

ACHIEVEMENTS AND CHALLENGES OF DEEP LEARNING

--- From Speech Recognition to Language and Multimodal Processing

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Abstract:

While artificial neural networks have been around for over half a century, it was not until year 2010 that they had made a significant impact on speech recognition with a deep form of such networks. This article, based on my keynote talk given at Interspeech conference in Singapore in September 2014, will first reflect on the historical path to this transformative success, after providing brief reviews of earlier studies on (shallow) neural networks and on (deep) generative models relevant to the introduction of deep neural networks (DNN) to speech recognition several years ago. The role of well-timed academic-industrial collaboration is highlighted, so are the advances of big data, big compute, and the seamless integration between the application-domain knowledge of speech and general principles of deep learning. Then, an overview is given on sweeping achievements of deep learning in speech recognition since its initial success. Such achievements, summarized into six major areas in this article, have resulted in across-the-board, industry-wide deployment of deep learning in speech recognition systems. Next, more challenging applications of deep learning, natural language and multimodal processing, are selectively reviewed and analyzed. Examples include machine translation and automatic image captioning, where fresh ideas from deep learning, continuous-space embedding in particular, are shown to be revolutionizing these application areas, albeit with less rapid pace than for speech and image recognition. Finally, a number of key issues in deep learning are discussed and future directions are analyzed for perceptual tasks such as speech, image, and video, as well as for cognitive tasks involving natural language.

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1. INTRODUCTION

The main theme of this paper is to reflect on the recent history of how deep learning has profoundly revolutionized the field of automatic speech recognition (ASR) and to elaborate on what kind of lessons we can learn to not only further advance ASR technology but to also impact the related, arguably more important, applications in language and multimodal processing. Language processing concerns “downstream” analysis and distillation of information from the ASR systems’ outputs. Semantic analysis of language and multimodal processing involving speech, text, and image, both experiencing rapid advances based on deep learning over the past few years, holds the potential to solve some difficult and remaining ASR problems and present new challenges for the deep learning technology.

A message to be conveyed in this paper is the importance of broadening deep learning from deep neural networks (DNNs) to include deep generative models as well. In fact, a brief historical review conducted in Section 2 will touch on how the development of deep (and dynamic) generative models of speech played a role in the inroads of DNNs into modern ASR. Since 2011, the DNN has taken over the dominating (shallow) generative model of speech, the Gaussian Mixture Model (GMM), as the output distribution in the Hidden Markov Model (HMM). This purely discriminative DNN has been well known to the ASR community, which can be considered as a shallow network unfolding in space. When the unfolding occurs in time, we have the recurrent neural network (RNN). On the other hand, deep generative models have distinct advantages over discriminative DNNs, including the strengths of model interpretability, of embedding domain knowledge and causal relationships, and of modeling uncertainty. Deep generative and

discriminative models represent two apparently opposing approaches yet with highly complementary strengths and weaknesses. The further success of deep learning is likely to lie in how to seamlessly integrate the two approaches in a practically effective and theoretically appealing fashion, and to achieve the best of both worlds.

The remainder of this paper is organized as follows. In Section 2, some brief history is provided on how deep learning made inroad into speech recognition, and a number of enabling factors are discussed. Outstanding achievements of deep learning both in academic world and in industry to date are reviewed in Section 3, categorized into six major areas where speech recognition technology has been revolutionized within just past several years. Section 4 is devoted to more challenging applications of deep learning to natural language and multimodal processing, where active work is ongoing with current progress reviewed. Finally, in Section 5, remaining challenges for deep speech recognition are examined, together with much greater challenges for natural-language-related applications of deep learning and with directions for the future development.

2. SOME BRIEF HISTORY OF “DEEP” SPEECH RECOGNITION

Artificial neural networks have been around for over half a century and their applications to speech processing have been almost as long. Representative early work in using shallow (and small) neural networks for speech includes the studies reported in (Toshiteru et al., 1988; Waibel et al., 1989; Bengio, 1991; Robinson, 1994; Bourlard and Morgan, 1993; Hermansky et al., 2000). However, these neural nets did not show superior performance over the GMM-HMM technology based on generative models of speech trained discriminatively (Baker et al., 2009, 2009a). A number of key difficulties had been methodologically analyzed, including gradient diminishing and weak temporal correlation structure in the neural predictive models (Bengio et al., 1994; Deng et al., 1994). These difficulties were investigated in addition to the lack of big training data and big computing power in those early days in 1990’s. Most speech recognition researchers who understood such barriers hence subsequently moved away from neural nets to pursue (deep) generative modeling approaches for ASR (Deng et al., 1994a, 1997; Bridle et al., 1998; Picone et al., 1999). Since mid 1990’s, many prominent neural network and machine learning researchers also published their books and research papers on generative modeling (Hinton et al., 1995, 2006; Jordan and Bishop, 1996; Jordan et al., 1999; Bishop, 1995, 2006). This was so in some cases even if the generative models’ architectures were based on neural network parameterization (Hinton et al., 1995, 2006). It was not until several years ago with the resurgence of neural networks (with the “deep” form) and with the start of deep learning that all the difficulties encountered in 1990s have been overcome, especially for large vocabulary ASR applications (Hinton et al., 2012; Dahl et al., 2011, 2012; Yu et al., 2010, 2011; Deng et al., 2013, 2013a; Yu and Deng, 2014). The path towards exploiting large amounts of labeled speech data and powerful GPU-based computing for serious new implementations of neural networks involved extremely valuable academic-industry collaboration during 2009-2010 between University of Toronto and Microsoft researchers. The importance of making models deep was initially motivated by the limitations of both probabilistic generative modeling and discriminative neural net modeling.

2.1 A selected review of deep generative models of speech prior to 2009

There has been a long history in speech recognition research where human speech production mechanisms are exploited to construct dynamic and deep structure in probabilistic generative models; see (Deng, 2006) and several presentations at the 2009 NIPS Workshop on Deep Learning for Speech Recognition and

Related Applications. More specifically, the early work described in (Deng 1992, 1993; Deng et al., 1994; Ostendorf et al., 1996; Deng and Sameti, 1996; Deng and Aksmanovic, 1997; Chengalvarayan et al., 1998) generalized and extended the conventional shallow and conditionally independent GMM-HMM structure by imposing dynamic constraints, in the form of polynomial trajectory, on the HMM parameters. A variant of this approach has been developed later using different learning techniques for time-varying HMM parameters and with the applications extended to speech recognition robustness (Yu et al., 2009). Similar trajectory HMMs also form the basis for parametric speech synthesis (Ling et al., 2012, 2013). Subsequent work added new hidden layers into the dynamic model, thus being deep, to explicitly account for the target-directed, articulatory-like properties in human speech generation (Deng et al., 1997; Deng, 1998; Bridle et al., 1998; Deng, 1999; Picone et al., 1999; Minami et al., 2002; Togneri and Deng, 2003; Seide et al., 2003; Zhou et al., 2003; Deng and Huang, 2004; Ma and Deng, 2000, 2003, 2004). More efficient implementation of this deep architecture with hidden dynamics was achieved with non-recursive or finite impulse response (FIR) filters in more recent studies (Deng et al., 2006).

Reflecting on these earlier primitive versions of deep and dynamic generative models of speech, we note that neural networks, being used as “universal” nonlinear function approximators, have been incorporated in various components of the generative models. For example, the models described in (Deng and Ma, 2000; Deng, 1998, 2003) made use of neural networks to approximate the highly nonlinear mapping from articulatory configurations to acoustic features. Further, a version of the hidden dynamic model described in (Bridle et al., 1999) has the full model parameterized as a dynamic neural network, and backpropagation algorithm was used to train this deep and dynamic generative model. The key difference between this backpropagation and that used in training the DNN lies in how the error objective function is defined, while the optimization methods based on gradient descent are the same. In the DNN case, the error objective is defined as the label mismatch. In the deep generative model, the error objective is defined as the mismatch at the observable acoustic feature level via analysis-by-synthesis, and the error “back” propagation is towards the top label layer instead of back towards the observations as in the standard backprop. The assumption is that if the speech features generated by this deep model matches well with the observed speech data, then top-layer labels responsible for the speech production mechanism much be correct.

The above deep-structured, dynamic generative models of speech can be shown as special cases of the more general dynamic network model and even more general dynamic graphical models (Bilmes, 2010). The graphical models (Bishop, 2006) can comprise many hidden layers to characterize the complex relationship among the variables including those in speech generation. Such deep generative graphical models are a powerful tool in many applications due to their capabilities of embedding domain knowledge and of explicitly modeling uncertainty in real-world applications. However, they often suffer from inappropriate approximations in inference, learning, prediction, and topology design, all arising from intractability in these tasks in practical applications.

Indeed, in the history of developing deep generative models of speech, the above difficulties have been found to seriously hinder the progress in improving ASR accuracy (Lee et al., 2003, 2004); see a review and analysis in (Deng and Togneri, 2014). In these early studies, variational Bayes for learning the intractable deep generative model was adopted, with the idea that during inference (i.e. the E step of learning), factorization of posterior probabilities was assumed while in the M-step the rigorous estimation should compensate for the approximation errors introduced by the factorization. It turned out that the inference results for the continuous-valued mid-hidden vectors were surprisingly good but those for the continuous-valued top-hidden layer (i.e. the linguistic symbols such as phones or words) were disappointing. Moreover, computation complexity for the inference step was extremely high. Only after many additional assumptions were made without sacrificing essential properties of deep and dynamic nature of the generative model (i.e. target-directedness in the phonetic space, smoothness in hidden dynamic variables,

adequate representation of phonetic target undershooting, rigorous nonlinear relationship between the hidden and observation vectors, etc.), did the model become well performed in inference in both continuous- and discrete-valued latent spaces (Deng et al., 2006, 2006a). In fact, when the hidden layer of the model took the vocal tract resonance vector as its physical variables, the inference algorithm on such continuous-valued vectors produced the best formant tracker then (Bazzi et al., 2006; Deng et al., 2007). The resulting estimates actually formed the basis for a standard database of the “ground truth” of formant frequencies to evaluate formant tracking algorithms (Deng et al., 2006b).

2.2 From deep generative models to deep neural nets

The deep and dynamic generative models of speech, all with probabilistic formulations of the various types discussed above, were closely examined in 2009 during the collaboration between Microsoft Research and University of Toronto researchers. In parallel with the development of these probabilistic speech models characterized by the distribution parameters in the graphical modeling framework, a different type of deep generative models characterized by neural network parameters in terms of connection matrices was developed mainly for image pixels as the observation data. These were called Deep Belief Networks or DBN (Hinton et al., 2006).

The DBNs have an intriguing property: The rigorous inference step is much easier than that for the hidden dynamic model. Therefore, there is no need for approximate variational Bayes as required for the latter. This highly desirable property of DBNs comes with the simplicity of not modeling dynamics, and thus not directly suitable for speech modeling.

How to reconcile the pros and cons of these two different types of deep generative models? In order to speed up the investigation in the academic-industrial collaborative work during 2009, our collaborators introduced three kluges. First, to remove the complexity of rigorously modeling speech dynamics, one can for the time being remove such dynamics but one can compensate for this modeling inaccuracy by using a long time window to approximate the effects of true dynamics. Note this first “kluge” used during 2009-2010 has since been fixed by adding recurrence to the DNN (Graves et al. 2013; Deng and Chen, 2014; Sak et al., 2015). And the dynamics of speech at the symbolic level can be approximately captured by the standard HMM.

The second kluge was to reverse the direction of information flow in the deep models --- from top-down as in the deep generative model to bottom-up as in the DNN, in order to make inference fast and accurate (given the models). However, it was known by 2009 that with many hidden layers, neural networks were very difficult to train. For fixing this problem, the third “kluge” was adopted: to use the DBN to initialize or pre-train the DNN based on the original proposal of (Hinton et al., 2006). Note this third “kluge” had been automatically fixed after the earlier DNN was subject to large-data training conducted in industry soon after DNNs showed promising results in small tasks (Dahl et al., 2012; Hinton et al., 2012; Seide et al., 2011; Yu et al., 2010). Careful analyses conducted during 2010 at Microsoft showed that with greater amounts of training data, enabled by GPU-based fast computing, and with more sensible weight initialization without generative pre-training using DBNs (Yu et al., 2011), the gradient diminishing problem encountered in 1990’s no longer plagued the training of DNNs.

Adopting the above three kluges shaped the deep generative models, rather indirectly, into the DNN-based ASR framework. The initial experimental results using pre-trained DNNs with DBNs showed rather similar phone recognition accuracy to the deep generative model of speech on the standard TIMIT task. The TIMIT data set has been commonly used to evaluate ASR models. Its small size allows many different

configurations to be tried quickly and effectively. More importantly, the TIMIT task concerns phone-sequence recognition, which, unlike word-sequence recognition, permits very weak “language models” and thus the weaknesses in the acoustic modeling aspect of ASR can be more easily analyzed. Such an analysis on TIMIT was conducted at Microsoft Research during 2010 that contrasted the phone recognition accuracy between deep generative models of speech (Deng and Yu, 2007) and deep discriminative models including pre-trained DNNs and deep conditional random fields (Mohamed et al, 2010, 2012, 2009; Yu and Deng, 2009, 2010; Deng and Yu, 2011, 2011a). There were a number of very interesting findings. For instance, while the overall phone recognition accuracy is slightly higher for the DNN system, it created many test errors associated with short vocalic phone segments. The errors were traced back to the use of long windows (11 to 25 frames) for the DNN, creating lots of “noise” for these short phones. Further, the acoustic properties of these vocalic phones are subject to phonetic reduction, not captured by the DNN. However, such phonetic reduction arising from articulatory dynamics is explicitly and adequately modeled by the deep generative model with hidden dynamics, accounting for much lower errors in the short vocalic phones than the DNN as well as the GMM systems that do not capture articulatory dynamics. For most other classes of phone-like segments in TIMIT, the DNN is doing substantially better than the deep generative model. This type of contrastive error analyses shed insights into distinctive strengths of the two types of deep models. With the highly regular computation and the ease of decoding associated with the DNN-based system, the strengths of the DNN identified by the error analysis stimulated early industrial investment onto deep learning for ASR from small to large scales, eventually leading to its pervasive and dominant deployment today.

The second “kluge” above is the only one that has not been fixed as in today’s state of the art ASR systems. This direction of future research will be discussed in later sections of this article.

2.3 Summary

Artificial neural networks have been around for over half a century and their applications to ASR have been almost as long, yet it was not until year 2010 that their real impact had been made by a deep form of such networks, built upon part of the earlier work on (shallow) neural nets and (deep) generative models developed by both speech and machine learning communities. A well-timed academic-industrial collaboration between Microsoft and University of Toronto played a central role in introducing DNN technology into the ASR industry. As reviewed above, by 2009 the ASR industry had been searching for new solutions when “principled” deep generative approaches could not deliver what industry needed, both in terms of recognition accuracy and decoding efficiency. In the meantime, academic researchers already developed powerful deep learning tools such as DBNs looking for practical applications (Hinton et al., 2006). Further, with the advent of general-purpose GPU computing and with Nvidia’s CUDA library released in 2008, DBN and DNN computation became fast enough to apply to large speech data. And luckily, by 2009 the ASR community, with the government support since 1980’s, had been keenly aware of the importance of large amounts of labeled data, popularized by the axiom “no data is like more data,” and had collected more labeled data for training ASR systems than any other discipline. All these enabling factors came in at a perfect time when academic and industrial researchers seized the opportunity and collaborated with each other effectively in the industry setting, leading to the birth of the new era of “deep” speech recognition.

3. ACHIEVEMENTS OF DEEP LEARNING IN SPEECH RECOGNITION

The early experiments discussed in the preceding section on phone recognition and error analysis, as well as on speech feature extraction which demonstrated the effectiveness of using raw spectrogram features (Deng et al., 2010) had pointed to strong promise and practical value of deep learning. This early progress excited researchers to devote more resources to pursue ASR research using deep learning approaches, the DNN approach in particular. The small-scale ASR experiments were soon expanded to larger scales (Dahl et al., 2011, 2012; Seide et al., 2011; Deng et al., 2013), and from Microsoft to other companies including Google, IBM, IflyTech, Nuance, Baidu, etc. (Dean et al., 2012; Sak et al., 2014, 2014a, 2015; Sainath et al., 2011, 2013, 2013a,b,c; Saon et al., 2013; Hannun et al., 2014). The experiments carried out at Microsoft showed that with increasing amounts of training data over the range of close to four orders of magnitude (from TIMIT to voice search to Switchboard), the DNN-based systems outperformed the GMM-based systems monotonically not only in absolute percentages but also in relative percentages. This is the kind of accuracy improvement not seen in the ASR history. In short, for the DNN-based speech recognizers, the more training data are used, the better the accuracy, the greater word error rate reduction over the GMM counterparts in both absolute and relative terms, and further, the less care required to initialize the DNN. Soon after these experiments at Microsoft were reported, similar findings were published by all major ASR groups worldwide.

Since the initial successful debut of DNNs for speech recognition around 2009-2011, there have been huge progresses made. These progresses, as well as future challenging research directions, are elaborated and summarized into six major areas, each dedicated by a separate subsection below.

3.1 Output representation learning

Most deep learning methods for ASR have focused on learning representations from input acoustic features without paying attention to output representations. The NIPS Workshop on Learning Output Representations held in December 2013 was dedicated to bridging this gap. The importance of designing effective linguistic representations for the output layers of deep networks for ASR was highlighted in (Deng, 2013). The most straightforward yet most important example is the use of context-dependent (CD) phone and state units as the DNN output layer, originally invented at Microsoft Research as described in (Yu et al., 2010; Dahl et al., 2011). This type of design for the DNN output representations drastically expands the output neurons from the context-independent phone states with the size of 100 to 200 commonly used on 1990's to the context-dependent ones with the size in the order of 1,000 to 30,000. Such design follows the traditional GMM-HMM systems, and was motivated initially by saving huge industry investment in the speech decoder software infrastructure. Early experiments further found that due to the significant increase of the HMM output weights and thus the model capacity, CD-DNN gave much higher accuracy when large training data supported such high modeling capacity. The combination of the above two factors accounted for why the CD-DNN has been so quickly adopted for industry deployment. Importantly, the design of the big CD-DNN within the traditional framework of HMM decoding requires combined expertise in the DNN and in the large-scale ASR decoder. It also requires industry know-how for constructing very large yet efficient CD units ported to the DNN outputs. It further require the knowledge of how to make decoding of such huge networks highly efficient using HMM technology and how to cut corner in making practical systems.

For future directions, the output representations for ASR can benefit from more linguistically-guided structured design based on symbolic or phonological units of speech. The rich phonological structure of

symbolic nature in human speech has been well known for many years. Likewise, it has also been well understood for a long time that the use of phonetic or its finer state sequences, even with (linear) contextual dependency, in engineering ASR systems, is inadequate in representing such rich structure (e.g., Deng and Erler, 1992; Ostendorf, 1999; Sun and Deng, 2002). Such inadequacy thus leaves a promising open door to improve ASR systems’ performance. Basic theories about the internal structure of speech sounds and their relevance to ASR in terms of the specification, design, and learning of possible output representations of the underlying speech model for speech target sequences have been surveyed in (Deng and O’Shaughnessy, 2003). The application of this huge body of speech knowledge is likely to benefit deep learning based ASR when deep generative and discriminative models are carefully integrated.

3.2 Moving towards raw features

One fundamental principle of deep learning is to do away with hand-crafted feature engineering and to use raw features. This principle was first explored successfully in the architecture of deep autoencoder on the “raw” spectrogram or linear filter-bank features, showing its superiority over the Mel-frequency cepstral coefficient (MFCC) features which contain a few stages of fixed transformation from spectrograms (Deng et al., 2010). Over the past 30 years or so, largely “hand-crafted” transformations of speech spectrogram have led to significant accuracy improvements in the GMM-based HMM systems, despite the known loss of information from the raw speech data. The most successful transformation is the non-adaptive cosine transform, which gave rise to MFCCs. The cosine transform approximately de-correlates feature components, important for the use of GMMs with diagonal covariance matrices. However, when GMMs are replaced by deep learning models such as DNNs, deep belief nets (DBNs), or deep autoencoders, such de-correlation becomes irrelevant due to the very strength of the deep learning methods in modeling data correlation.

The feature engineering pipeline from speech waveforms to MFCCs and their temporal differences goes through intermediate stages of log-spectra and then (Mel-warped) filter-banks. Deep learning is aimed to move away from separate design of feature representations and of classifiers. This idea of jointly learning classifier and feature transformation for ASR was already explored in early studies on the GMM-HMM-based systems (Chengalvarayan and Deng, 1997; 1997a; Rathinavalu and Deng, 1997; Biem et al., 2001). However, greater speech recognition performance gain is obtained only recently in the recognizers empowered by deep learning methods. For example, Mohamed et al. (2012a) and Li et al., (2012) showed significantly lowered ASR errors using large-scale DNNs when moving from the MFCC features back to more primitive (Mel-scaled) filter-bank features. These results indicate that DNNs can learn a better transformation than the original fixed cosine transform from the Mel-scaled filter-bank features.

Compared with MFCCs, “raw” spectral features not only retain more information, but also enable the use of convolution and pooling operations to represent and handle some typical speech invariance and variability --- e.g. vocal tract length differences across speakers, distinct speaking styles causing formant undershoot or overshoot, etc. --- expressed explicitly in the frequency domain. For example, the convolutional neural network (CNN) can only be meaningfully and effectively applied to ASR (Abdel-Hamid et al., 2012; 2013, 2013a; Deng et al., 2013) when spectral features, instead of MFCC features, are used. More recently, Sainath et al. (2013b) went one step further toward raw features by learning the parameters that define the filter-banks on power spectra. That is, rather than using Mel-warped filter-bank features as the input features, the weights corresponding to the Mel-scale filters are only used to initialize the parameters, which are subsequently learned together with the rest of the deep network as the classifier. Substantial ASR error reduction is reported.

Ultimately, deep learning would go all the way to the lowest level of raw features of speech, i.e., speech sound waveforms. As an initial attempt toward this goal, the study carried out by Jaitly and Hinton (2011) made use of speech sound waves as the raw input feature to a deep learning system. Although the final

results were disappointing, similarly for the earlier work on using speech waveforms in generative model-based ASR (Sheikhzadeh and Deng, 1994), the work nevertheless showed that more work is needed along this direction. Most recently, the new use of raw waveforms of speech by DNNs (i.e., zero-feature extraction prior to DNN training) was reported by Tuske et al. (2014). The study not only demonstrated the same advantage of learning precise nonstationary patterns of the speech signal localized in time across frame boundaries, but also reported excellent larger-scale ASR results.

3.3 Better optimization

Better optimization criteria and methods are another area where significant advances have been made over the past several years in applying DNNs to ASR. In 2010, researchers at Microsoft recognized the importance of sequence training based on their earlier experience on GMM-HMM (He et al., 2008; Yu et al., 2007, 2008) and started working on full-sequence discriminative training for the DNN-HMM in phone recognition (Mohamed et al., 2010). Unfortunately, we did not find the right approach to control the overfitting problem. Effective solutions were first reported by Kingsbury et al. (2012) using Hessian-free training, and then by Su et al. (2013) and by Vesely et al. (2013) based on stochastic gradient descent training. These authors developed a set of non-trivial techniques to handle the overfitting problems associated with full-sequence training of DNN-HMMs, including lattice compensation, frame dropping, and F-smoothing, which are widely used today. Other better and novel optimization methods include distributed asynchronous stochastic gradient descent (Dean et al., 2012; Sak et al., 2014a), primal-dual method for applying natural parameter constraints (Chen and Deng, 2014), and Bayesian optimization for automated hyper-parameter tuning (Bergstra et al., 2012).

3.4 A new level of noise robustness

Research into noise robustness in ASR has a long history, mostly before the recent rise of deep learning. A wide range of noise-robust techniques developed over past 30 years can be analyzed and categorized using five different criteria: 1) feature-domain vs. model-domain processing, 2) the use of prior knowledge about the acoustic environment distortion, 3) the use of explicit environment-distortion models, 4) deterministic vs. uncertainty processing, and 5) the use of acoustic models trained jointly with the same feature enhancement or model adaptation process used in the testing stage. See a comprehensive review in (Li et al., 2014) and additional review literature or original work in (Gales, 2011; Acero et al., 2000; Huang et al., 2001; Deng et al., 2005).

The model-domain techniques developed for GMM-HMMs are often not applicable to the new DNN models for ASR. The difficulty arises due primarily to the differences between generative models that GMMs belong and discriminative models that DNNs belong. The feature-domain techniques, however, can be more directly applied to the DNN system. A detailed investigation of the use of DNNs for noise robust speech recognition in the feature domain was reported by Seltzer et al. (2013), who applied the C-MMSE (Yu et al., 2008) feature enhancement algorithm on the input feature used in the DNN. By processing both the training and testing data with the same algorithm, any consistent errors or artifacts introduced by the enhancement algorithm can be learned by the DNN-HMM recognizer. Strong results were obtained on the Aurora4 task. More recently, Kashiwagi et al. (2013) applied the SPLICE feature enhancement technique (Deng et al., 2000, 2001) to a DNN speech recognizer, where the DNN’s output layer was determined on clean data instead of on noisy data as in the study reported by Seltzer et al. (2013).

Recently, a series of studies were reported by Huang et al. (2014) comparing GMMs and DNNs on the mobile voice search and short message dictation datasets. Their data were collected through real-world applications used by millions of users with distinct speaking styles in diverse acoustic environments. A pair of state-of-the-art GMM and DNN models were trained using 400 hours of VS/SMD data. The two models shared the same training data and decision tree. The same GMM seed model was used for the lattice generation in the GMM and the senone state alignment in the DNN. Under such carefully controlled

conditions, the experimental results showed that the DNN-based system yields uniform performance gain over the GMM counterpart across a wide range of SNR levels on all types of datasets and acoustic environments. That is, the use of DNNs raises the performance of noise-robust ASR to a new level. However, this study, the most comprehensive in the noise-robust DNN-based ASR literature so far, also suggests that noise robustness remains an important research area and techniques such as speech enhancement, noise robust acoustic features, or other multi-condition learning methods need to be further explored in the DNN setup.

In the most recent study on noise-robust ASR using deep learning, Hannun et al. (2014) reported an interesting brute-force approach based on “data augmentation.” It is intriguing to see how deep learning, deep recurrent neural nets in particular, make the problem solution conceptually much easier than other approaches discussed above. That is, simply throw in very large amounts of synthesized or “superpositioned” noisy data that capture the right kinds of variability controlled by the synthesis process. The efficient parallel training system was used to training deep speech models with as many as 100,000 hours of such synthesized data and produced excellent results. The challenge for this brute-force approach is to efficiently represent the combinatorially growing size of a multitude of distortion factors known to corrupt speech acoustics under real-world application environments.

3.5 Multi-task and transfer learning

In the area of ASR, the most interesting application of multi-task learning is multi-lingual or cross-lingual ASR, where ASR for different languages is considered as different tasks. Prior to the rise of deep learning, cross-language data sharing and data weighing were already shown to be useful for the GMM-HMM system (Lin et al., 2009). Another successful approach for the GMM-HMM is to map pronunciation units across languages either via knowledge-based or data-driven methods (Yu et al., 2009a). For the more recent, DNN-based systems, these multi-task learning applications in ASR are much more successful.

In the studies reported by Huang et al. (2013) and Heigold et al. (2013), two research groups independently developed closely related DNN architectures with multi-task learning capabilities for multilingual speech recognition. The idea is that the hidden layers in the DNN, when learned appropriately, serve as increasingly complex feature transformations sharing common hidden factors across the acoustic data in different languages. The final softmax layer representing a log-linear classifier makes use of the most abstract feature vectors represented in the top-most hidden layer. While the log-linear classifier is necessarily separate for different languages, the feature transformations can be shared across languages. Excellent multilingual speech recognition results were reported. The implication of this set of work is significant and far reaching. It points to the possibility of quickly building a high-performance DNN-based system for a new language from an existing multilingual DNN. This huge benefit requires only a small amount of training data from the target language, although having more data would further improve the performance. This multitask learning approach can reduce the need for the unsupervised pre-training stage, and can train the DNN with much fewer epochs. Extension of this set of work would be to efficiently build a language-universal speech recognition system. Such a system will not only recognize many languages and improve the accuracy for each individual language, but also expand the languages supported by simply stacking softmax layers on the DNN for new languages.

3.6 Better architectures

The tensor version of the DNN was reported by Yu et al. (2012, 2013) and showed substantially lower ASR errors compared with the conventional DNN. It extends the DNN by replacing one or more of its layers with a double-projection layer and a tensor layer. In the double-projection layer, each input vector is projected into two nonlinear subspaces. In the tensor layer, two subspace projections interact with each other and jointly predict the next layer in the overall deep architecture. An approach is developed to map

the tensor layers to the conventional sigmoid layers so that the former can be treated and trained in a similar way to the latter.

The DNN and its tensor version are fully connected. Locally connected architectures, or (deep) convolutional neural networks (CNN), have each CNN module consisting of a convolutional layer and a pooling layer. The convolutional layer shares weights, and the pooling layer subsamples the output of the convolutional layer and reduces the data rate from the layer below. With appropriate changes from the CNN designed for image recognition to that taking into account speech-specific properties, the CNN has been found effective for ASR (Abdel-Hamid et al., 2012, 2013, 2013a, 2014; Sainath et al., 2013; Deng et al., 2013). Note that the time-delay neural network (TDNN, Waibel et al., 1989) developed for early days of ASR is a special case and predecessor of the CNN when weight sharing is limited to one of the two dimensions, and there is no pooling layer. It was not until recently that researchers have discovered that the time-dimension invariance is less important than the frequency-dimension invariance for ASR (Abdel-Hamid et al., 2012, 2013; Deng et al., 2013).

Another important deep architecture is the (deep) recurrent neural network (RNN), especially its long-short-term memory (LSTM) version. The LSTM was reported to give the lowest error rate on the benchmark TIMIT phone recognition task (Graves et al., 2013). More recently, the LSTM was shown high effectiveness on large-scale tasks with applications to Google Now, voice search, and mobile dictation with excellent accuracy results (Sak et al., 2014, 2014a). To reduce the model size, the otherwise very large output vectors of LSTM units are linearly projected to smaller-dimensional vectors. Asynchronous stochastic gradient descent (ASGD) algorithm with truncated backpropagation through time is performed across hundreds of machines in CPU clusters. The best accuracy was obtained by optimizing the frame-level cross-entropy objective function followed by sequence discriminative training (Sak et al., 2014a).

Another set of novel deep architectures, which are quite different from the standard DNN, are reported in (Deng et al., 2011, 2012; Tur et al., 2012; Vinyals et al., 2012) for successful ASR and related applications including speech understanding. These models are exemplified by the Deep Stacking Network (DSN), its tensor variants (Hutchinson et al., 2012, 2013), and its kernel version (Deng et al., 2012a). The novelty of this type of deep models lies in its modular design, where each module is constructed by taking its input from the output of the lower module concatenated with the original data input, and in the specific way of computing the error gradient of the weight matrices in each module (Yu and Deng, 2012a).

The initial motivation of concatenating the original input vector with the output vector of each DSN module as the new input vector for each higher DSN module was to avoid loss of information when building up higher and higher modules in this deep model. Due to the largely convex learning problem formulated for the DSN training, such concatenation makes training errors (nearly) always decrease as each new module is added to the DSN. It turns out such concatenation is also a natural consequence of another type of deep architecture, called deep unfolding nets (Hershey et al., 2014). These nets are constructed by stacking a number of (shallow) generative models based on non-negative matrix factorization. This stacking process, called unfolding, follows the inference algorithm applied to the original shallow generative model, which determines the nonlinear activation function and also naturally requires the original input vector as part of the inference algorithm. Importantly, this type of deep stacking or unfolding models allow the problem-domain knowledge to be built into the model, which DNNs with generic architectures consisting of weight matrices and fixed forms of nonlinear units would have greater difficulties in incorporating knowledge.

An example of problem-domain knowledge discussed above in the area of speech processing is how noise speech is formed from clean speech and noise. Another example in the area of language processing is how (hidden) topics can be generated from words in text. Note that in these examples, the domain knowledge of

generative type can be parameterized naturally by matrices in the same way that DNNs are parameterized. This enables similar kinds of DNN learning algorithms to apply to fine-tuning the deep stacking or unfolding nets in a straightforward manner. When the generative models cannot be naturally parameterized by matrices, e.g. the deep generative models of speech with temporal dynamics discussed in Section 2.1, how to incorporate such knowledge in integrated deep generative and discriminative models is a challenging research direction. That is, the second kluge discussed in Section 2.2 has yet to be overcome in more general settings than those when the generative models can be parameterized by matrices and common nonlinear functions. Further, when the original generative model moves from shallow to deep, as in the hidden dynamic models discussed in Section 2.1, the inference algorithm itself becomes computationally complex and requires various kinds of approximation; e.g. variational inference. How to build deep unfolding models and to carry out discriminative fine-tuning using backpropagation becomes a more challenging task.

3.7 Summary

Six main areas of achievements and progresses of deep learning in ASR after the initial success of the pre-trained DNN are surveyed in this section. Due to the space limit, several other important areas of progresses are not included here, including adaptation of DNNs for speakers (Yao et al., 2012; Yu et al., 2012), better regularization methods, better nonlinear units, speedup of DNN training and decoding, tensor-based DNNs (Yu et al., 2012, 2013), exploitation of sparseness in DNNs (Yu et al., 2012a), and understanding the underlying mechanisms of DNN feature processing.

In summary, large-scale ASR is the first and the most convincing successful case of deep learning in the recent history, embraced by both industry and academia across the board. Between 2010 and 2014, the two major conferences on signal processing and ASR, IEEE-ICASSP and Interspeech, have seen near exponential growth in the numbers of accepted papers in their respective annual conferences on the topic of deep learning for ASR. More importantly, all major commercial ASR systems (e.g., Microsoft Cortana, Xbox, Skype Translator, Google Now, Apple Siri, Baidu and iFlyTek voice search, and a range of Nuance speech products, etc.) nowadays are based on deep learning methods, the best evidence of high achievements of deep learning in ASR.

In addition to ASR, deep learning is also creating high impact in image recognition (e.g., Krizhevsky et al., 2012) and in speech synthesis (e.g., Ling et al., 2015), as well as in spoken language understanding (Mesnil et al., 2013, 2015). A related major area with perhaps more important practical applications, where deep learning has the potential to make equally strong achievements but where special challenges are lying ahead, will be discussed and analyzed in the next section.

4. DEEP LEARNING FOR NATURAL LANGUAGE AND MULTIMODAL PROCESSING

ASR involves the inference from low-level or raw speech waves to high-level linguistic entities such as word sequences. Image recognition involves the inference from low-level pixels to high-level semantic categories. Due to the reasonably well understood hierarchical, layered structure of human speech and visual perception systems, it is easy to appreciate why deep learning can do so well in ASR and image recognition.

For natural language processing (NLP) and multimodal processing involving language, the raw signal often starts with words, which already embody rich semantic information. As of this writing, one has not observed as striking achievements of deep learning in natural language and multimodal processing as in speech and image recognition, and huge challenges lie ahead. However, strong research activities have been taking place in recent years. In this section, a selected review is provided on some of these progresses.

4.1 A selected review on deep learning for natural language processing

Over the past few years, deep learning methods based on neural nets have been shown to perform well on various NLP tasks such as language modeling, machine translation, part-of-speech tagging, named entity recognition, sentiment analysis, and paraphrase detection, as well as NLP-related tasks involve user behaviors such as computational advertising and web search (informational retrieval). The most attractive aspect of deep learning methods is their ability to perform these tasks without external hand-designed resources or feature engineering. To this end, deep learning develops and makes use of an important concept called “embedding”. That is, each linguistic entity (e.g. word, phrase, sentence, paragraph, or a full text document), a physical entity, a person, a concept, or a relation, which is often represented as a sparse, high-dimensional vector in the symbolic space, can be mapped into a low-dimensional, continuous-space vector via distributed representations by neural nets (Bengio et al., 2003; Collobert et al., 2011; Mikolov et al., 2013; Socher et al., 2013). In the most recent work, such “point” embedding has been generalized to “region” embedding or Gaussian embedding (Vilnis and McCallum, 2015).

Use of deep learning techniques in machine translation, one most important task in NLP applications, has recently attracted much attention. In (Gao et al., 2013, 2014a), the phrase-translation component in a machine translation system is replaced by a set of DNNs with semantic phrase embeddings. A pair of source and target phrases are projected into continuous-valued vector representations in a low-dimensional latent semantic space. Their translation score is then computed by cosine distance between the pair in this new space. In a more recent study, a deep RNN with LSTM cells are used to encode the source sentence into a fixed-length embedding vector, which excites another deep RNN as the decoder that generates the target sentence (Sutskever et al., 2014). Most recently, Bahdanau et al. (2015) reported a neural machine translation approach that learns to align and translate jointly, where the earlier encoder-decoder architecture is extended by allowing a soft search for parts of source sentence relevant to predicting a target word with no need for explicit segmentation.

Another important NLP-related task is knowledge-base completion, instrumental in question-answering and other NLP applications. In (Bordes et al., 2013), a simple method (TransE) was proposed which models relationships by interpreting them as translations operating on the low-dimensional embeddings of the entities. More recent work (Socher et al., 2013) adopts an alternative approach, based on the use of neural tensor networks, to attack the problem of reasoning over a large joint knowledge graph for relation classification. The most recent work (Yang et al., 2015) generalizes these earlier models to a unified learning framework, where entities are represented as low-dimensional dense vectors learned from a neural network and relations are represented by bilinear and/or linear mapping functions. For the NLP problem of question answering, a most recent and highly visible deep learning approach is proposed in (Weston et al., 2015) using memory networks, which use a long-term memory as a dynamic knowledge base. The output of the memory network forms the text response to input questions to the network.

Information retrieval is another important area of NLP applications, where a user enters a keyword or natural language query into the automated computer system that contains a collection of many documents with the goal of obtaining a set of most relevant documents. Web search is a large-scale information retrieval task on largely unstructured web data. Since 2013, Microsoft Research has successfully developed

and applied a specialized deep learning architecture, called deep-structured semantic model or deep semantic similarity model (DSSM; Huang et al., 2013) and its convolutional version (C-DSSM; Shen et al., 2014, 2014a), to web search and related tasks. The DSSM uses the DNN architecture to capture complex semantic properties of the query and the document, and to rank a set of documents for a given query. Briefly, a non-linear projection is performed first to map the query and the documents to a common semantic space. Then, the relevance of each document given the query is calculated as the cosine similarity between their vectors in that semantic space. The DNNs are trained using the click-through data such that the conditional likelihood of the clicked document given the query is maximized. The DSSM is optimized directly for Web document ranking exploiting distantly supervised signals, and thus gives strong performance. Furthermore, to deal with large vocabularies in Web search applications, a new *word hashing* method is developed, through which the high-dimensional term vectors of queries or documents are projected to low-dimensional letter based n -gram vectors.

More recently, the DSSM has been further developed and successfully applied to online ads selection and placement (unpublished), to multitask learning involving both semantic classification and information retrieval tasks (Liu et al., 2015), to entity ranking in an Microsoft Office application (Gao et al., 2014), and to automatic image captioning (Fang et al., 2014, 2015). The latter is a currently trendy multimodal processing task involving natural language, which will be discussed shortly in the next subsection.

4.2 A selected review on deep learning for multimodal processing

Multimodal processing is a class of applications closely related to multitask learning, where the learning domains or “tasks” cut across more than one modalities for practical applications that embrace a mix of natural language, image/video, audio/speech, touch, and gesture. As evidenced in the successful cases in ASR described in Section 3.5, multitask learning fits very well to the paradigm of deep representation learning where the shared representations and statistical strengths across tasks (e.g., those involving separate modalities of audio, image, touch, and text) is expected to greatly facilitate many machine learning scenarios under low-resource conditions. Before deep learning methods were adopted, there had already been numerous efforts in multimodal and multitask learning. For example, a prototype called MiPad for multimodal interactions involving capturing, leaning, coordinating, and rendering a mix of speech, touch, and visual information was developed and reported in (Huang et al., 2001; Deng et al., 2002). In (Zheng et al., 2004; Subramanya et al., 2005), mixed sources of information from multiple-sensory microphones with separate bone-conductive and air-born paths were exploited to de-noise speech. These early studies all used shallow models and achieved worse than desired performance. With the advent of deep learning, it is hopeful that the difficult multi-modal learning problems can be solved with eventual success to enable a wide range of practical applications.

The deep architecture of DeVISE (Deep Visual-Semantic Embedding), developed by Frome et al. (2013), is a typical example of multimodal learning where text information is used to improve the image recognition system. In this system, the loss function used in the training adopts a combination of dot-product similarity and max-margin, hinge rank loss. This is closely related to the cosine distance or maximum-mutual information based loss function used for training the DSSM model in (Huang et al., 2013) described in Section 4.1. The results show that the information provided by text significantly improves zero-shot image predictions, achieving excellent hit rates across thousands of the labels never seen by the image model.

One most interesting application of deep learning methods to multimodal processing appeared recently in November 2014, when several groups almost simultaneously publicized their work on automatic image captioning in ArXiv, all to be revised and officially published at the CVPR-2015 conference. In the Microsoft system (Fang et al., 2014), the image is first broken down into a number of regions likely to be objects, and then a deep CNN is applied to each region to generate a high-level feature vector to capture

relevant visual information. The resulting bag of words are then put together using a language model to produce a set of likely candidate sentences. They are subsequently ranked by the DSSM which captures global semantics of the caption sentence about the image and produces the final answer. Baidu's approach is based on a multimodal RNN that generates novel sentence descriptions to explain the image's content (Mao et al., 2014). Google's paper (Vinyals et al., 2014), and Stanford's paper (Karpathy and Fei-Fei, 2014) described two conceptually similar systems, both based on multimodal RNN generative models conditioned on the image embedding vectors at the first time step. University of Toronto (Kiros et al., 2014) reported a system pipeline that is based on multimodal neural language models that are unified with visual-semantic embeddings produced by the deep CNN. All these systems were evaluated using the common MSR's COCO database, and thus upon final systems' refinement the results of these different systems can be compared.

4.3 Summary

The goal of NLP is to analyze, understand, and generate languages that humans use naturally, and NLP is also a critical component of multimodal systems. Significant progress in NLP has been achieved in recent years, addressing important and practical real-world problems. Deep learning based on embedding methods has contributed to such progress. Words in sequence are traditionally treated as discrete symbols, and deep learning provides continuous-space vector representations that describes words and their semantic and syntactic relationships in a distributed manner permitting meaningfully defined similarity measures. Practical advantages of such representations include natural abilities to mitigate data sparseness, to incorporate longer contexts, and to representing morphological, syntactic and semantic relationships across words and larger linguistic entities. The several NLP and multimodal applications reviewed in this section have all been grounded on vector-space embeddings for the distributed representation of words and larger units as well as of the relations among them. In particular, in multimodal processing, all types of signals---image, voice, text--- are projected into the same semantic vector space in the deep learning framework, greatly facilitating their comparison, integration, and joint processing. The representation power of such flat vectors based on neural networks in contrast with tree-like structure in NLP is currently under active investigation by deep learning, NLP, and cognitive science researchers (Tai et al., 2015).

5. CONCLUSIONS AND CHALLENGES FOR FUTURE WORK

This article reviews part of the history on neural networks and (deep) generative modeling, and reflects on the path to the current triumph of applying deep neural nets to speech recognition, the first successful case of deep learning at industry scale. The roles of generative models have been analyzed in the review, pointing out that key advantages of embedding knowledge about speech dynamics that are naturally enabled by deep generative modeling have yet to be incorporated as part of the new-generation deep learning framework.

For speech recognition, one remaining future challenge lies in how to effectively integrate major relevant speech knowledge and problem constraints into new deep models of the future. Examples of such knowledge and constraints would include distributed, feature-based phonological representations of sound patterns of language via hierarchical structure based on modern phonology, articulatory dynamics and motor program control, acoustic distortion mechanisms for the generation of noisy, reverberant speech in multi-speaker environments, Lombard effects caused by modification of articulatory behavior due to noise-induced reduction of communication effectiveness, and so on. Deep generative models are much better able to impose the problem constraints above than purely discriminative DNNs. These deep generative models should be parameterized to facilitate highly regular, matrix-centric, large-scale computation in order to take advantage of modern high-efficiency GPGPU computing already demonstrated to be extremely fruitful for DNNs. The design of the overall deep computational network architecture of the future may be motivated

by approximate inference algorithms associated with the initial generative model. Then, discriminative learning algorithms such as backpropagation can be developed and applied to learn all network parameters (i.e. large matrices) in an end-to-end fashion. Ultimately, the run-time computation follows the inference algorithm in the generative model, but the parameters have been learned to best discriminate all classes of speech sounds. This is akin to discriminative learning for GMM-HMMs, but now with much more powerful deep architectures and with more comprehensive ways of incorporating speech knowledge. The discriminative learning will be much more powerful (via backprop through the entire deep structure) than the earlier discriminative learning on shallow architectures of GMM-GMMs that relied on extended Baum-Welch algorithm (He et al., 2008).

The past several years of deep learning research and practical applications have established that for perceptual tasks such as speech and image recognition, DNN-like discriminative models perform extremely well and scale beautifully with large amounts of strong supervised training data. Some remaining issues would include: 1) What will be the limit for growing recognition accuracy with respect to further increasing amounts of labeled data? 2) Beyond this limit or when labeled data become exhausted or non-economical to collect, what kind of novel unsupervised or semi-supervised deep learning architectures will emerge? Deep generative models which can naturally handle unlabeled training data appear well suited for meeting this challenge. It is expected that within next four to five years, most of the above issues will be resolved and rapid progress will be made to enable more impressive application scenarios, such as analyzing videos and then telling stories about them by a machine.

For the more difficult and challenging cognitive tasks --- natural language, multimodal processing, reasoning, knowledge, attention, memory, etc. --- deep learning researchers so far have not found as much low-hanging fruit as for the perceptual tasks of speech and image above, and the views for the future development are somewhat less clear. Nevertheless, solid progress has been made over past several years, as we selectively reviewed in Section 4 of this paper. If successful, the revolution created by deep learning for the cognitive tasks will be even more impactful than the revolution in speech and image recognition we have seen so far. Important issues to be addressed and the technical challenges for future developments would include: 1) Will supervised deep learning, which applies to NLP tasks like machine translation, significantly beat the state of the art currently still held by dominant NLP methods as for speech and image recognition tasks? 2) How do we distill and exploit “distant” supervision signals for (weakly) supervised deep learning in the NLP, multimodal and other cognitive tasks? and 3) Will flat dense-vector embedding with distributed representations, which is the backbone of much of the deep learning methods for language as discussed in Section 4, be sufficient for general tasks involving natural language that is known to possess rich tree-like structure? That is, do we need to directly encode and recover syntactic and semantic structure of natural language?

Tackling NLP problems in the deep learning scheme based on embedding may become more promising when the problems are part of wider big-data analytic applications, where not only words and other linguistic entities but also business activities, people, events, and so on may be embedded into the unified vector space. Then the “distant” supervision signals may be mined with broader context than what we discussed in Section 4 for text-centric tasks alone. For example, an email from a sender to a receiver with the email subject line, email body, and possible attachments would readily establish such supervision signals that relate different people in connection with different levels of detail of natural language data. With large amounts of such business-analytic data available including a wealth of weakly supervised information, deep learning is expected to play important roles in a wider range of applications than we have discussed in the current article.

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