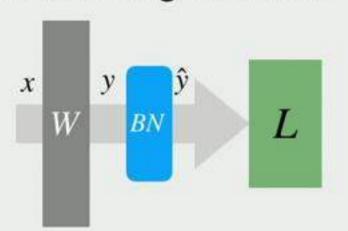
Gradients (wrt y) become more predictive

Translates into similar worst-case improvements

Network without BatchNorm



Network with a single BatchNorm layer

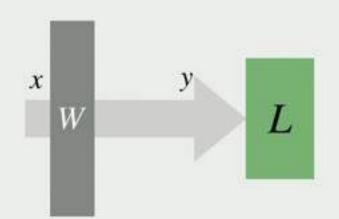


Theorem (Effect of BatchNorm on the Lipschitzness of the loss)

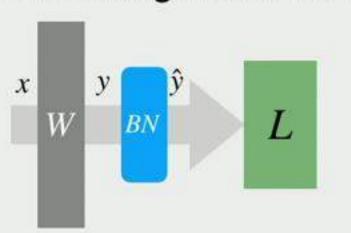
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Network without BatchNorm



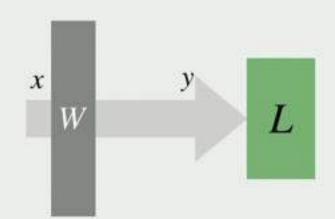
Network with a single BatchNorm layer



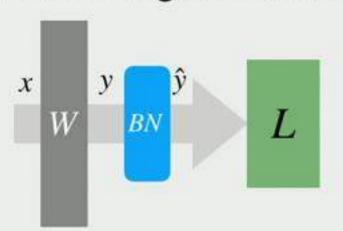
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$$||\nabla_{y_{j}}L_{BN}||^{2} \leq \frac{\gamma^{2}}{\sigma_{j}^{2}} \left(||\nabla_{y_{j}}L_{Std}||^{2} - \mu(\nabla_{y_{j}}L_{Std})^{2} - \frac{1}{m}(\hat{y}_{j}^{T}\nabla_{y_{j}}L_{Std})^{2}\right)$$
Multiplicative \(\psi\)
Additive \(\psi\)

Network without BatchNorm



Network with a single BatchNorm layer

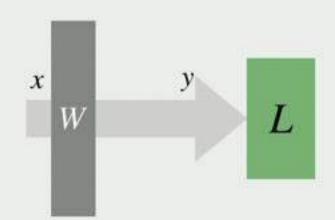


We also show:

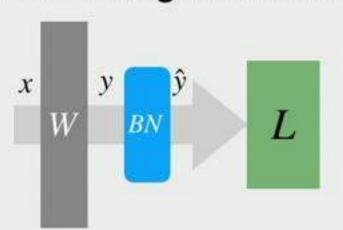
Gradients (wrt y) become more predictive

Translates into similar worst-case improvements

Network without BatchNorm



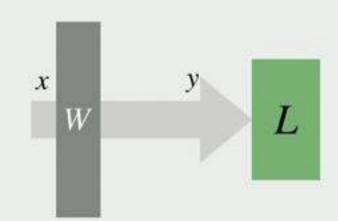
Network with a single BatchNorm layer



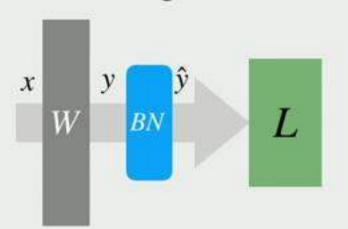
Theorem (Effect of BatchNorm on the Lipschitzness of the loss)

$$||\nabla_{y_{j}}L_{BN}||^{2} \leq \frac{\gamma^{2}}{\sigma_{j}^{2}} \left(||\nabla_{y_{j}}L_{Std}||^{2} - \mu(\nabla_{y_{j}}L_{Std})^{2} - \frac{1}{m}(\hat{y}_{j}^{\mathsf{T}}\nabla_{y_{j}}L_{Std})^{2}\right)$$

Network without BatchNorm



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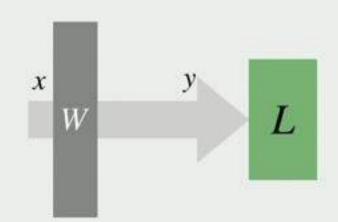
Theorem (Effect of BatchNorm on the Lipschitzness of the loss)

For any weights W and loss function L, we have:

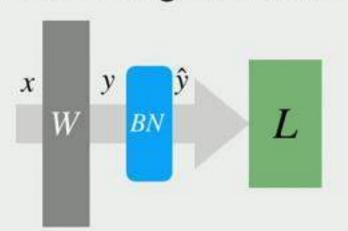
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Multiplicative ↓

Network without BatchNorm



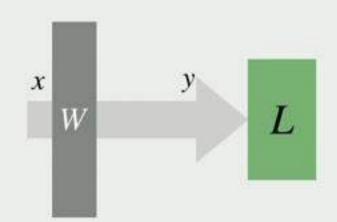
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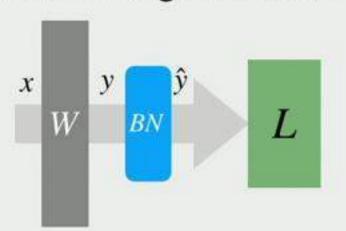
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Network without BatchNorm



Network with a single BatchNorm layer



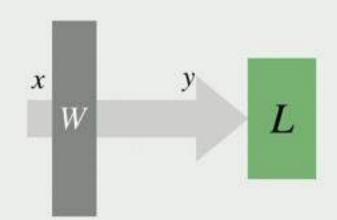
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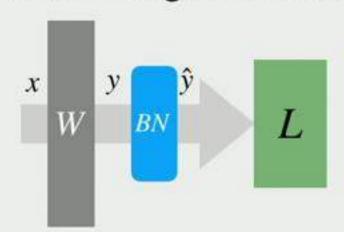
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Multiplicative \(\psi\)
Additive \(\psi\)

What if we normalize by a different notion of activation "scale"?

$$\hat{y} = \gamma \frac{y - \hat{\mu}}{C} + \beta$$

Typical BatchNorm

$$\hat{\mu} = \frac{1}{B} \sum_{i=1}^{B} y_i$$

$$\mathbf{C} = \frac{1}{B} \|y - \hat{\mu}\|_2$$

ℓ_p BatchNorm

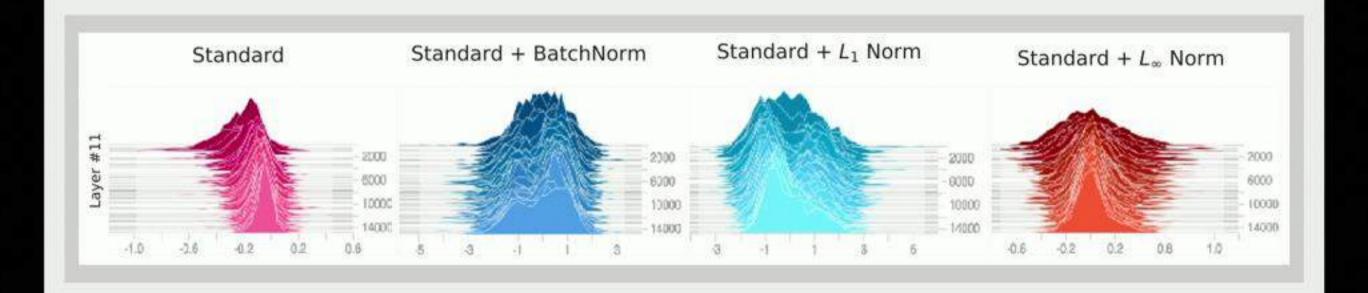


$$\mathbf{C} = \|\mathbf{y}\|_{p}$$

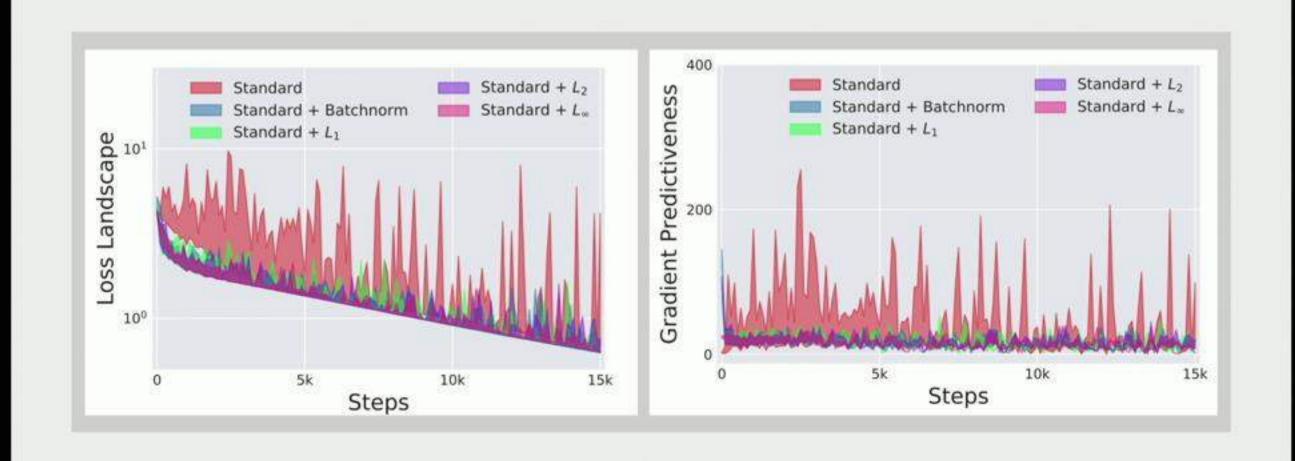
$$= \left(\frac{1}{B} \sum_{i=1}^{B} |y_{i}|^{p}\right)^{1/p}$$

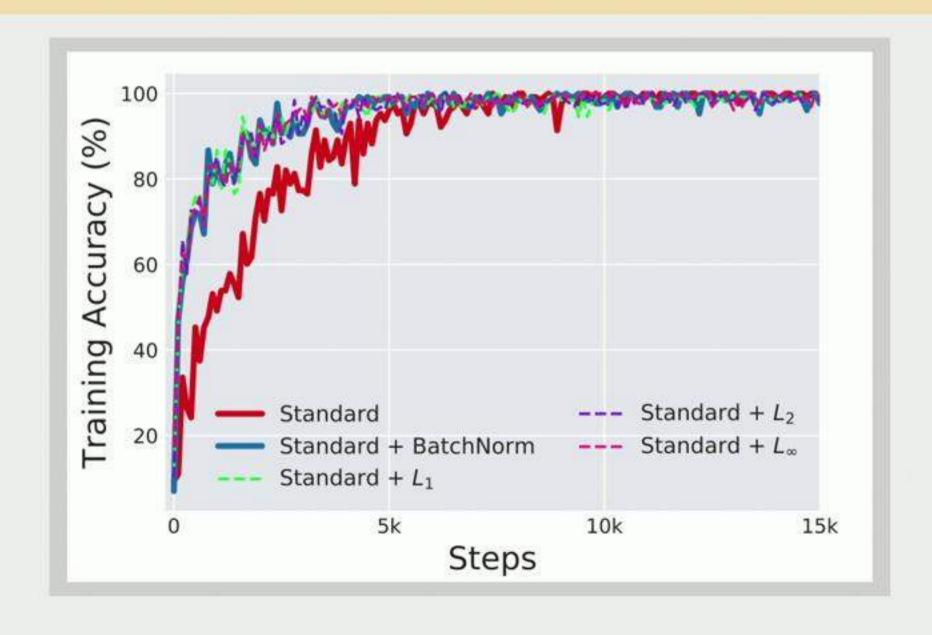
In general, no control over distribution moments.

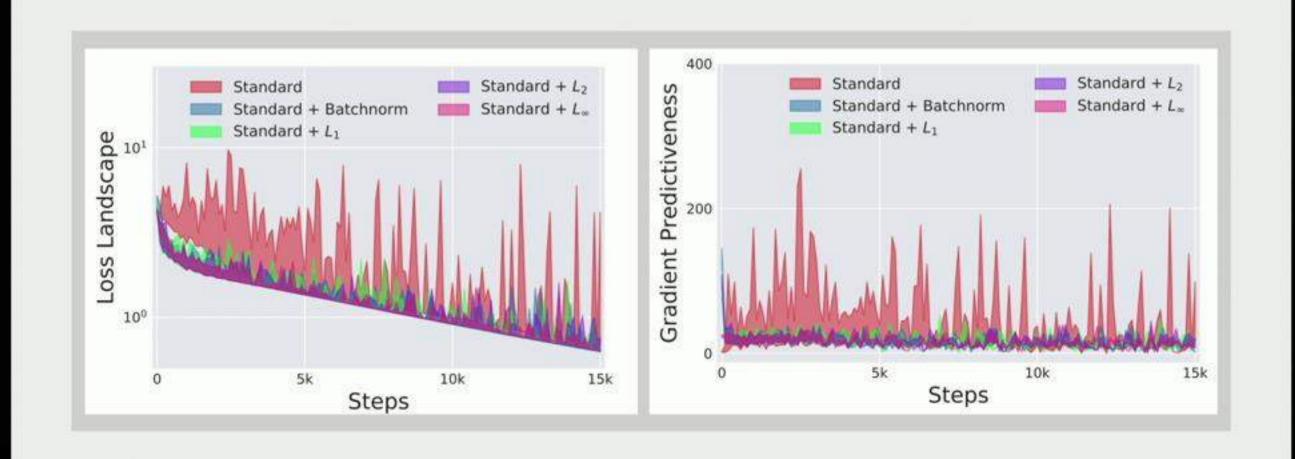
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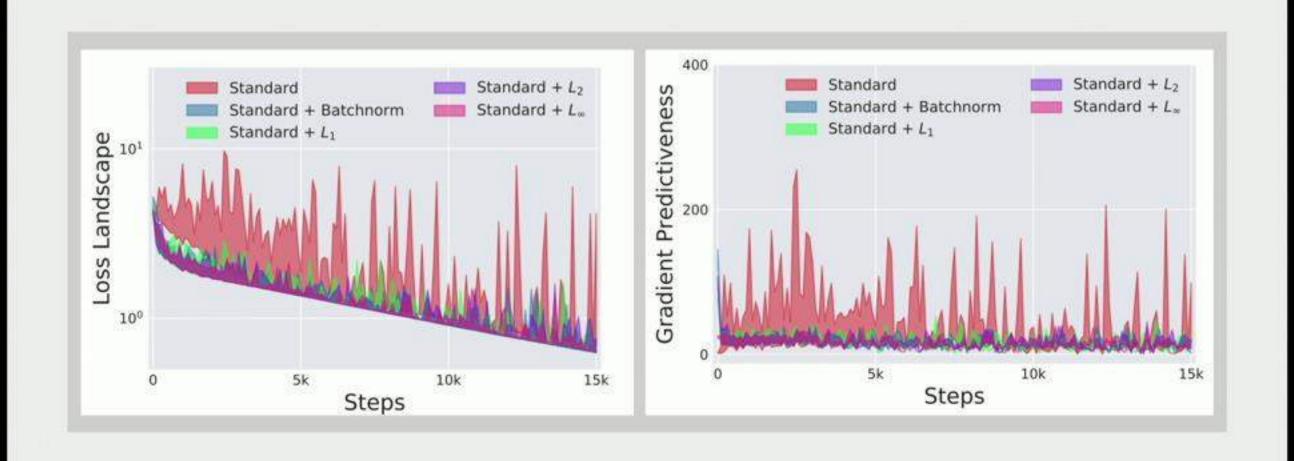
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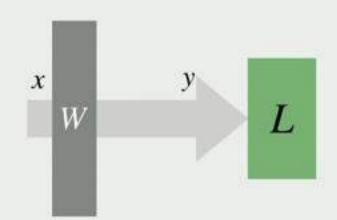




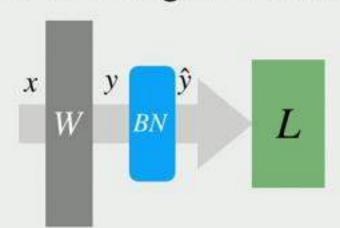




Network without BatchNorm



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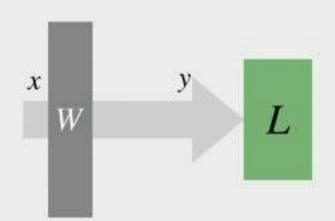


ℓ_p BatchNorm

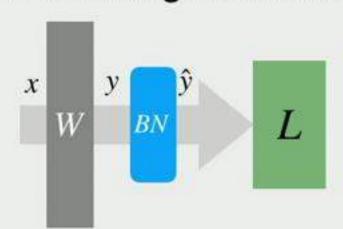
$$\mathbf{C} = \|\mathbf{y}\|_{p}$$

$$= \left(\frac{1}{B} \sum_{i=1}^{B} |y_{i}|^{p}\right)^{1/p}$$

Network without BatchNorm



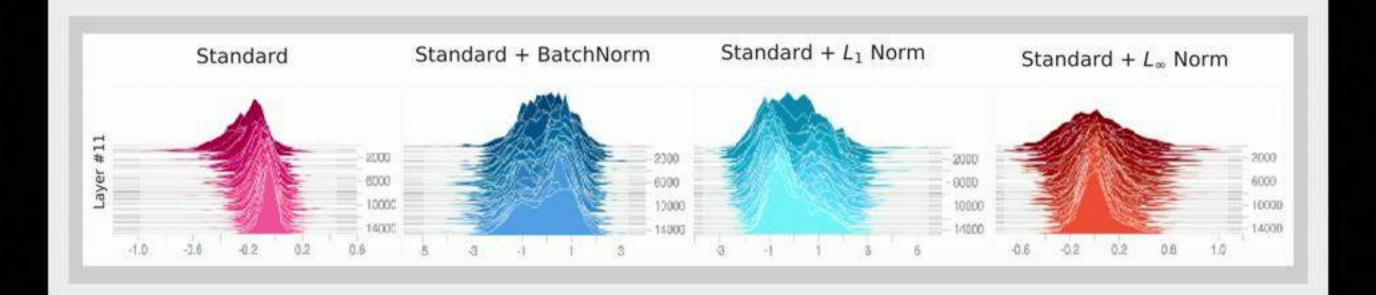
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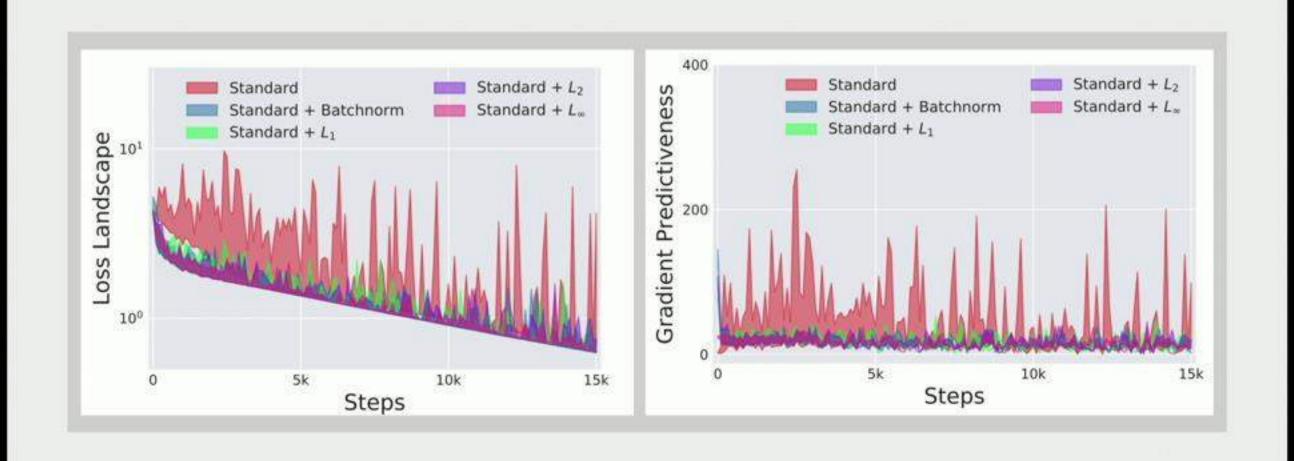
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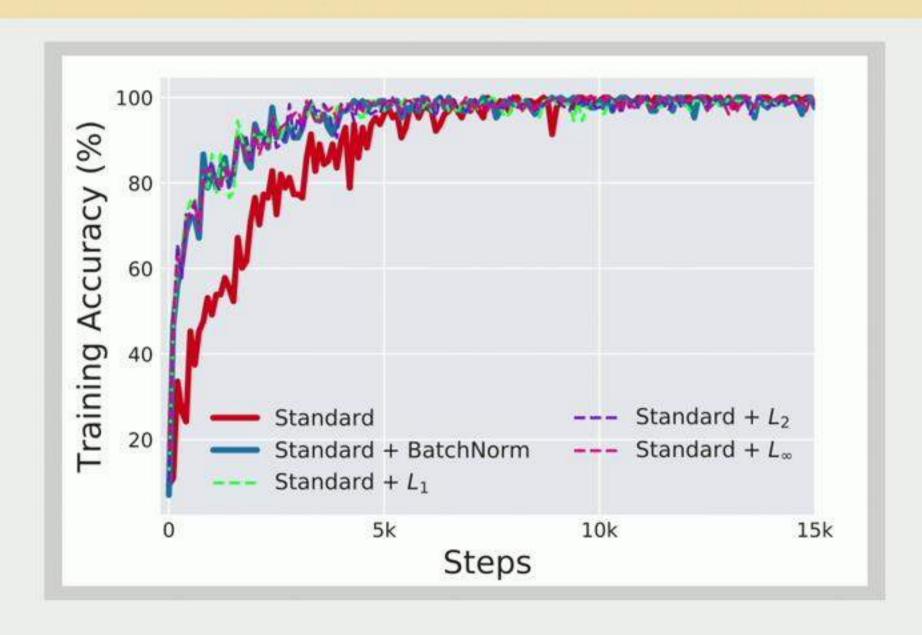
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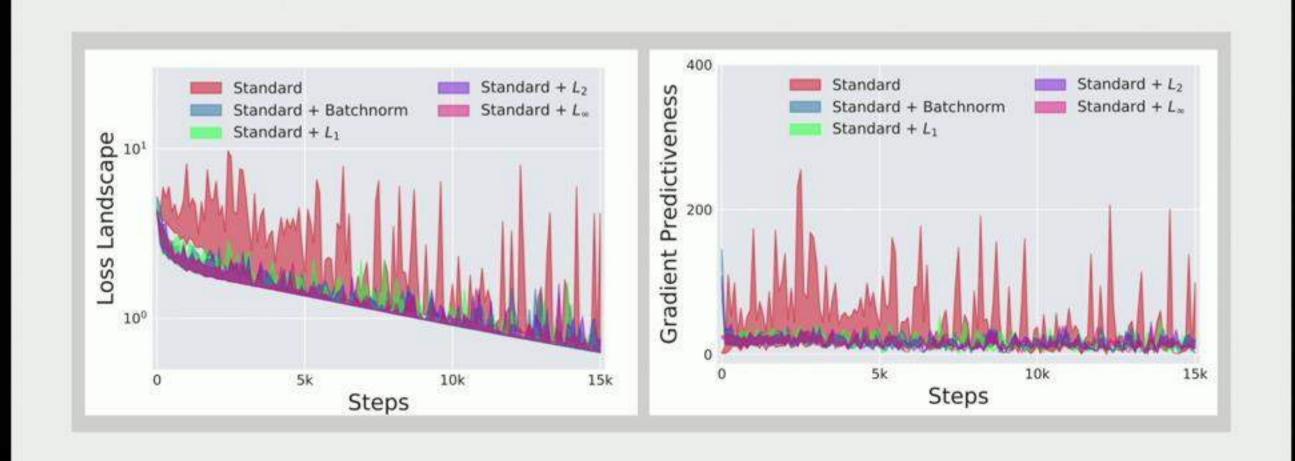
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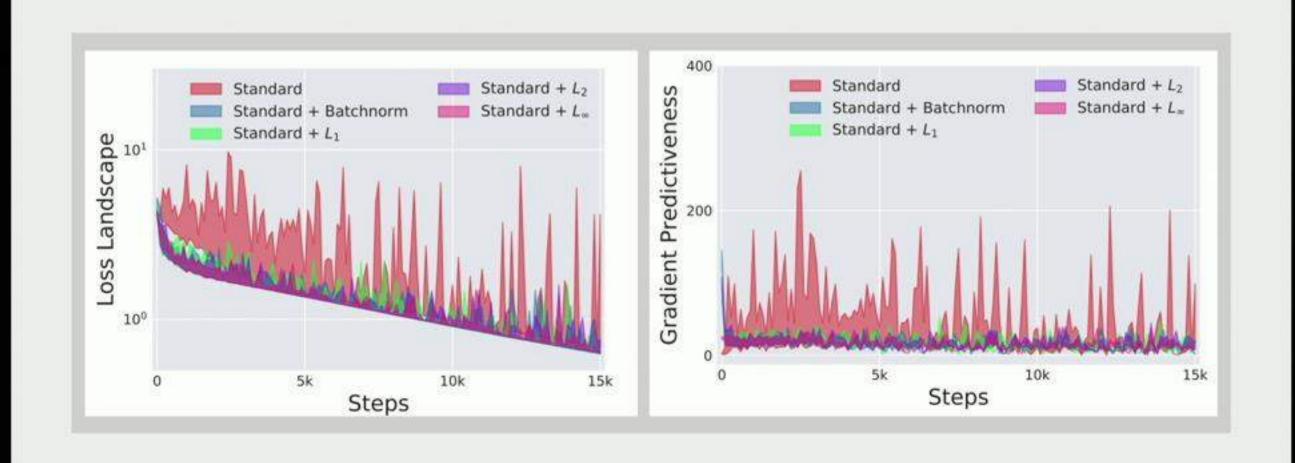
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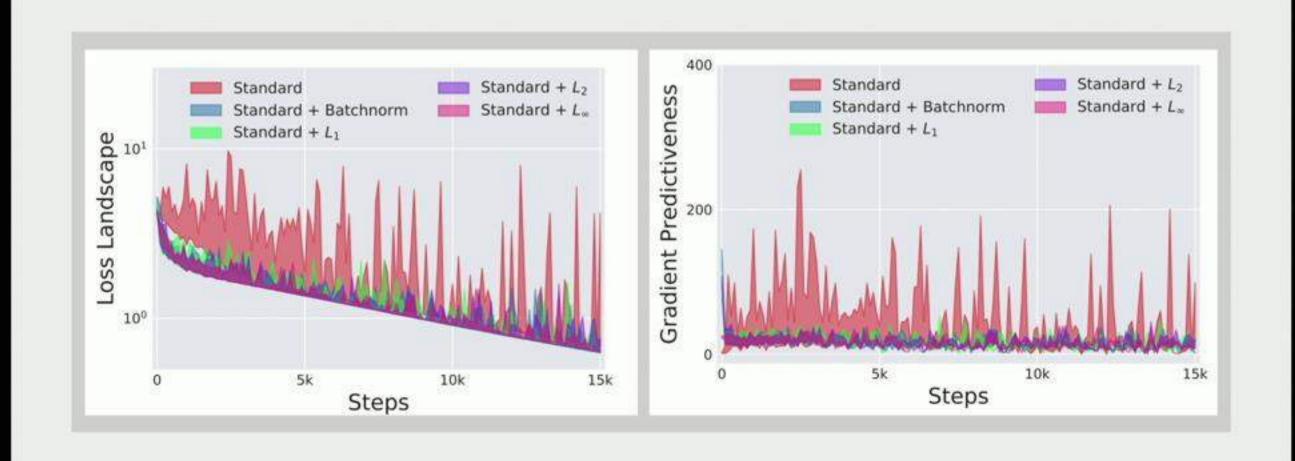




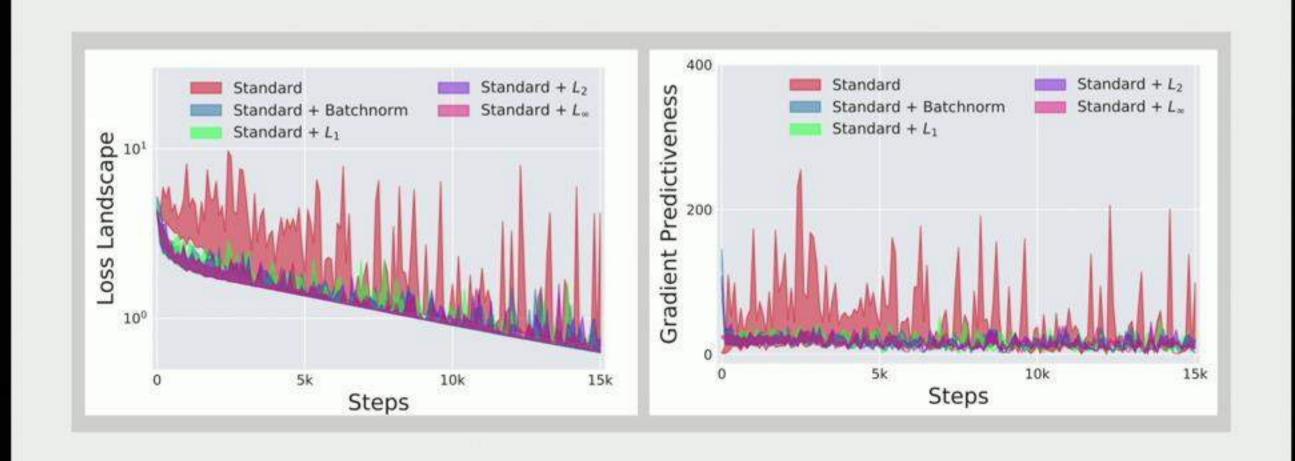




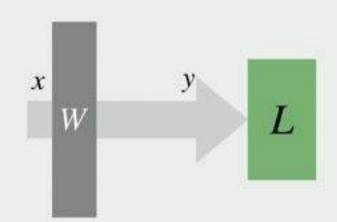




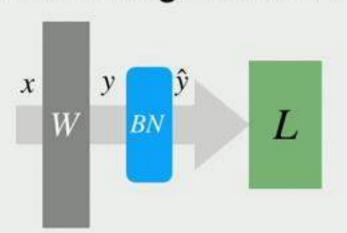




Network without BatchNorm



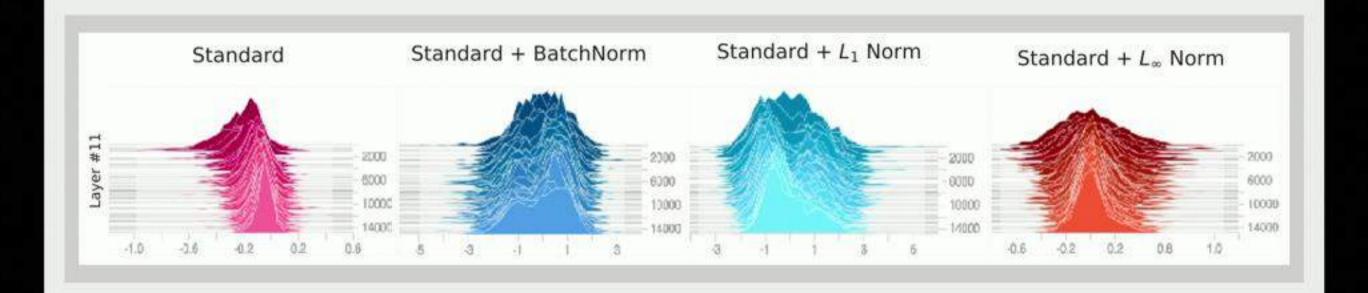
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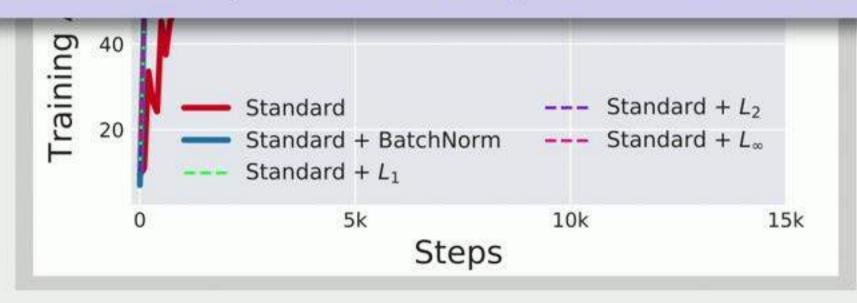
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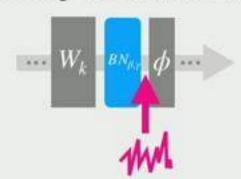
Performance improvement comparable to BatchNorm!



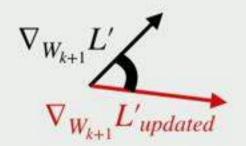
Goal: Understand the exact role of BatchNorm in optimization

BatchNorm ↔ ICS ↔ Optimization relationships tenuous

Noisy BatchNorm

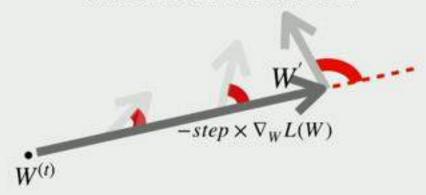


Optimization-based ICS

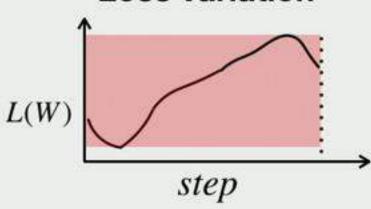


Identify a fundamental smoothing effect of BatchNorm

Gradient variation



Loss variation



Goal: Understand the exact role of BatchNorm in optimization

Moving forward:

Direct approaches to landscape smoothing

BatchNorm and generalization

Other normalization methods

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Other normalization methods

More broadly: understand other elements of our DL toolkit



arXiv:1805.11604

See our blog post at gradsci.org/batchnorm

