

# Implementing Algebraic Effects in C

## “Monads for Free in C”

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**Abstract.** We describe a full implementation of algebraic effects and handlers as a library in standard and portable C99, where effect operations can be used just like regular C functions. We use a formal operational semantics to guide the C implementation at every step where an evaluation context corresponds directly to a particular C execution context. Finally we show a novel extension to the formal semantics to describe optimized tail resumptions and prove that the extension is sound. This gives two orders of magnitude improvement to the performance of tail resumptions (up to about 150 million operations per second on a Core i7@2.6GHz)

## 1. Introduction

Algebraic effects [33] and handlers [34, 35] come from category theory as a way to reason about effects. Effects come with a set of operations as their interface, and handlers to give semantics to the operations. Any free monad [2, 17, 37] can be expressed using algebraic effect handlers: the operations describe an algebra that gives rise to a free monad, whereas the handler is the *fold* over that algebra giving its semantics.

This makes algebraic effects highly expressive and practical, and they can describe many control flow constructs that are usually built into a language or compiler. Examples include, exception handling, iterators, backtracking, and *async/await* style asynchronous programming. Once you have algebraic effects, all of these abstractions can be implemented *as a library* by the user. In this article, we describe a practical implementation of algebraic effects and handlers as a library itself in C. In particular,

- We describe a full implementation of algebraic effects and handlers in standard and portable C99. Using effect operations is just like calling regular C functions. Stacks are always restored at the same location and regular C semantics are preserved.
- Even though the semantics of algebraic effects are simple, the implementation in C is not straightforward. We use a formal operational semantics to guide the C implementation at every step. In particular, we use context

based semantics where a formal context corresponds directly to a particular C execution context.

- We show a novel extension to the formal semantics to describe optimized tail resumptions and prove that the extension is sound. This gives two orders of magnitude improvement to the performance of tail resumtive operations (up to about 150 million operations per second on a Core i7).

At this point using effects in C is nice, but defining handlers is still a bit cumbersome. Its interface could probably be improved by providing a C++ wrapper. For now, we mainly see the library as a target for library writers or compilers. For example, the P language [10] is a language for describing verifiable asynchronous state machines, and used for example to implement and verify the core of the USB device driver stack that ships with Microsoft Windows 8. Compiling to C involves a complex CPS-style transformation [19, 25] to enable `async/await` style programming [5] with a `receive` statement – using the effects library this transformation is no longer necessary and we can generate straightforward C code instead. Similarly, we hope to integrate this library with `libuv` [28] (the asynchronous C library underlying Node [40]) and improve programming with `libuv` directly from C or C++ using `async/await` style abstractions [12, 26].

The library is publicly available as `libhandler` under an open-source license [27]. For simplicity the description in this paper leaves out many details and error handling etc. but otherwise follows the real implementation closely.

## 2. Overview

We necessarily give a short overview here of using algebraic effects in C. For how this can look if a language natively supports effects, we refer to reader to other work [3, 18, 25, 26, 29]. Even though the theory of algebraic effects describes them in terms of monads, we use a more operational view in this article that is just as valid – and view effects as *resumable exceptions*. Therefore we start by describing how to implement regular exceptions using effect handlers.

### 2.1. Exceptions

We start by implementing exceptions as an algebraic effect. First we declare a new effect `exn` with a single operation `raise` that takes a `const char*` argument:

```
DEFINE_EFFECT1(exn, raise)
DEFINE_VOIDOP1(exn, raise, string)
```

Later we will show exactly what these macros expand to. For now, it is enough to know that the second line defines a new operation `exn_raise` that we can call as any other C function, for example:

```
int divexn( int x, int y ) {
    return (y!=0 ? x / y : exn_raise("divide by zero")); }
```

Since using an effect operation is just like calling a regular C function, this makes the library very easy to use from a user perspective.

Defining *handlers* is a bit more involved. Here is a possible handler function for our `raise` operation:

```
value handle_exn_raise(resume* r, value local, value arg) {
    printf("exception raised: %s\n", string_value(arg));
    return value_null; }
```

The `value` type is used here to simulate parametric polymorphism in C and is typedef'd to a `long long`, together with some suitable conversion macros; in the example we use `string_value` to cast the `value` back to the `const char*` argument that was passed to `exn_raise`.

Using the new operation handler is done using the `handle` library function. It is a bit cumbersome as we need to set up a handler definition (`handlerdef`) that contains a table of all operation handlers<sup>1</sup>:

```
const operation _exn_ops[] = {
    { OP_NORESUME, OPTAG(exn,raise), &handle_exn_raise } };
const handlerdef _exn_def = { EFFECT(exn), NULL, NULL, NULL, _exn_ops };

value my_exn_handle(value(*action)(value), value arg) {
    return handle(&_exn_def, value_null, action, arg); }
```

Using the handler, we can run the full example as:

```
value divide_by(value x) {
    return value_long(divexn(42,long_value(x)));
}
int main() {
    my_exn_handle( divide_by, value_long(0));
    return 0; }
```

When running this program, we'll see:

```
exception raised: divide by zero
```

A handler definition has as its last field a list of operations, defined as:

```
typedef struct _operation {
    const opkind opkind;
    const optag optag;
    value (*opfun)(resume* r, value local, value arg);
} operation;
```

The operation tag `optag` uniquely identifies the operation, while the `opkind` describes the kind of operation handler:

```
typedef enum _opkind {
    OP_NULL,
    OP_NORESUME, // never resumes
    OP_TAIL,     // only uses `resume` in tail-call position
}
```

---

<sup>1</sup> Ah, if only we had lambda expressions and virtual methods in C99 ;-)

```

    OP_SCOPED,    // only uses `resume` inside the handler
    OP_GENERAL   // `resume` is a first-class value
} opkind;

```

These operation kinds are used for optimization and restrict what an operation handler can do. In this case we used `OP_NORESUME` to signify that our operation handler never resumes. We’ll see examples of the other kinds in the following sections.

The `DEFINE_EFFECT` macro defines a new effect. For our example, it expands into something like:

```

const char* effect_exn[3] = {"exn", "exn_raise", NULL};
const optag optag_exn_raise = { effect_exn, 1 };

```

An effect can now be uniquely identified by the address of the `effect_exn` array, and `EFFECT(exn)` expands simply into `effect_exn`. Similarly, `OPTAG(exn,raise)` expands into `optag_exn_raise`. Finally, the `DEFINE_VOIDOP1` definition in our example expands into a small wrapper around the library `yield` function:

```

void exn_raise( const char* s ) {
    yield( optag_exn_raise, value_string(s) ); }

```

which “yields” to the innermost handler for `exn_raise`.

## 2.2. Ambient State

As we saw in the exception example, the handler for the `raise` operation took a `resume*` argument. This can be used to *resume* an operation at the point where it was issued. This is where the true power of algebraic effects come from (and why we can view them as resumable exceptions). As another example, we are going to implement *ambient state* [26].

```

DEFINE_EFFECT(state,put,get)
DEFINE_OPO(state,get,int)
DEFINE_VOIDOP1(state,put,int)

```

This defines a new effect `state` with the operations `void state_put(int)` and `int state_get()`. We can use them as any other C function:

```

void loop() {
    int i;
    while((i = state_get()) > 0) {
        printf("state: %i\n", i);
        state_put(i-1);
    }
}

```

We call this *ambient state* since it is dynamically bound to the innermost state handler – instead of being global or local state. This captures many common patterns in practice. For example, when writing a web server, the “current” request object needs to be passed around manually to each function in general; with algebraic effects you can just create a `request` effect that gives access to

the current request without having to pass it explicitly to every function. The handler for `state` uses the `local` argument to store the current state:

```
value handle_state_get( resume* r, value local, value arg ) {
  return tail_resume(r,local,local);
}
value handle_state_put( resume* r, value local, value arg ) {
  return tail_resume(r,arg,value_null);
}
```

The `tail_resume` (or `resume`) library function resumes an operation at its yield point. It takes three arguments: the resumption object `r`, the new value of the local handler state `local`, and the return value for the `yield` operation. Here the `handle_state_get` handler simply returns the current local state, whereas `handle_state_put` returns a null value but resumes with its local state set to `arg`. The `tail_resume` operation can only be used in a tail-call position and only with `OP_TAIL` operations, but it is much more efficient than using a general `resume` function (as shown in Section 5).

### 2.3. Backtracking

You can enter a room once, yet leave it twice.

— Peter Landin [22, 23]

In the previous examples we looked at an abstractions that never resume (e.g. exceptions), and an abstractions that resumes once (e.g. `state`). Such abstractions are common in most programming languages. Less common are abstractions that can resume more than once. Examples of this behavior can usually only be found in languages like Lisp and Scheme, that implement some variant of `callcc` [39]. A nice example to illustrate multiple resumptions is the ambiguity effect:

```
DEFINE_EFFECT1(amb,flip)
DEFINE_BOOLOPO(amb,flip,bool)
```

which defines one operation `bool amb_flip()` that returns a boolean. We can use it as:

```
bool xor() {
  bool p = amb_flip();
  bool q = amb_flip();
  return ((p || q) && !(p && q)); }
```

One possible handler just returns a random boolean on every flip:

```
value random_amb_flip( resume* r, value local, value arg ) {
  return tail_resume(r, local, value_bool( rand()%2 )); }
```

but a more interesting handler resumes *twice*: once with a `true` result, and once with `false`. That way we can return a list of all results from the handler:

```
value all_amb_flip( resume* r, value local, value arg ) {
  value xs = resume(r,local, value_bool(true)); }
```

```

    value ys = resume(r,local, value_bool(false)); // resume again at `r`!
    return list_append(xs,ys); }

```

Note that the results of the `resume` operations are lists themselves since a resumption runs itself under the handler. When we run the `xor` function under the `all_amb` handler, we get back a list of all possible results of running `xor`, printed as:

```
[false,true,true,false]
```

In general, resuming more than once is a dangerous thing to do in C. When using mutable state or external resources, most C code assumes it runs at most once, for example closing file handles or releasing memory when exiting a lexical scope. Resuming again from inside such scope would give invalid results.

Nevertheless, you can make this work safely if you for example manage state using effect handlers themselves which take care of releasing resources correctly. Multiple resumptions are also needed for implementing `async/await` interleaving where the resumptions are safe by construction.

Combining the `state` and `amb` handlers is also possible; if we put `state` as the outermost handler, we get a “global” state per ambiguous strand, while if we switch the order, we get a “local” state per ambiguous strand. We refer to other work for a more in-depth explanation [3, 25].

## 2.4. Asynchronous Programming

Recent work shows how to build `async/await` abstractions on top of algebraic effects [12, 26]. We plan to use a similar approach to implement a nice interface to programming `libuv` directly in C. This is still work in progress and we only sketch here the basic approach to show how algebraic effects can enable this. We define an asynchronous effect as:

```

DEFINE_EFFECT1(async,await)
int  await( uv_req_t* req );
void async_callback(uv_req_t* req);

```

The handler for `async` only needs to implement `await`. This operation receives an asynchronous `libuv` request object `uv_req_t` where it only stores its resumption in the request custom `data` field. However, it does not resume itself! Instead it returns directly to the outer `libuv` event loop which invokes the registered callbacks when an asynchronous operation completes.

```

value handle_async_await( resume* r, value local, value arg ) {
    uv_req_t* req = (uv_req_t*)ptr_value(arg);
    req->data = r;
    return value_null; }

```

We ensure that the asynchronous `libuv` functions all use the same `async_callback` function as their callback. This in turn calls the actual resumption that was stored in the `data` field by `await`:

Expressions	$e ::= e(e)$	application
	$\text{val } x = e; e$	binding
	$\text{handle}_h(e)$	handler
	$v$	value
Values	$v ::= x \mid c \mid op \mid \lambda x. e$	
Clauses	$h ::= \text{return } x \rightarrow e$	
	$op(x) \rightarrow e; h$	$op \notin h$

---

**Figure 1.** Syntax of expressions in  $\lambda_{\text{eff}}$

```
void async_callback( uv_req_t* req ) {
  resume* r = (resume*)req->data;
  resume(r, req->result); }
```

In other words, instead of explicit callbacks with the current state encoded in the `data` field, the current execution context is fully captured by the first-class resumption provided by our library. We can now write small wrappers around the `libuv` asynchronous API to use the new `await` operation, for example, here is the wrapper for an asynchronous file stat:

```
int async_stat( const char* path, uv_stat_t* stat ) {
  uv_fs_t* req = (uv_fs_t*)malloc(sizeof(uv_fs_t));
  uv_stat(uv_default_loop(), req, path, async_callback); // register
  int err = await((uv_req_t*)req); // and await
  *stat = req->statbuf;
  uv_fs_req_cleanup(req); free(req);
  return content; }
```

The asynchronous functions can be called just like regular functions:

```
uv_stat_t stat;
int err = async_stat("foo.txt", &stat); // asynchronous!
printf("Last access time: %li\n", (err < 0 ? 0 : stat.st_atim.tv_sec));
```

This would make it as easy to use `libuv` as using the standard C libraries for doing I/O.

### 3. Operational Semantics

An attractive feature of algebraic effects and handlers is that they have a simple operational semantics that is well-understood. To guide our implementation in C we define a tiny core calculus for algebraic effects and handlers that is well-suited to reason about the operational behavior.

Figure 1 shows the syntax of our core calculus,  $\lambda_{\text{eff}}$ . This is equivalent to the definition given by Leijen [25]. It consists of basic lambda calculus extended with handler definitions  $h$  and operations  $op$ . The calculus can also be typed

$$\begin{array}{l}
\text{Evaluation contexts:} \\
\mathbf{E} ::= [] \mid \mathbf{E}(e) \mid v(\mathbf{E}) \mid \text{op}(\mathbf{E}) \mid \text{val } x = \mathbf{E}; e \mid \text{handle}_h(\mathbf{E}) \\
\mathbf{X}_{op} ::= [] \mid \mathbf{X}_{op}(e) \mid v(\mathbf{X}_{op}) \mid \text{val } x = \mathbf{X}_{op}; e \\
\quad \mid \text{handle}_h(\mathbf{X}_{op}) \qquad \qquad \qquad \text{if } op \notin h
\end{array}$$

$$\begin{array}{l}
\text{Reduction rules:} \\
(\delta) \quad c(v) \quad \longrightarrow \quad \delta(c, v) \quad \text{if } \delta(c, v) \text{ is defined} \\
(\beta) \quad (\lambda x. e)(v) \quad \longrightarrow \quad e[x \mapsto v] \\
(\text{let}) \quad \text{val } x = v; e \quad \longrightarrow \quad e[x \mapsto v] \\
\\
(\text{return}) \quad \text{handle}_h(v) \quad \longrightarrow \quad e[x \mapsto v] \\
\qquad \qquad \qquad \qquad \qquad \qquad \text{with} \\
\qquad \qquad \qquad \qquad \qquad \qquad (\text{return } x \rightarrow e) \in h \\
\\
(\text{handle}) \quad \text{handle}_h(\mathbf{X}_{op}[op(v)]) \quad \longrightarrow \quad e[x \mapsto v, \text{resume} \mapsto \lambda y. \text{handle}_h(\mathbf{X}_{op}[y])] \\
\qquad \qquad \qquad \qquad \qquad \qquad \text{with} \\
\qquad \qquad \qquad \qquad \qquad \qquad (op(x) \rightarrow e) \in h
\end{array}$$

---

**Figure 2.** Reduction rules and evaluation contexts

using regular static typing rules [18, 25, 36]. However, we can still give a dynamic *untyped* operational semantics: this is important in practice as it allows an implementation algebraic effects without needing explicit types at runtime.

Figure 2 defines the semantics of  $\lambda_{\text{eff}}$  in just five evaluation rules. It has been shown that well-typed programs cannot go ‘wrong’ under these semantics [25]. We use two evaluation contexts: the  $\mathbf{E}$  context is the usual one for a call-by-value lambda calculus. The  $\mathbf{X}_{op}$  context is used for handlers and evaluates down through any handlers that do *not* handle the operation  $op$ . This is used to express concisely that the ‘innermost handler’ handles particular operations.

The  $\mathbf{E}$  context concisely captures the entire evaluation context, and is used to define the evaluation function over the basic reduction rules:  $\mathbf{E}[e] \mapsto \mathbf{E}[e']$  iff  $e \longrightarrow e'$ . The first three reduction rules,  $(\delta)$ ,  $(\beta)$ , and  $(\text{let})$  are the standard rules of call-by-value evaluation. The final two rules evaluate handlers. Rule  $(\text{return})$  applies the return clause of a handler when the argument is fully evaluated. Note that this evaluation rule subsumes both lambda- and let-bindings and we can define both as a reduction to a handler without any operations:

$$\begin{array}{l}
(\lambda x. e_1)(e_2) \quad \equiv \quad \text{handle}\{\text{return } x \rightarrow e_1\}(e_2) \\
\text{val } x = e_1; e_2 \quad \equiv \quad \text{handle}\{\text{return } x \rightarrow e_2\}(e_1)
\end{array}$$

These equivalences are used in the Frank language [29] to express everything in terms of handlers.

The next rule,  $(\text{handle})$ , is where all the action is. Here we see how algebraic effect handlers are closely related to delimited continuations as the evaluation rules captures a delimited ‘stack’  $\mathbf{X}_{op}[op(v)]$  under the handler  $h$ . Using a  $\mathbf{X}_{op}$  context ensures by construction that only the innermost handler containing a



clause for  $op$ , can handle the operation  $op(v)$ . Evaluation continues with the expression  $\epsilon$  but besides binding the parameter  $x$  to  $v$ , also the *resume* variable is bound to the continuation:  $\lambda y. \text{handle}_h(\mathbf{X}_{op}[y])$ . Applying *resume* results in continuing evaluation at  $\mathbf{X}_{op}$  with the supplied argument as the result. Moreover, the continued evaluation occurs again under the handler  $h$ .

Resuming under the same handler is important as it ensures that our semantics correspond to the original categorical interpretation of algebraic effect handlers as a *fold* over the effect algebra [35]. If the continuation is not resumed under the same handler, it behaves more like a *case* statement doing only one level of the *fold*. Such handlers are sometimes called *shallow handlers* [20, 29].

For this article we do not formalize parameterized handlers as shown in Section 2.2. However the reduction rule is straightforward. For example, a handler with a single parameter  $p$  is reduced as:

$$\begin{aligned} \text{handle}_h(p = v_p)(\mathbf{X}_{op}[op(v)]) &\longrightarrow \{ op(v) \rightarrow e \in h \} \\ e[x \mapsto v, p \mapsto v_p, \text{resume} \mapsto \lambda q y. \text{handle}_h(p = q)(\mathbf{X}_{op}[y])] \end{aligned}$$

### 3.1. Dot Notation

The C implementation closely follows the formal semantics. We will see that we can consider the contexts as the current evaluation context in C, i.e. the call stack and instruction pointer. To make this more explicit, we use *dot* notation to express the notion of a context as call stack more clearly. We write  $\cdot$  as a right-associative operator where  $e \cdot e' \equiv e(e')$  and  $\mathbf{E} \cdot e \equiv \mathbf{E}[e]$ . Using this notation, we can for example write the (*handle*) rule as:

$$\text{handle}_h \cdot \mathbf{X}_{op} \cdot op(v) \longrightarrow e[x \mapsto v, \text{resume} \mapsto \lambda y. \text{handle}_h \cdot \mathbf{X}_{op} \cdot y]$$

where  $(op(x) \rightarrow e) \in h$ . This more clearly shows that we evaluate  $op(v)$  under a current “call stack”  $\text{handle}_h \cdot \mathbf{X}_{op}$  (where  $h$  is the innermost handler for  $op$  as induced by the grammar of  $\mathbf{X}_{op}$ ).

## 4. Implementing Effect Handlers in C

The main contribution of this paper is showing how we can go from the operational semantics on an idealized lambda-calculus to an implementation as a C library. All the regular evaluation rules like application and let-bindings are already part of the C language. Of course, there are no first-class lambda expressions either so we must make do with top-level functions only. So, our challenge is to implement the (*handle*) rule:

$$\text{handle}_h \cdot \mathbf{X}_{op} \cdot op(v) \longrightarrow e[x \mapsto v, \text{resume} \mapsto \lambda y. \text{handle}_h \cdot \mathbf{X}_{op} \cdot y]$$

where  $(op(x) \rightarrow e) \in h$ . For this rule, we can view “ $\text{handle}_h \cdot \mathbf{X}_{op}$ ” as our current execution context, i.e. as a *stack* and instruction pointer. In C, the execution context is represented by the current call stack and the current register context, including the instruction pointer. That means:

1. When we enter a handler, push a `handleh` frame on the stack.
2. When we encounter an operation  $op(v)$ , walk down the call stack “`E · handleh · Xop`” until we find a handler for our operation.
3. Capture the current execution context “`handleh · Xop`” (call stack and registers) into a `resume` structure.
4. Jump to the handler  $h$  (restoring its execution context), and pass it the operation  $op$ , the argument  $v$ , and the captured resumption.

In the rest of this article, we assume that a stack always grows up with any parent frames “below” the child frames. In practice though, most platforms have downward growing stacks and the library adapts dynamically to that.

#### 4.1. Entering a Handler

When we enter a handler, we need to push a handler frame on the stack. Effect handler frames are defined as:

```
typedef struct _handler {
    jmp_buf          entry;           // used to jump back to a handler
    const handlerdef* hdef;          // operation definitions
    volatile value   arg;            // the operation argument is passed here
    const operation* arg_op;         // the yielded operation is passed here
    resume*          arg_resume;     // the resumption function
    void*            stackbase;      // stack frame address of the handler function
} handler;
```

Each handler needs to keep track of its `stackbase` – when an operation captures its resumption, it only needs to save the stack up to its handler’s `stackbase`. The `handle` function starts by recording the `stackbase`:

```
value handle( const handlerdef* hdef,
              value (*action)(value), value arg ) {
    auto void* base = (void*)&base;
    return handle_upto( hdef, base, action, arg );
}
```

The stack base is found by taking the address of the local variable `base` itself; this is a good conservative estimate of an address just below the frame of the handler. We mark `handle_upto` as `noinline` to ensure it gets its own stack frame just above `base`:

```
noinline value handle_upto( hdef, base, action, arg ) {
    handler* h = hstack_push();
    h->hdef = hdef;
    h->stackbase = base;
    value res;
    if (setjmp(h->entry) == 0) {
        // (H1): we recorded our register context
        ...
    }
    else {
```

```

    // (H2): we long jumped here from an operation
    ...
}
// (H3): returning from the handler
return res; }

```

This function pushes first a fresh `handler` on a *shadow* handler stack. In principle, we could have used the C stack to “push” our handlers simply by declaring it as a local variable. However, as we will see later, it is more convenient to maintain a separate shadow stack of handlers which is simply a thread-local array of handlers. Next the handler uses `setjmp` to save its execution context in `h->entry`. This is used later by an operation to `longjmp` back to the handler. On its invocation, `setjmp` returns always 0 and the (H1) block is executed next. When it is long jumped to, the (H2) block will execute.

For our purposes, we need a standard C compliant `setjmp/longjmp` implementation; namely one that just saves all the necessary registers and flags in `setjmp`, and restores them all again in `longjmp`. Since that includes the stack pointer and instruction pointer, `longjmp` will effectively “jump” back to where `setjmp` was called with the registers restored. Unfortunately, we sometimes need to resort to our own assembly implementations on some platforms. For example, the Microsoft Visual C++ compiler (`msvc`) will unwind the stack on a `longjmp` to invoke destructors and finalizers for C++ code [32]. On other platforms, not always all register context is saved correctly for floating point registers. We have seen this in library code for the ARM Cortex-M for example. Fortunately, a compliant implementation of these routines is straightforward as they just move registers to and from the `entry` block. Appendix A.1 shows an example of the assembly code for `setjmp` on 32-bit x86.

**4.1.1. Handling Return** The (H1) block in `handle_upto` is executed when `setjmp` finished saving the register context. It starts by calling the `action` with its argument:

```

if (setjmp(h->entry) == 0) {
    // we recorded our register context
    res = action(arg);
    hstack_pop();           // pop our handler
    res = hdef->retfun(res); // invoke the return handler
}

```

If the action returns normally, we are in the (*return*) rule:

$$\text{handle}_h \cdot v \longrightarrow e[x \mapsto v] \quad \text{with } (\text{return} \rightarrow e) \in h$$

We have a handler `h` on the handler stack, and the result value `v` in `res`. To proceed, we call the return handler function `retfun` (i.e. `e`) with the argument `res` (i.e. `x ↦ v`) – but only after popping the `handleh` frame.

**4.1.2. Handling an Operation** The (H2) block of `handle_upto` executes when an operation long jumps back to our handler entry:

```

else {
    // we long jumped here from an operation
    value arg = h->arg;           // load our parameters
    const operation* op = h->arg_op;
    resume* resume = h->arg_resume;
    hstack_pop();                // pop our handler
    res = op->opfun(resume, arg); // and call the operation
}

```

This is one part of the (*handle*) rule:

$$\text{handle}_h \cdot X_{op} \cdot op(v) \longrightarrow e[x \mapsto v, \text{resume} \mapsto \lambda y. \text{handle}_h \cdot X_{op} \cdot y]$$

where  $(op(x) \rightarrow e) \in h$ . At this point, the yielding operation just jumped back and the  $X_{op}$  part of the stack has been “popped” by the long jump. Moreover, the yielding operation has already captured the resumption *resume* and stored it in the handler frame `arg_resume` field together with the argument *v* in `arg` (Section 4.2). We store them in local variables, pop the handler frame `handle_h`, and execute the operation handler function *e*, namely `op->opfun`, passing the resumption and the argument.

## 4.2. Yielding an Operation

Calling an operation  $op(v)$  is done by a function call `yield(OPTAG(op), v)`:

```

value yield(const optag* optag, value arg) {
    const operation* op;
    handler* h = hstack_find(optag, &op);
    if (op->opkind==OP_NORESUME) yield_to_handler(h, op, arg, NULL);
    else return capture_resume_yield(h, op, arg); }

```

First we call `hstack_find(optag, &op)` to find the first handler on the handler stack that can handle `optag`. It returns the a pointer to the handler frame and a pointer to the operation description in `&op`. Next we make our first optimization: if the operation handler does not need a resumption, i.e. `op->opkind==OP_NORESUME`, we can pass `NULL` for the resumption and not bother capturing the execution context. In that case we immediately call `yield_to_handler` with a `NULL` argument for the resumption. Otherwise, we capture the resumption first using `capture_resume_yield`. The `yield_to_handler` function just long jumps back to the handler:

```

noreturn void yield_to_handler( handler* h, const operation* op,
                               value oparg, resume* resume ) {
    hstack_pop_upto(h);        // pop handler frames up to `h`
    h->arg = oparg;            // pass the arguments in then handler fields
    h->arg_op = op; h->arg_resume = resume;
    longjmp(h->entry, 1); }    // and jump back down! (to (H2))

```

**4.2.1. Capturing a Resumption** At this point we have a working implementation of effect handlers without *resume* and basically implemented custom exception handling. The real power comes from having first-class resumptions though. In the (*handle*) rule, the resumption is captured as:

$$\text{resume} \mapsto \lambda y. \text{handle}_h \cdot X_{op} \cdot y$$

This means we need to capture the current execution context, “ $\text{handle}_h \cdot X_{op}$ ”, so we can later resume in the context with a result  $y$ . The execution context in C would be the stack up to the handler together with the registers. This is done by `capture_resume_yield`:

```
value capture_resume_yield(handler* h, const operation* op, oparg ) {
    resume* r = (resume*)malloc(sizeof(resume));
    r->refcount = 1; r->arg = lh_value_null;
    // set a jump point for resuming
    if (setjmp(r->entry) == 0) {
        // (Y1) we recorded the register context in `r->entry`
        void* top = get_stack_top();
        capture_cstack(&r->cstack, h->stackbase, top);
        capture_hstack(&r->hstack, h);
        yield_to_handler(h, op, oparg, r); } // back to (H2)
    else {
        // (Y2) we are resumed (and long jumped here from (R1))
        value res = r->arg;
        resume_release(r);
        return res;
    } }
}
```

A resumption structure is allocated first; it is defined as:

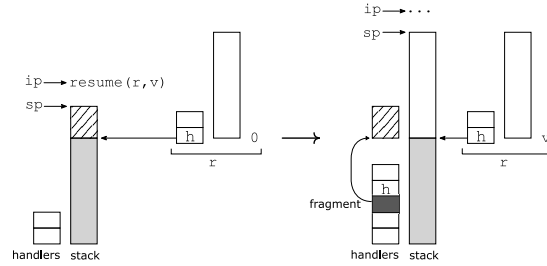
```
typedef struct _resume {
    ptrdiff_t refcount; // resumptions are heap allocated
    jmp_buf entry; // jump point where the resume was captured
    cstack cstack; // captured call stack
    hstack hstack; // captured handler stack
    value arg; // the argument to `resume` is passed through `arg`.
} resume;
```

Once allocated, we initialize its reference count to `1` and record the current register context in its `entry`. We then proceed to the (Y1) block to capture the current call stack and handler stack.

These structures are defined as:

```
typedef struct _hstack {
    ptrdiff_t count; // number of valid handlers in hframes
    ptrdiff_t size; // total entries available
    handler* hframes; // array of handlers (0 is bottom frame)
} hstack;

typedef struct _cstack {
    void* base; // The base of the stack part
```



**Figure 3.** Resuming a resumption  $r$  that captured the stack up to a handler  $h$ . The captured stack will overwrite the striped part of the existing stack, which is saved by a fragment handler. The argument  $v$  is passed in the `arg` field of the resumption  $r$ .

```

ptrdiff_t size;    // The byte size of the captured stack
byte*     frames  // The captured stack data (allocated in the heap)
} cstack;

```

Capturing the handler stack is easy and `capture_hstack(&r->hstack,h)` just copies all handlers up to and including  $h$  into  $r$ 's `hstack` field (allocating as necessary). Capturing the C call stack is a bit more subtle. To determine the current top of the stack, we cannot use our earlier trick of saying

```
void* top = (void*)&top;
```

since that may underestimate the actual stack used: the compiler may have put some temporaries above the `top` variable, and ABI's like the System V `amd64` include a *red zone* which is a part of the stack pointer where the compiler can freely spill registers [31,3.2.2]. Instead, we call a child function that captures its stack top instead as a guaranteed conservative estimate:

```

noinline void* get_stack_top() {
    auto void* top = (void*)&top;
    return top; }

```

The piece of stack that needs to be captured is exactly between the lower estimate of the handler `stackbase` up to the upper estimate of our stack `top`. The `capture_cstack(&r->cstack,h->stackbase,top)` allocates a `cstack` and `memcpy`'s into that from the C stack.

At this point the resumption structure is fully initialized and captures the delimited execution context. We can now use the previous `yield_to_handler` to jump back to the handler with the operation, its argument, and a first-class `resume` structure.

### 4.3. Resuming

Now that we can capture a resumption, we can define how to resume one. In our operational semantics, a resumption is just a lambda expression:

$$resume \mapsto \lambda y. \text{handle}_h \cdot X_{op} \cdot y$$

and resuming is just application,  $E \cdot \text{resume}(v) \longrightarrow E \cdot \text{handle}_h \cdot X_{op} \cdot v$ . For the C implementation, this means pushing the captured stack onto the main stacks and passing the argument  $v$  in the `arg` field of the resumption. Unfortunately, we cannot just push our captured stack on the regular call stack. In C, often local variables *on the stack* are passed by reference to child functions. For example,

```
char buf[N];  snprintf(buf,N,"address of buf: %p", buf);
```

Suppose inside `snprintf` we call an operation that captures the stack. If we resume and restore the stack at a different starting location, then all those stack relative addresses are wrong! In the example, `buf` is now at a different location in the stack, but the address passed to `snprintf` is still the same.

Therefore, we must *always restore a stack at the exact same location*, and we need to do extra work in the C implementation to maintain proper stacks. In particular, when jumping back to an operation (H2), the operation may call the resumption. At that point, restoring the original captured stack will need to overwrite part of the current stack of the operation handler!

**4.3.1. Fragments** This situation is shown in Figure 3. It shows a resumption `r` that captured the stack up to a handler `h`. The arrow from `h` points to the `stackbase` which is below the current stack pointer. Upon restoring the saved stack in `r`, the striped part of the stack is overwritten. This means:

1. We first save that part of the stack in a `fragment` which saves the register context and part of a C stack.
2. We push a special `fragment` handler frame on the handler stack just below the newly restored handler `h`. When `h` returns, we can now restore the original part of the call stack from the `fragment`.

The implementation of resuming becomes:

```
value resume(resume* r, value arg) {
    fragment* f = (fragment*)malloc(sizeof(fragment));
    f->refcount = 1; f->res = value_null;
    if (setjmp(f->entry) == 0) {
        // (R1) we saved our register context
        void* top = get_stack_top();
        capture_cstack(&f->cstack, cstack_bottom(&r->cstack), top);
        hstack_push_fragment(f); // push the fragment frame
        hstack_push_frames(r->hstack); // push the handler frames
        r->arg = arg; // pass the argument to resume
        jumpto(r->cstack, r->entry); } // and jump (to (Y2))
    else {
        // (R2) we jumped back to our fragment from (H3).
        value res = f->res; // save the resume result to a local
        hstack_pop(hs); // pop our fragment frame
        return res; // and return the resume result
    } }
}
```

The `capture_cstack` saves the part of the current stack that can be overwritten into our fragment. Note that this may capture an “empty” stack if the stack happens to be below the part that is restored. This only happens with resumptions though that escape the scope of an operation handler (i.e. *non-scoped* resumptions). The `jump_to` function restores an execution context by restoring a C stack and register context. We discuss the implementation in the next section.

First, we need to supplement the handler function `handle_upto` to take `fragment` handler frames into account. In particular, every handler checks whether it has a fragment frame below it: if so, it was part of a resumption and we need to restore the original part of the call stack saved in the fragment. We add the following code to (H3):

```

noinline value handle_upto( hdef, base, action, arg ) {
    ...
    // (H3): returning from the handler
    if (hstack_top_is_fragment()) {
        fragment* f = hstack_top_fragment();
        f->res = res; // pass the result
        jump_to(f->cstack, f->entry); // and restore the fragment (to (R2))
    }
    return res; }

```

Here we use the same `jump_to` function to restore the execution context. Unwinding through fragments also needs to be done with care to restore the stack correctly; we discuss this in detail in Appendix A.2.

**4.3.2. Jump\_to: Restoring an Execution Context** The `jump_to` function takes a C stack and register context and restores the C stack at the original location and long jumps. We cannot implement this directly though as:

```

noreturn void jump_to( cstack* cstack, jmp_buf* entry ) {
    // wrong!
    memcpy(c->base, c->frames, c->size); // restore the stack
    longjmp(*entry, 1); // restore the registers
}

```

In particular, the `memcpy` may well overwrite the current stack frame of `jump_to`, including the `entry` variable! Moreover, some platforms use a `longjmp` implementation that aborts if we try to jump up the stack [14].

The trick is to do `jump_to` in two parts: first we reserve in `jump_to` enough stack space to contain the stack we are going to restore and a bit more. Then we call a helper function `_jump_to` to actually restore the context. This function is now guaranteed to have a proper stack frame that will not be overwritten:

```

noreturn noinline
void _jump_to( byte* space, cstack* cstack, jmp_buf* entry ) {
    space[0] = 0; // make sure is live
    memcpy(c->base, c->frames, c->size); // restore the stack
    longjmp(*entry, 1); // restore the registers
}
noreturn void jump_to(cstack* cstack, jmp_buf* entry ) {

```



Compiler	Native (s)	Effects (s)	Slowdown	Operation Cost	Ops/s
msvc 2015 /02	0.00057	0.1852	326×	162 · sqrt	1.158 · 10 <sup>6</sup>
clang 3.8.0 -03	0.00056	0.1565	279×	139 · sqrt	1.402 · 10 <sup>6</sup>
gcc 5.4.0 -03	0.00056	0.1883	336×	167 · sqrt	1.193 · 10 <sup>6</sup>

**Figure 4.** Performance using full resumptions. All measurements are on a 2016 Surface Book with an Intel Core i7-6600U at 2.6GHz with 8GB ram (LPDDR3-1866) using 64-bit Windows 10 & Ubuntu 16.04. The benchmark ran for 100000 iterations. The *Native* version is a plain C loop, while the *Effect* version uses effect handlers to implement state. *Operation cost* is the approximate cost of an effect operation relative to a double precision *sqrt* instruction. *Ops/s* are effect operations per second performed without doing any work.

```

void*    top    = get_stack_top();
ptrdiff_t extra = top - cstack_top(cstack);
extra += 128;           // safety margin
byte* space = alloca(extra); // reserve enough stack space
_jumpto(space, cstack, entry); }

```

As before, for clarity we left out error checking and assume the stack grows up and `extra` is always positive. By using `alloca` we reserve enough stack space to restore the `cstack` safely. We pass the `space` parameter and write to it to prevent optimizing compilers to optimize it away as an unused variable.

#### 4.4. Performance

To measure the performance of operations in isolation, we use a simple loop that calls a work function. The native C version is:

```

int counter_native(int i) {
    int sum = 0;
    while (i > 0) { sum += work(i); i--; }
    return sum; }

```

The effectful version mirrors this but uses a *state* effect to implement the counter, performing two effect operations per loop iteration:

```

int counter() {
    int i; int sum = 0;
    while ((i = state_get()) > 0) {
        sum += work(i);
        state_put(i - 1); }
    return sum; }

```

The work function is there to measure the relative performance; the native C loop is almost “free” on a modern processors as it does almost nothing with a loop variable in a register. The work function performs a double precision square root:

```

noinline int work(int i) { return (int)(sqrt((double)i)); }

```

This gives us a baseline to compare how expensive effect operations are compared to the cost of a square root instruction.

Figure 4 shows the results of running 100,000 iteration on a 64-bit platform. The effectful version is around  $300\times$  times slower, and we can execute about 1.3 million of effect operations per second.

The reason for the somewhat slow execution is that we capture many resumptions and fragments, moving a lot of memory and putting pressure on the allocator. There are various ways to optimize this. First of all, we almost never need a *first-class* resumption that can escape the scope of the operation. For example, if we use a `OP_NORESUME` operation that never resumes, we need to capture no state and the operation can be as cheap as a `longjmp`.

Another really important optimization opportunity is *tail resumptions*: these are resumes in a tail-call position in the operation handler. In the benchmark, each `resume` remembers its continuation in a fragment so it can return execution there – just to return directly without doing any more work! This leads to an ever growing handler stack with fragment frames on it. It turns out that in practice, almost *all* operation implementations use `resume` in a tail-call position. And fortunately, we can optimize this case very nicely giving orders of magnitude improvement as discussed in the next section.

## 5. Optimized Tail Resumptions

In this section we expand on the earlier observation that tail resumptions can be implemented more efficiently. We consider in particular a operation handler of the form  $(op(x) \rightarrow resume(e)) \in h$  where  $resume \notin fv(e)$ . In that case:

$$\begin{aligned} & \text{handle}_h \cdot X_{op} \cdot op(v) \longrightarrow \\ & resume(e)[x \mapsto v, resume \mapsto \lambda y. \text{handle}_h \cdot X_{op} \cdot y] \longrightarrow \{ resume \notin e \} \\ & (\lambda y. \text{handle}_h \cdot X_{op} \cdot y)(e[x \mapsto v]) \longrightarrow^* \{ e[x \mapsto v] \longrightarrow^* v' \} \\ & (\lambda y. \text{handle}_h \cdot X_{op} \cdot y)(v') \longrightarrow \\ & \text{handle}_h \cdot X_{op} \cdot v' \end{aligned}$$

Since we end up with the same stack,  $\text{handle}_h \cdot X_{op}$ , we do not need to capture and restore the context  $\text{handle}_{op} \cdot X_{op}$  at all but can directly evaluate the operation expression  $e$  as if it was a regular function call! However, if we leave the stack in place, we need to take special precautions to ensure that any operations yielded in the evaluation of  $e[x \mapsto v]$  are not handled by any handler in  $\text{handle}_h \cdot X_{op}$ .

### 5.1. A Tail Optimized Semantics

In order to evaluate such tail resumptive expressions under the stack  $\text{handle}_{op} \cdot X_{op}$ , but prevent yielded operations from being handled by handlers in that stack, we introduce a new *yield* frame  $\text{yield}_{op}(e)$ . Intuitively, a piece of stack of the form  $\text{handle}_{op} \cdot X_{op} \cdot \text{yield}_{op}$  can be ignored – the  $\text{yield}_{op}$  specifies that any handlers up to  $h$  (where  $op \in h$ ) should be skipped when looking for an operation handler.

**Evaluation contexts:**

$$\begin{aligned}
F & ::= [] \mid F(e) \mid v(F) \mid op(F) \mid \text{val } x = F; e \mid \text{handle}_h(F) \mid \text{yield}_{op}(F) \\
Y_{op} & ::= [] \mid Y_{op}(e) \mid v(Y_{op}) \mid op(Y_{op}) \mid \text{val } x = Y_{op}; e \\
& \quad \mid \text{handle}_h(Y_{op}) && \text{if } op \notin h \\
& \quad \mid \text{handle}_h(Y_{op'}[\text{yield}_{op'}(Y_{op})]) && \text{if } op' \in h
\end{aligned}$$

**New Reduction rules:**

$$\begin{aligned}
(\text{handle}) \quad & \text{handle}_h \cdot Y_{op} \cdot op(v) \xrightarrow{-} e[x \mapsto v, \text{resume} \mapsto \lambda y. \text{handle}_h \cdot Y_{op} \cdot y] \\
& \quad \text{with } (op(x) \rightarrow e) \in h \\
(\text{thandle}) \quad & \text{handle}_h \cdot Y_{op} \cdot op(v) \xrightarrow{-} \text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op} \cdot \text{resume}(e)[x \mapsto v] \\
& \quad \text{with } (op(x) \rightarrow \text{resume}(e)) \in h \\
& \quad \quad \text{resume} \notin \text{fv}(e) \\
(\text{tail}) \quad & \text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op} \cdot \text{resume}(v) \xrightarrow{-} \text{handle}_h \cdot Y_{op} \cdot v \quad \text{with } (op \in h)
\end{aligned}$$

**Figure 5.** Optimized reduction rules with yield frames. Rules  $(\delta)$ ,  $(\beta)$ ,  $(let)$ , and  $(return)$  are the same as in Figure 2.

This is made formal in Figure 5. We have a new evaluation context  $F$  that evaluates under the new yield expression, and we define a new handler context  $Y_{op}$  that is like  $X_{op}$  but now also skips over parts of the handler stack that are skipped by yield frames, i.e. it finds the innermost handler that is not skipped.

The reduction rules in Figure 5 use a new reduction arrow  $\xrightarrow{-}$  to signify that this reduction can contain  $\text{yield}_{op}$  frames. The first five rules are equivalent to the usual rules except that the  $(handle)$  rule uses the  $Y_{op}$  context now instead of  $X_{op}$  to correctly select the innermost handler for  $op$  skipping any handlers that are part of a  $\text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op}$  (with  $op \in h$ ) sequence.

The essence of our optimization is in the  $(thandle)$  rule which applies when the  $\text{resume}$  operation is only used in the tail-position. In this case we can (1) keep the stack *as is*, just pushing a  $\text{yield}_{op}$  frame, and (2) we can skip capturing a resumption and binding  $\text{resume}$  since  $\text{resume} \notin \text{fv}(e)$ . The “unbound” tail  $\text{resume}$  is now handled explicitly in the  $(tail)$  rule: it can just pop the  $\text{yield}_{op}$  frame and continue evaluation under the original stack.

**5.1.1. Soundness** We would like to preserve the original semantics with our new optimized rules: if we reduce using our new  $\xrightarrow{-}$  reduction, we should get the same result if we reduce using the original reduction rule  $\longrightarrow$ . To state this formally, we define a *ignore* function on expression,  $\bar{e}$ , and contexts  $\bar{F}$  and  $\bar{Y}$ . This function removes any  $\text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op}$  sub expressions where  $op \in h$ , effectively turning any of our extended expressions into an original one, and taking  $F$  to  $E$ , and  $Y_{op}$  to  $X_{op}$ . Using this function, we can define soundness as:

**Theorem 1.** (*Soundness*)

If  $F \cdot e \xrightarrow{-} F \cdot e'$  then  $\bar{F} \cdot \bar{e} \longrightarrow \bar{F} \cdot \bar{e}'$ .

Compiler	Native (s)	Effects (s)	Slowdown	Operation Cost	Ops/s
<code>msvc 2015 /02</code>	0.059	0.197	3.3×	1.15 · <code>sqrt</code>	134 · 10 <sup>6</sup>
<code>clang 3.8.0 -03</code>	0.059	0.153	2.6×	0.79 · <code>sqrt</code>	150 · 10 <sup>6</sup>
<code>gcc 5.4.0 -03</code>	0.059	0.167	2.8×	0.90 · <code>sqrt</code>	141 · 10 <sup>6</sup>

**Figure 6.** Performance using tail optimized resumptions. Same benchmark as in Figure 4 but with  $10 \cdot 10^6$  iterations.

The proof is given in Appendix A.3.

## 5.2. Implementing Tail Optimized Operations

The implementation of tail resumptions only requires a modification to yielding operations:

```

value yield(const optag* optag, value arg) {
  const operation* op;
  handler* h = hstack_find(optag,&op);
  if (op->opkind==OP_NORESUME) yield_to_handler(h,op,arg,NULL);
  else if (op->opkind==OP_TAIL) {
    hstack_push_yield(h);           // push a yield frame
    value res = op->opfun(NULL,op,arg); // call operation directly
    hstack_pop_yield();           // pop the yield again
    return res;
  }
  else return capture_resume_yield(h,op,arg); }

```

We simply add a new operation kind `OP_TAIL` that signifies that the operation is a tail resumption, i.e. the operation promises to end in a tail call to `tail_resume`. We then push a yield frame, and directly call the operation. It will return with the final result (as a `tail_resume`) and we can pop the yield frame and continue. We completely avoid capturing the stack and allocating memory. The `tail_resume` is now just an identity function:

```

value tail_resume(const resume* r, value arg) { return arg; }

```

In the real implementation, we do more error checking and also allow `OP_TAIL` operations to not resume at all (and behave like and `OP_NORESUME`). We also need to adjust the `hstack_find` and `hstack_pop_upto` functions to skip over handlers as designated by the yield frames.

## 5.3. Performance, again

With our new optimized implementation of tail-call resumptions, let’s repeat our earlier *counter* benchmark of Section 4.4. Figure 6 shows the new results where we see three orders of magnitude improvements and we can perform up to 150 million (!) tail resumming operations per second with the `clang` compiler. That is quite good as that is only about 18 instruction cycles on our processor running at 2.6GHz.

## 6. What doesn't work?

Libraries for co-routines and threading in C are notorious for breaking common C idioms. We believe that the structured and scoped form of algebraic effects prevents many potential issues. Nevertheless, with stacks being copied, we make certain assumptions about the runtime:

- We assume that the C stack is contiguous and does not move. This is the case for all major platforms. For platforms that support “linked” stacks, we could even optimize our library more since we can then capture a piece of stack by reference instead of copying! The “not moving” assumption though means we cannot resume a resumption on another thread than where it was captured. Otherwise any C idioms work as expected and arguments can be passed by stack reference. Except..
- When calling `yield` and `(tail_)resume`, we cannot pass parameters by stack reference but must allocate them in the heap instead. We feel this is a reasonable restriction since it only applies to new code specifically written with algebraic effects. When running in debug mode the library checks for this.
- For resumes in the scope of a handler, we always restore the stack and fragments at the exact same location as the handler stack base. This way the stack is always valid and can be unwound by other tools like debuggers. This is not always the case for a first-class resumption that escapes the handler scope – in that case a resumption stack may restore into an arbitrary C stack, and the new C stack is (temporarily) only valid above the resume base. We have not seen any problems with this though in practice with either `gdb` or Microsoft’s debugger and profiler. Of course, in practice almost all effects use either tail resumptions or resumptions that stay in the scope of the handler. The only exception is really the `async` effect but that in that case we happen to still resume at the right spot since we always resume from the same event loop.

## 7. Related Work

This is the first library to implement algebraic effects and handlers for the C language, but many similar techniques have been used to implement co-routines [21,1.4.2] and cooperative threading [1, 4, 6, 7, 11]. In particular, stack copying/switching, and judicious use of `longjmp` and `setjmp` [14]. Many of these libraries have various drawbacks though and restrict various C idioms. For example, most co-routines libraries require a fixed C stack [9, 15, 24, 38], move stack locations on resumptions [30], or restrict to one-shot continuations [8].

We believe that is mostly a reflection that general co-routines and first-class continuations (`call/cc`) are *too* general – the simple typing and added structure of algebraic effects make them more “safe” by construction. As Andrej Bauer, co-creator of the Eff [3] language puts it as: *effects+handlers* are to *delimited continuations* as what *while* is to *goto* [20].

Recently, there are various implementations of algebraic effects, either embedded in Haskell [20, 41], or built into a language, like Eff [3], Links [18], Frank [29], and Koka [25]. Most closely related to this article is Multi-core OCaml [12, 13] which implements algebraic effect natively in the OCaml runtime system. The prevent copying the stack, it uses linked stacks in combination with explicit copying when resuming more than once.

Multi-core OCaml supports *default* handlers [12]: these are handlers defined at the outermost level that have an implicit `resume` over their result. These are very efficient and implemented just as a function call. Indeed, these are a special case of the tail-resumptive optimization shown in Section 5.1: the implicit `resume` guarantees that the resumption is in a tail-call position, while the outermost level ensures that the handler stack is always empty and thus does not need a `yieldop` frame specifically but can use a simple flag to prevent handling of other operations.

## 8. Conclusion

We are excited by this library to provide powerful new control abstractions in C. For the near future we plan to integrate this into a compiler backend for the P language [10], and to create a nice wrapper for `libuv`. As part of the P language backend, we are also working on a C++ interface to our library which requires special care to run destructors correctly.

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## A. Appendix

### A.1. Implementing Setjmp and Longjmp

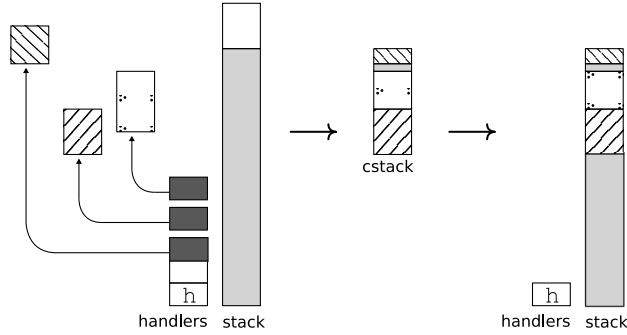
Here is some example of the assembly code for `setjmp` and `longjmp` for 32-bit x86 with the `cdecl` calling convention is [16]. The `setjmp` function just moves the registers into the `jmp_buf` structure:

```
; called with:
; [esp + 4]: _jmp_buf address (cleaned up by caller)
; [esp]    : return address
mov     ecx, [esp+4]    ; _jmp_buf to ecx
mov     [ecx+ 0], ebp  ; save registers
mov     [ecx+ 4], ebx
mov     [ecx+ 8], edi
mov     [ecx+12], esi
lea    eax, [esp+4]    ; save esp (minus return address)
mov     [ecx+16], eax
mov     eax, [esp]     ; save the return address (eip)
mov     [ecx+20], eax
stmxcsr [ecx+24]      ; save sse control word
fnstcw [ecx+28]      ; save fpu control word
xor     eax, eax      ; return zero
ret
```

Note that we only need to save the *callee save* registers; all other temporary registers will have already been spilled by compiler when calling the `setjmp` function.

The `longjmp` function reloads the saved registers and in the end jumps directly to the stored instruction pointer (which was the return address of `setjmp`):

```
; called with:
; [esp+8]: argument
; [esp+4]: jmp_buf address
; [esp]  : return address (unused!)
_lh_longjmp PROC
    mov     eax, [esp+8]    ; set eax to the return value (arg)
    mov     ecx, [esp+4]    ; ecx to jmp_buf
    mov     ebp, [ecx+ 0]   ; restore registers
    mov     ebx, [ecx+ 4]
    mov     edi, [ecx+ 8]
    mov     esi, [ecx+12]
    ldmxcsr [ecx+24]      ; load sse control word
    fnclex                ; clear fpu exception flags
    fldcw  [ecx+28]      ; restore fpu control word
    test   eax, eax      ; longjmp should never return 0
    jnz    ok
    inc    eax
ok:
    mov     esp, [ecx+16]  ; restore esp
    jmp    dword ptr [ecx+20] ; and jump to the eip
```



**Figure 7.** Unwinding a stack with fragments

## A.2. Unwinding through fragments

This section shows in more detail how to unwind the handler stack in the presence of fragments (as discussed in Section 4.3.1). The `hstack_pop_upto` function without fragments can just pop handlers, skipping over `yield` segments, until it reaches the handler `h`. In the presence of fragment handlers though, it also needs to restore the C stack as it was when the handler `h` was on top of the stack.

Figure 7 shows this in more detail. When unwinding to handler `h`, there are three fragment handlers on the stack. In the figure, the top of the gray part of the stack shows the `stackbase` for `h`. When unwinding the handler stack, a new composite fragment is created that applies each fragment on the handler stack in order. After unwinding, the C stack can be properly restored to its original state.

## A.3. Proof of Soundness

Here we prove soundness of the tail resumptive optimization discussed in Section 5. Useful properties of the `ignore` function are  $\bar{v} = v$ , and  $\bar{F} \cdot \text{handle}_h \cdot \text{Y}_{op} \cdot \text{yield}_{op}$  (with  $op \in h$ ) equals  $\bar{F}$ .

**Proof.** (Of Theorem 1, Section 5.1.1) We show this by case analysis on reduction rules. The first five rules are equivalent to the original rules. For (`yhandle`) we

have:

$$\begin{aligned}
& \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot op(v)}}}}} \\
&= \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot op(v)}}}}} \\
&= \overline{\overline{\overline{\overline{\text{handle}_{\bar{h}} \cdot \bar{Y}_{op} \cdot op(v)}}}}} \\
&\longrightarrow \\
&\overline{\overline{\overline{\overline{e[x \mapsto v, \text{resume} \mapsto \lambda y. \text{handle}_{\bar{h}} \cdot \bar{Y}_{op} \cdot y]}}}}} \\
&= \{ \text{resume} \notin \text{fv}(e) \} \\
&\overline{\overline{\overline{\overline{e[x \mapsto v]}}}}} \\
&= \{ op \in h \} \\
&\overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op} \cdot e[x \mapsto v]}}}}} \\
&= \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op} \cdot e[x \mapsto v]}}}}}
\end{aligned}$$

In the (*tail*) rule, we know by construction that in the original reduction rules, *resume* would have been bound as a regular  $\text{resume} \mapsto \lambda y. \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot y}}}}}$ :

$$\begin{aligned}
& \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op} \cdot \text{resume}(v)}}}}} \\
&= \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot \text{yield}_{op} \cdot (\lambda y. \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot y}}}})}(v)}}}}} \\
&= \{ op \in h \} \\
&\overline{\overline{\overline{\overline{(\lambda y. \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot y}}}})}(v)}}}}} \\
&\longrightarrow \\
&\overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot v}}}}} \\
&= \overline{\overline{\overline{\overline{\text{handle}_h \cdot Y_{op} \cdot v}}}}}
\end{aligned}$$

□