

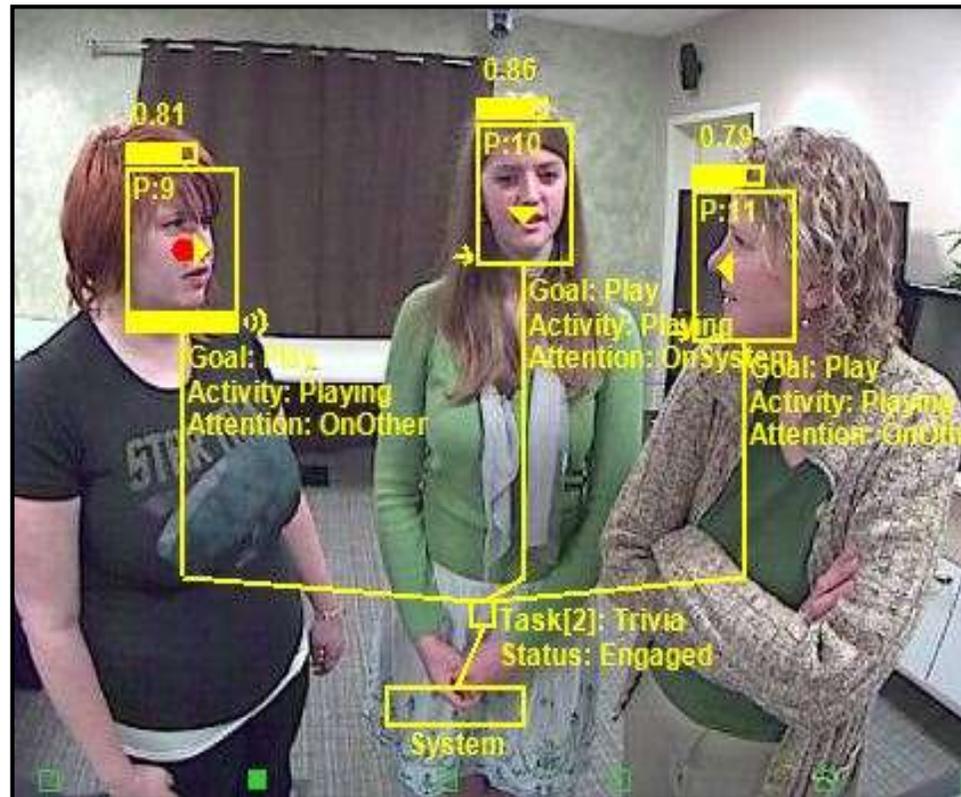
Platform for Situated Intelligence enabling interactive, real-time AI



Sean Andrist, Dan Bohus, John Elliott, Ashley Feniello, Don Gillett, Eric Horvitz, Mihai Jalobeanu, Anne Loomis
Thompson, Nick Saw
MSR AI, Redmond

Physically Situated Language Interaction

enable computers to perceive and reason about their surroundings and engage in language interaction in physically situated settings



Physically Situated Language Interaction



Human robot interaction

Physically Situated Language Interaction



Social mobile robots

Integrative AI

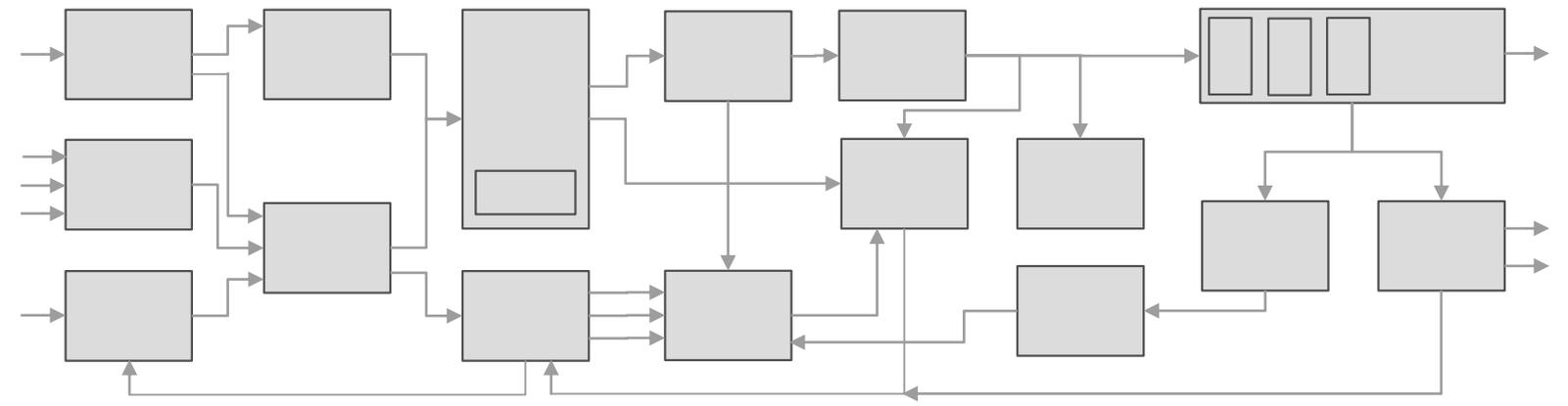


Integrative AI development challenges

Complexity

Missing primitives

Debugging

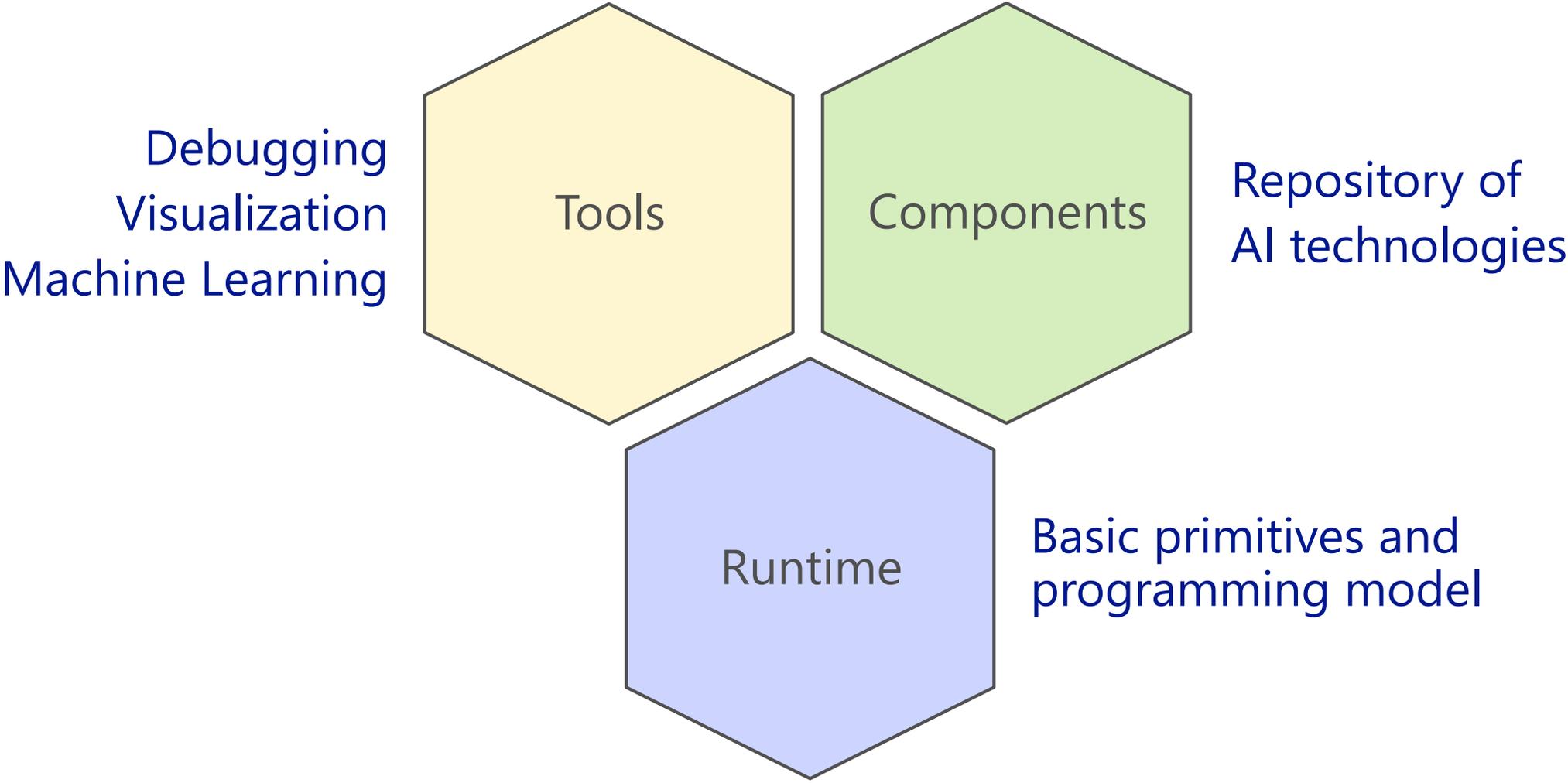


Microphone array capture
Sound source localization
Speech recognition
Language understanding
Infrared proximity sensors
Badge sensors
Face detection and tracking
Head-pose tracking

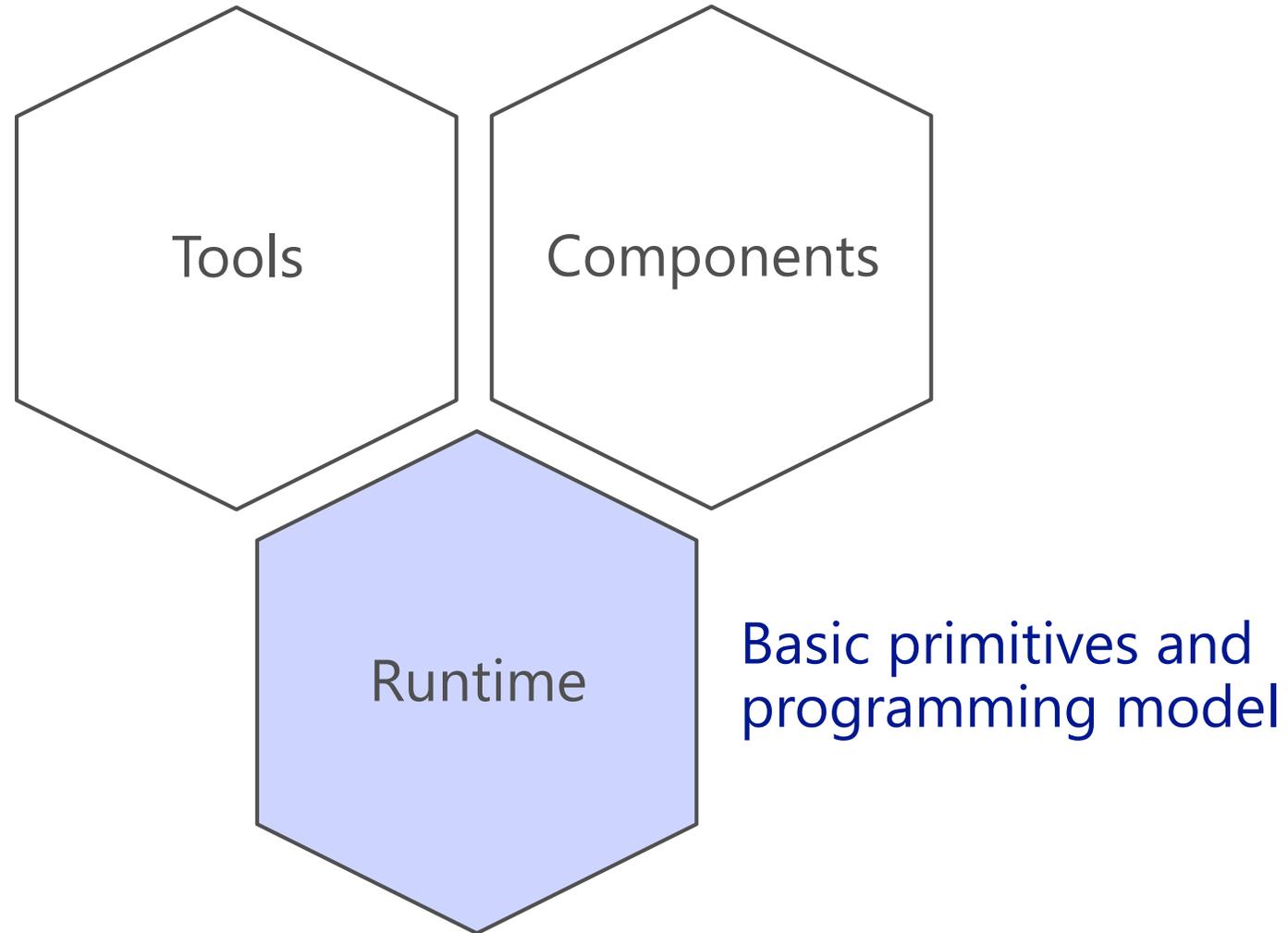
Facial feature tracking
Face identity recognition
Gender detection
Attention models
Engagement models
Turn-taking models
Behavioral control

Dialog management
Natural language generation
Speech synthesis
Avatar synthesis
Robot motion control
Floor-plan models
User models

Platform for Situated Intelligence

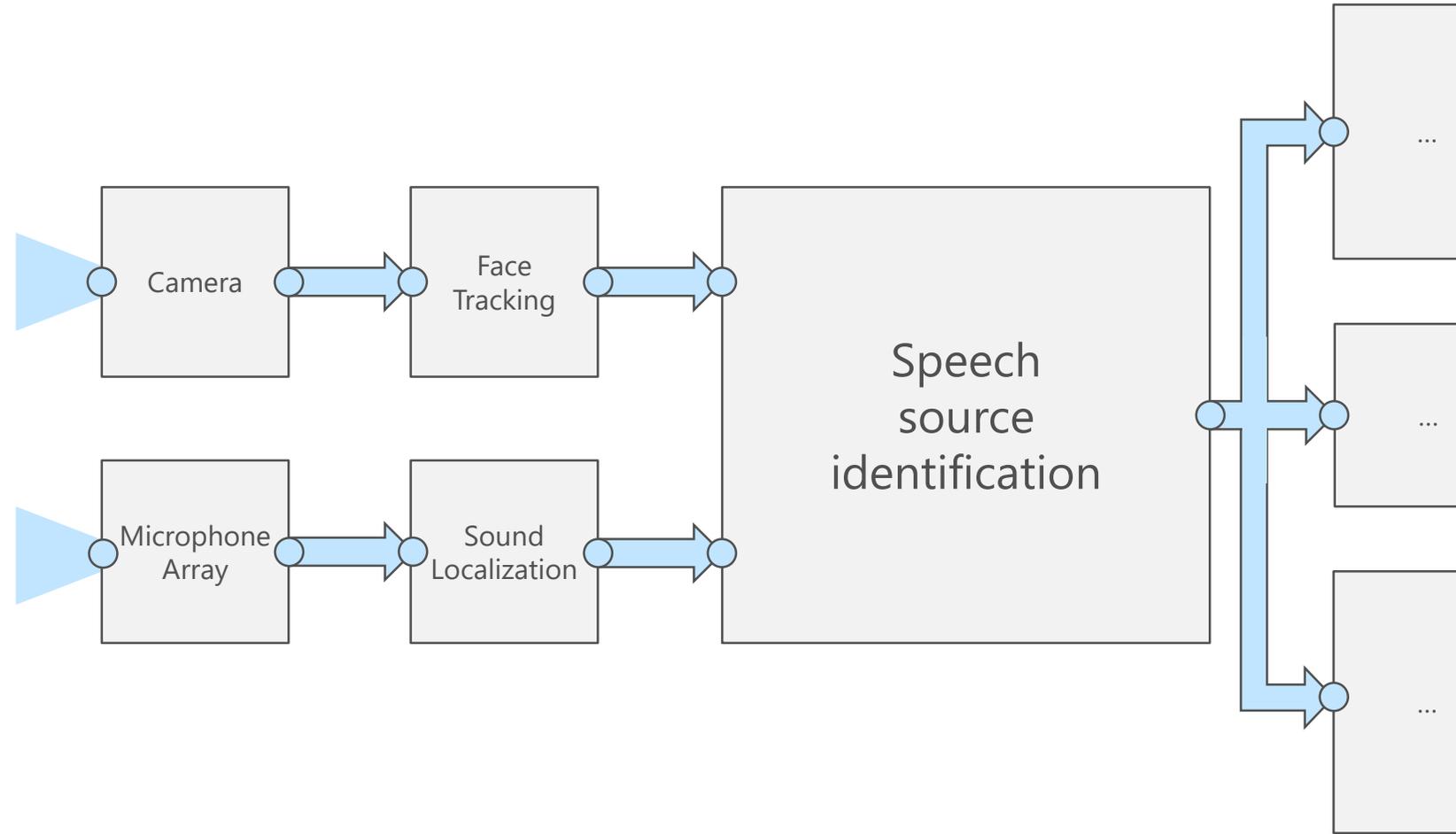
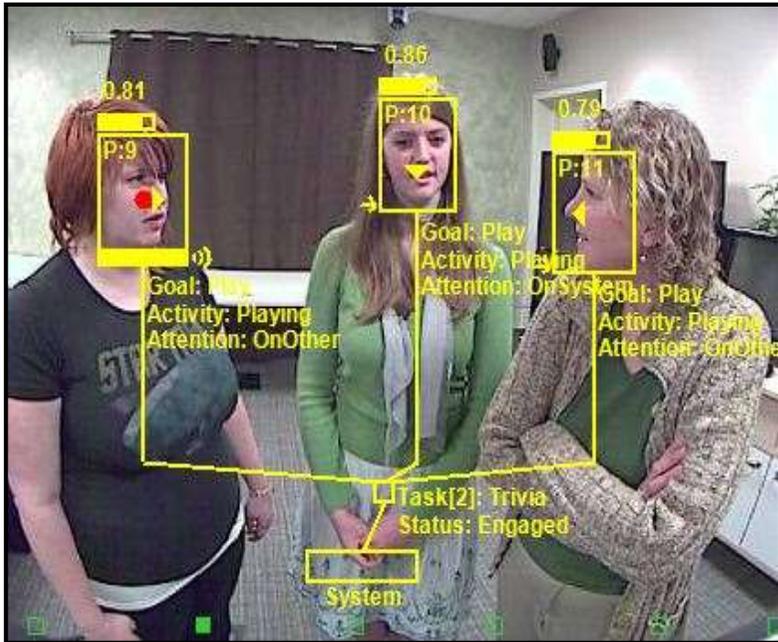


Platform for Situated Intelligence



Runtime: parallel coordinated computation

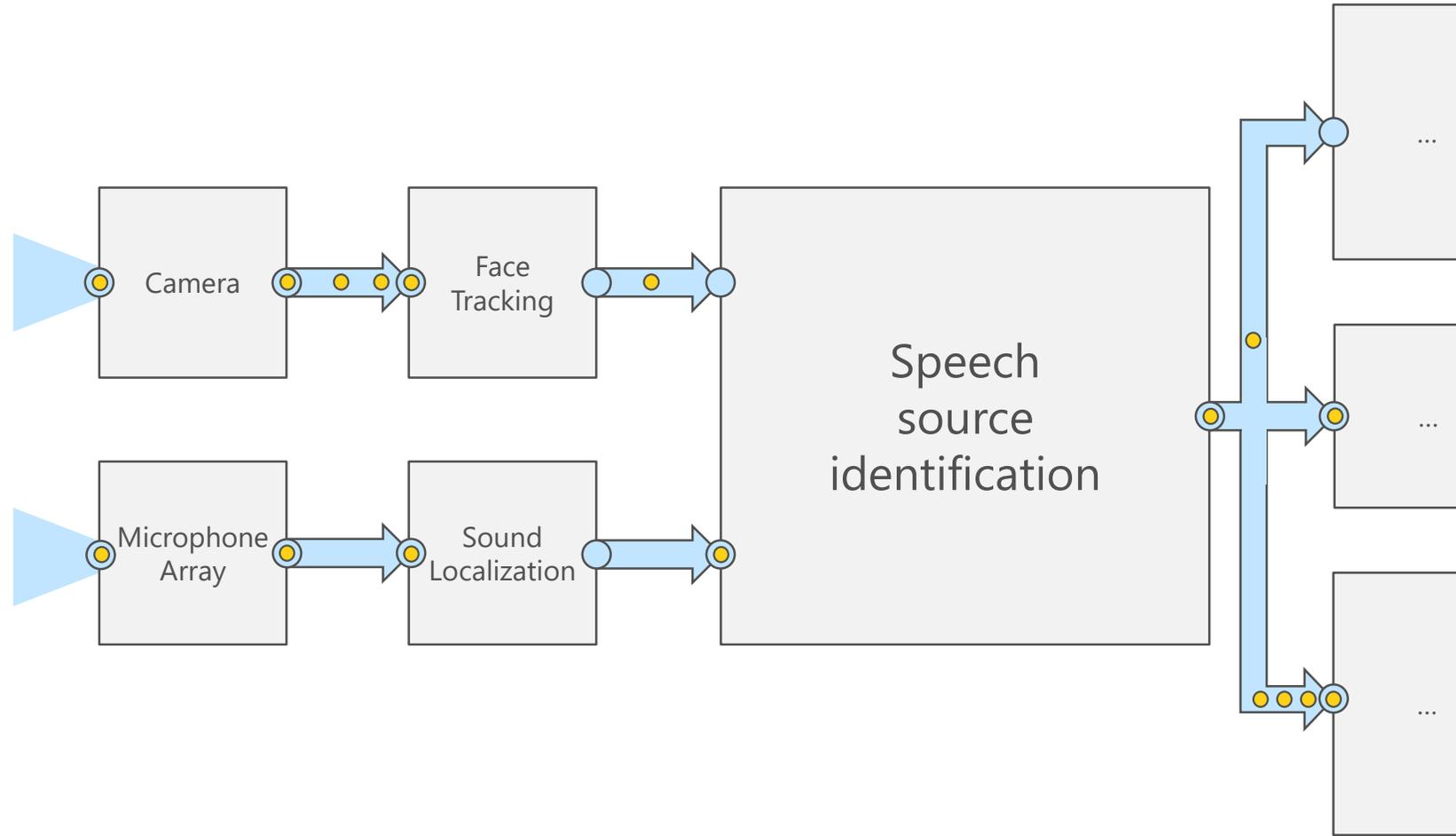
Connect components



Runtime: parallel coordinated computation

Connect components

Streams & messages

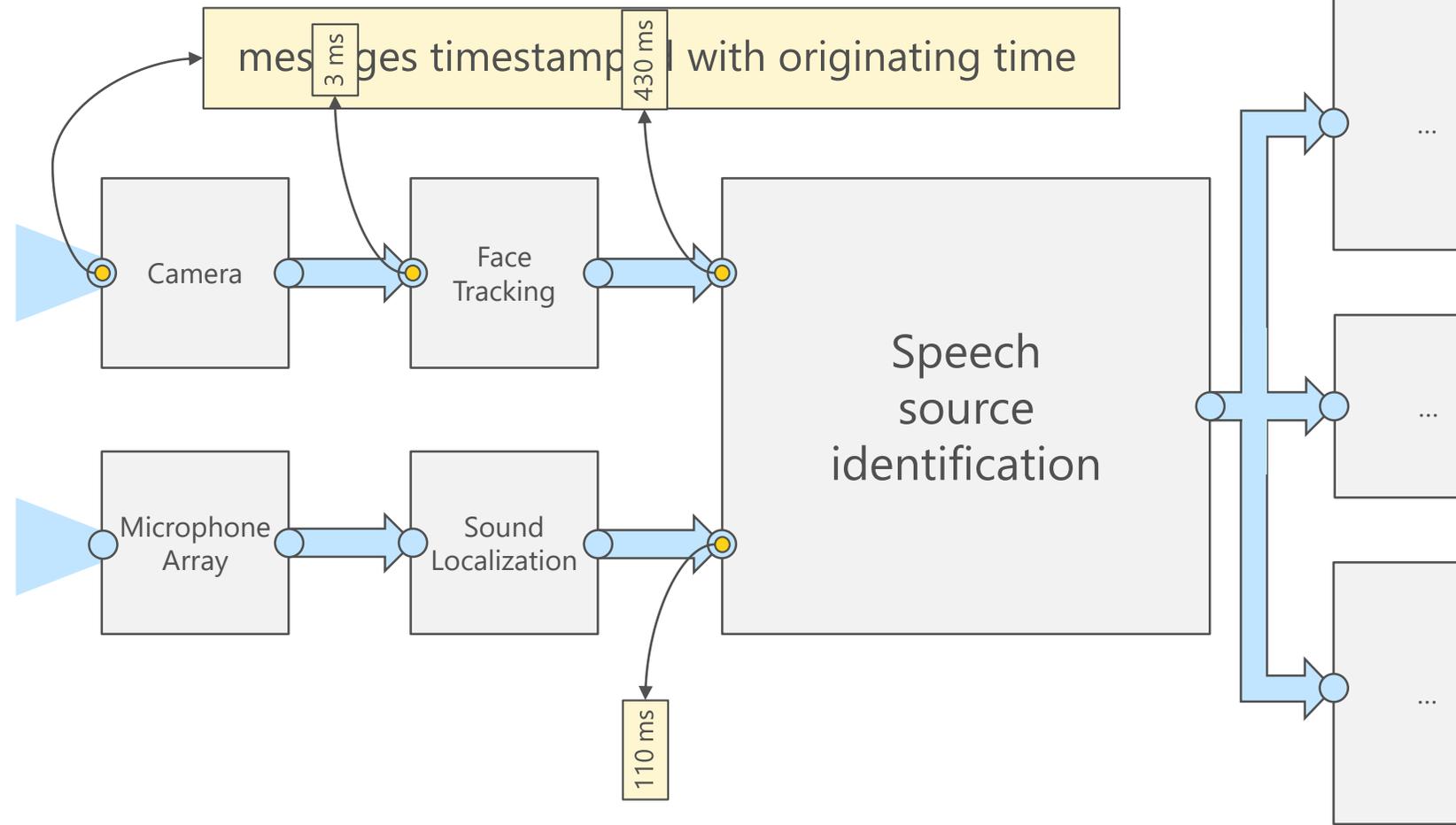


Runtime: parallel coordinated computation

Connect components

Streams & messages

Synchronization



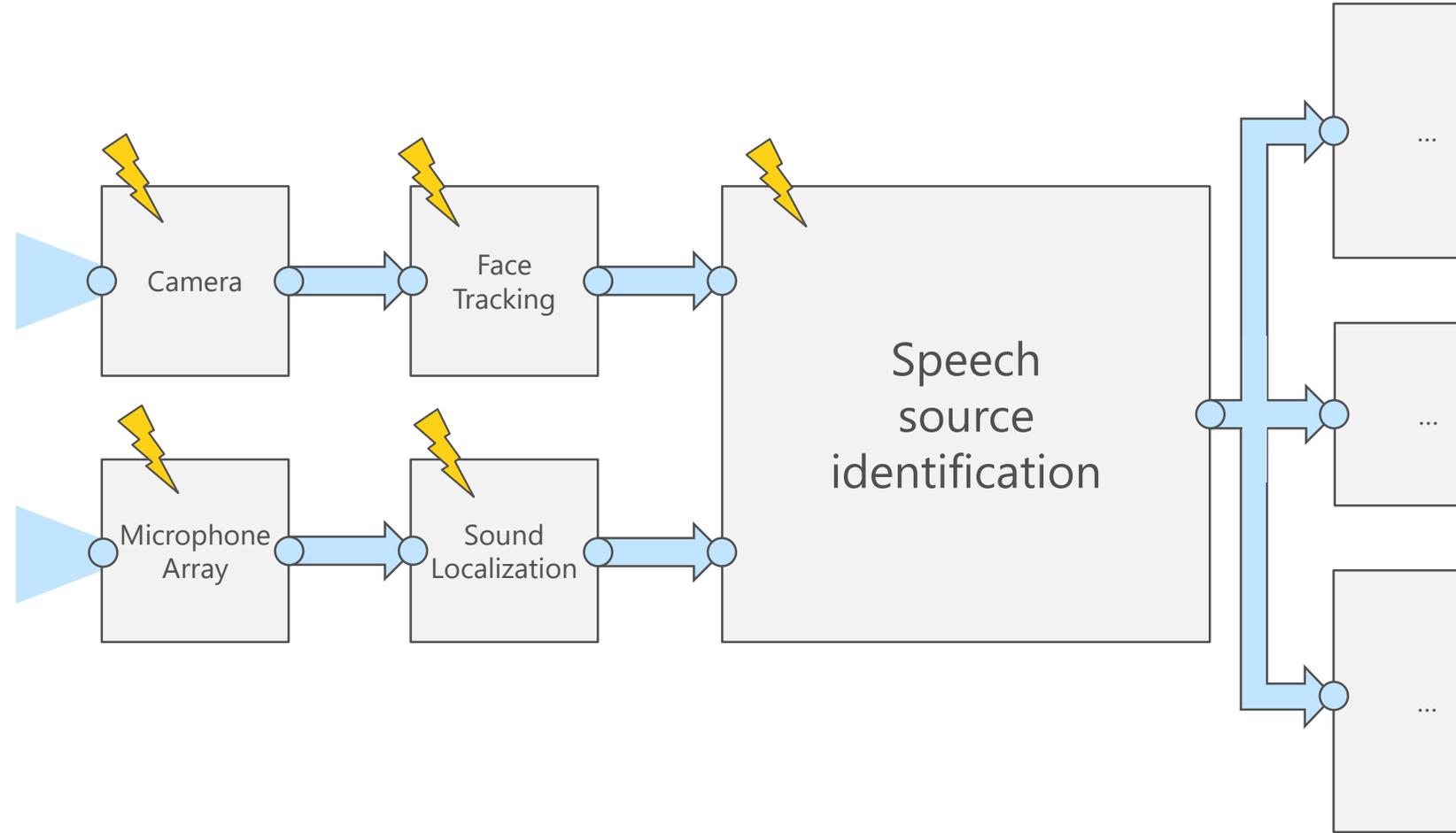
Runtime: parallel coordinated computation

Connect components

Streams & messages

Synchronization

Scheduling



Runtime: parallel coordinated computation

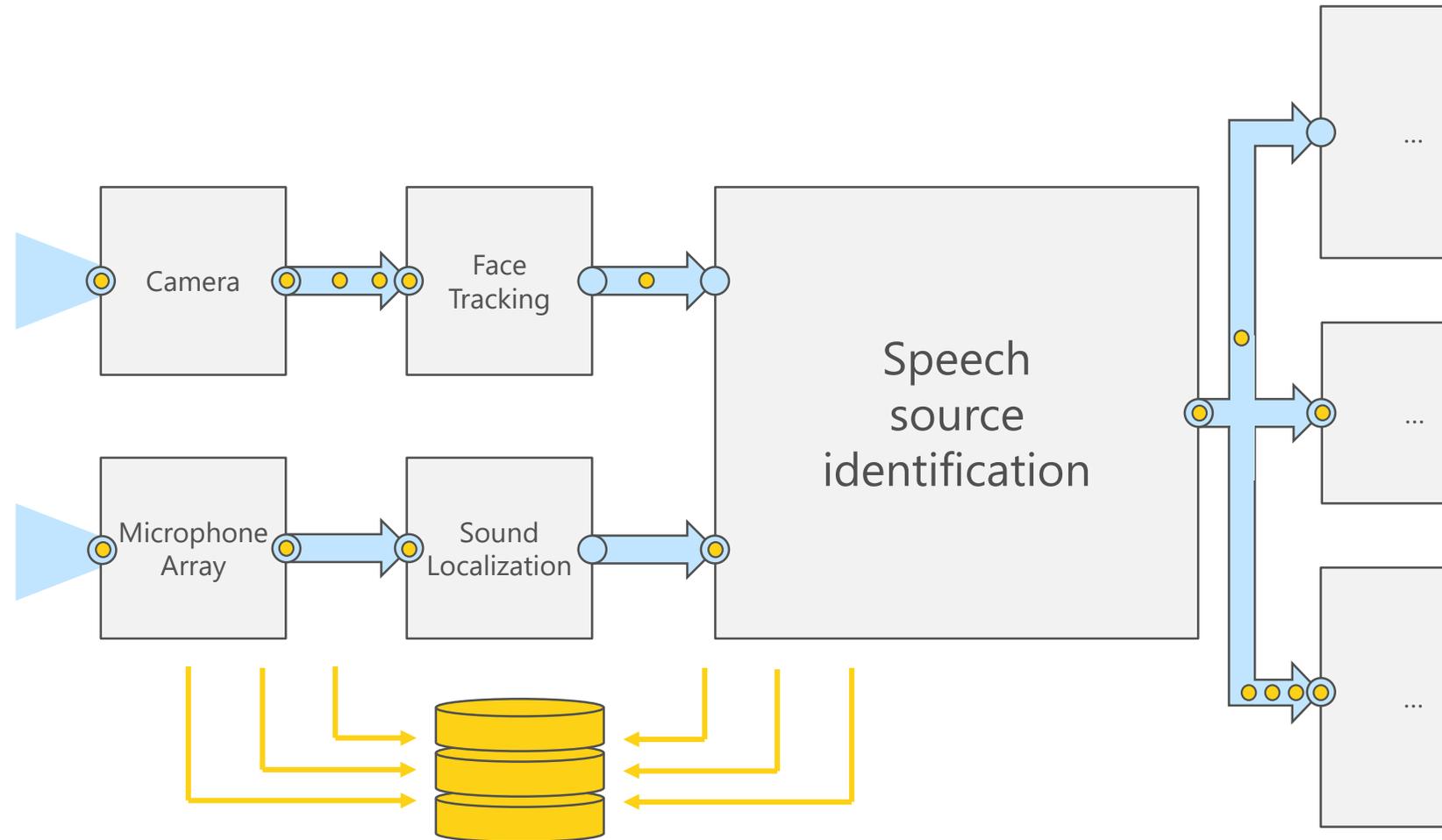
Connect components

Streams & messages

Synchronization

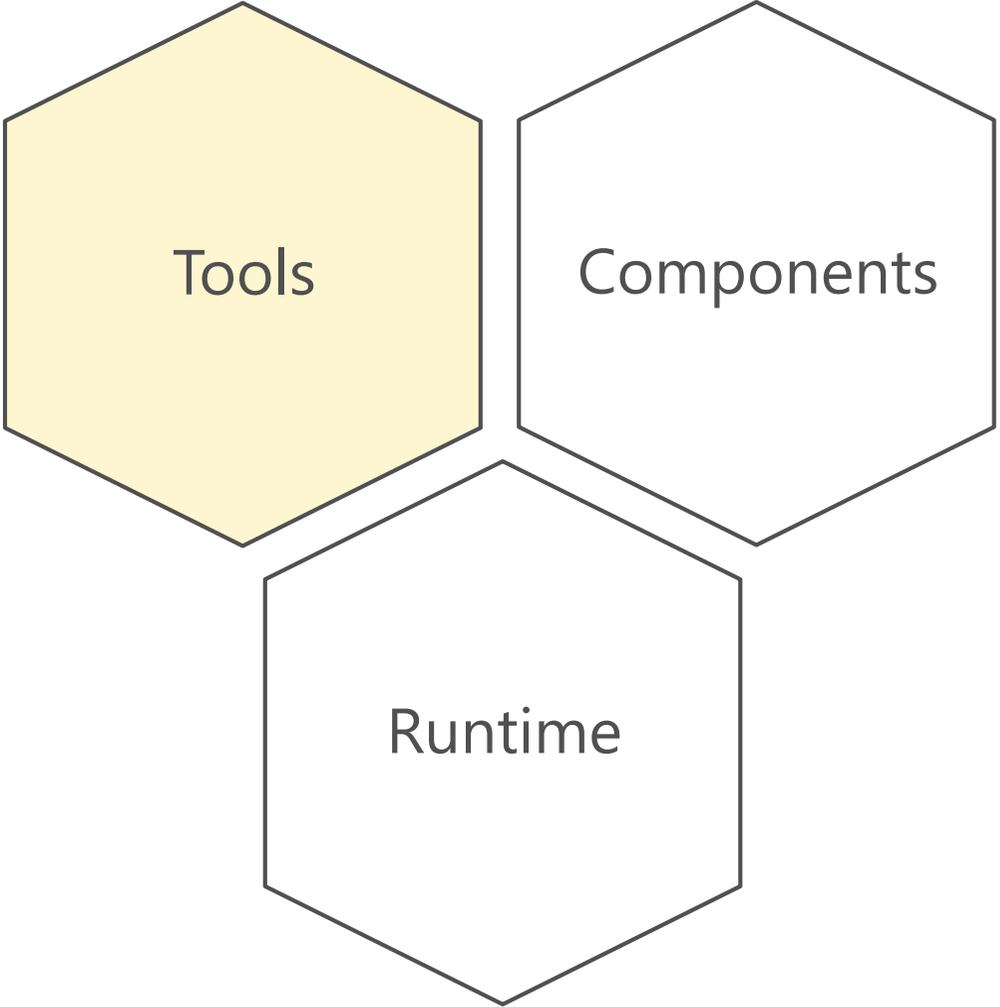
Scheduling

Persistence



Platform for Situated Intelligence

Debugging
Visualization
Machine Learning



Tools

Visualization

Composited visualizations

Navigation

Live mode

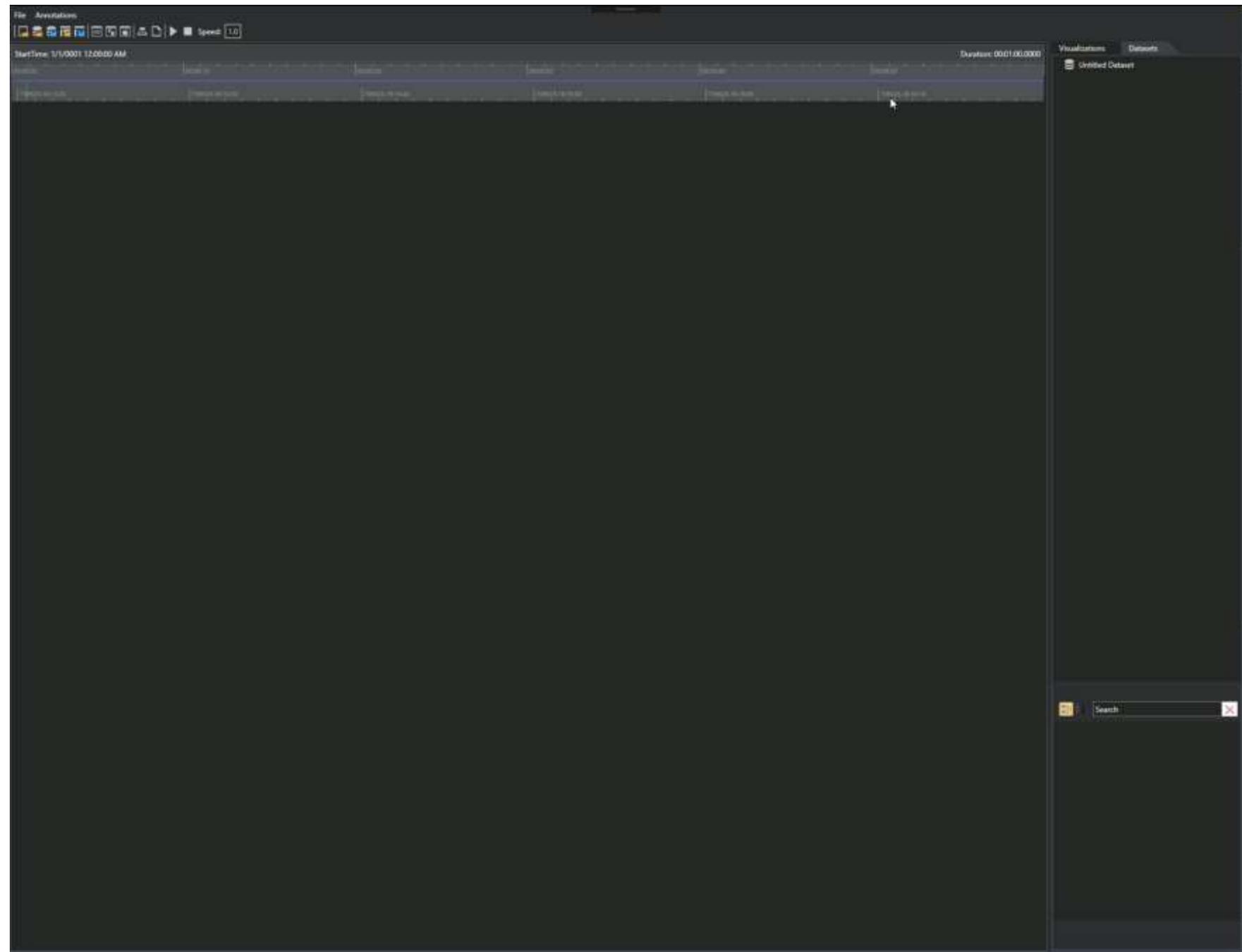
Tools

Visualization

Composited visualizations

Navigation

Live mode



Tools

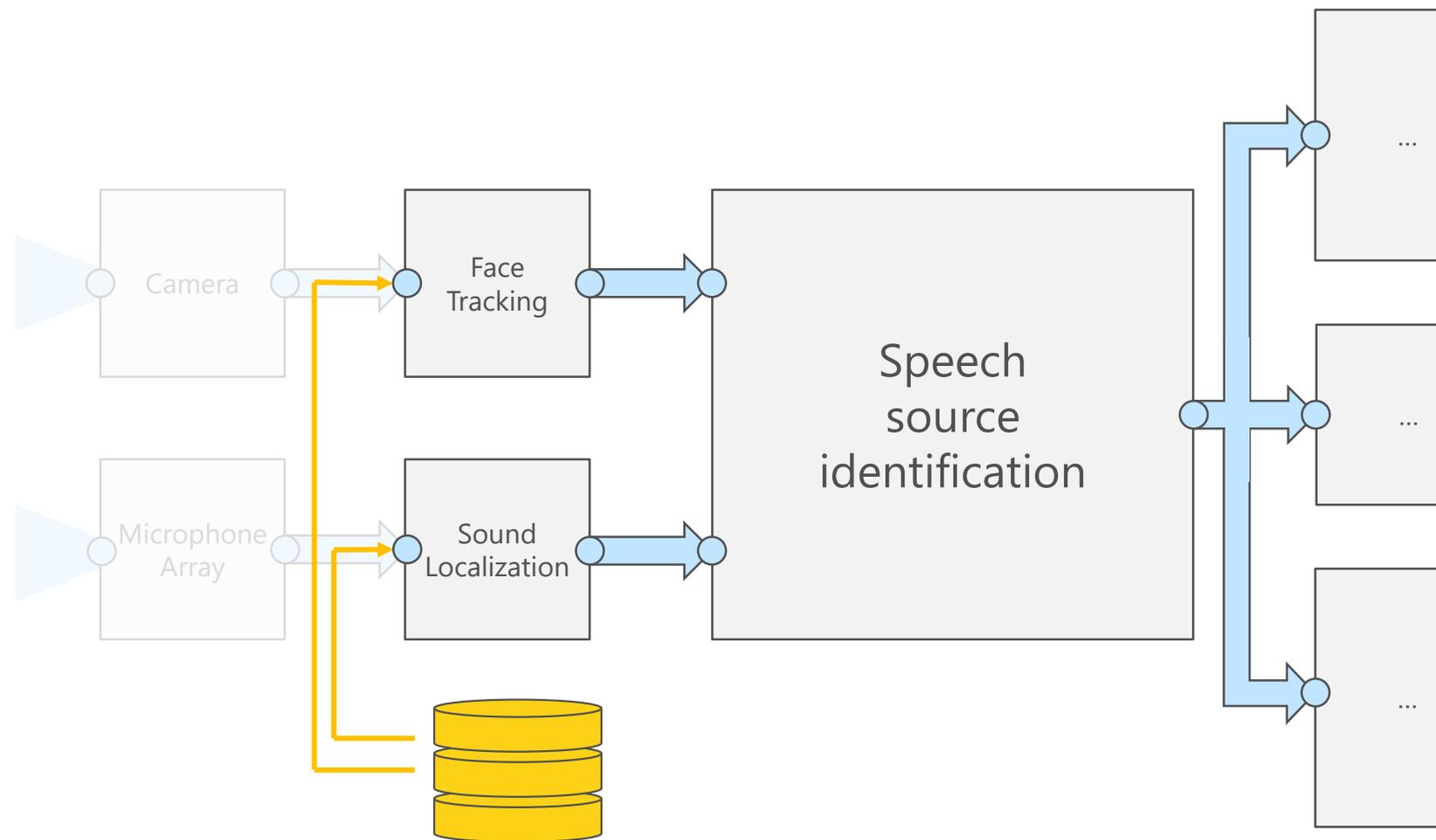
Visualization

Composited visualizations

Navigation

Live mode

Replay & Experiment



Tools

Visualization

Composited visualizations

Navigation

Live mode

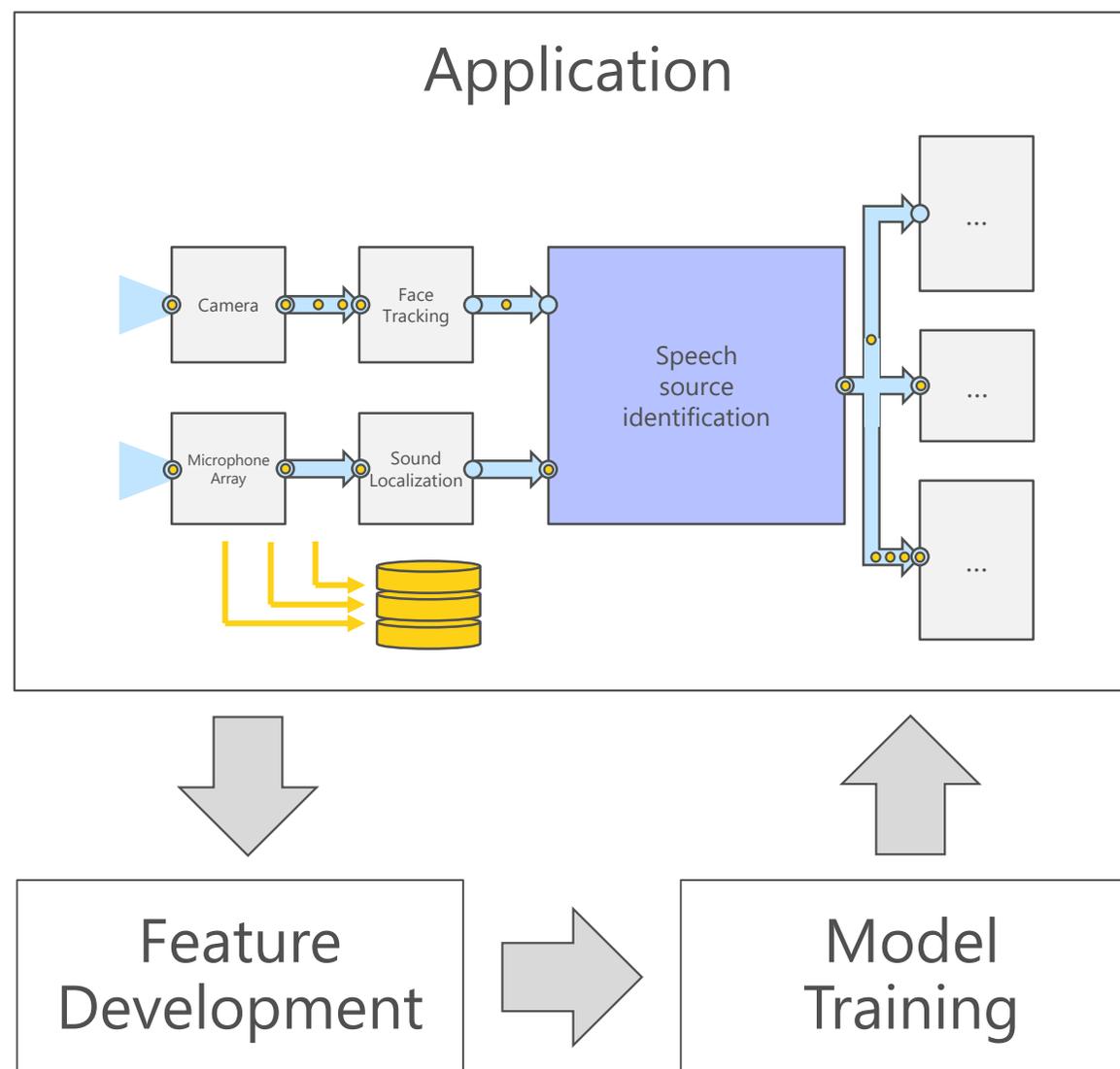
Replay & Experiment

Machine learning

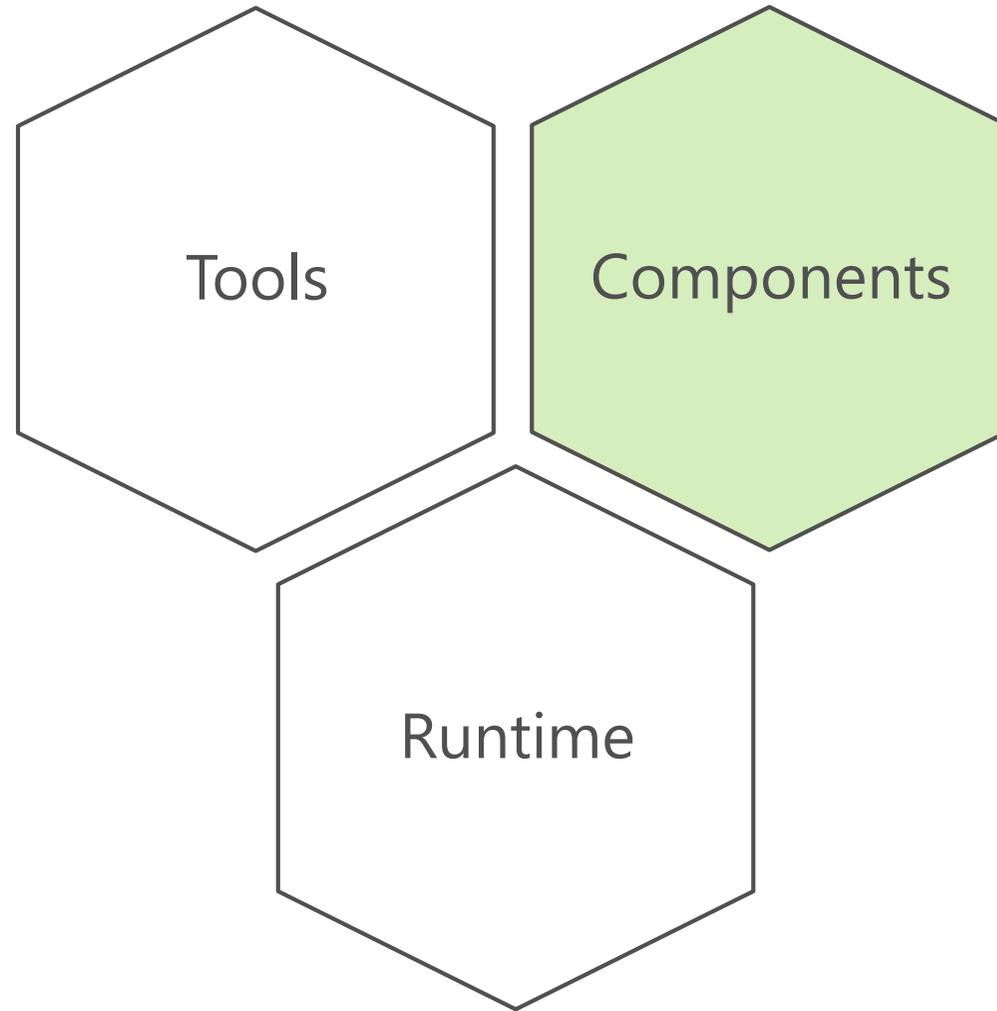
Annotation

Feature construction

End-to-end support



Platform for Situated Intelligence



Repository of
AI technologies

Store for real-time AI components

▶ Wrap existing technologies

▼ Sensors

Cameras: USB, PointGrey, Kinect
Microphones: USB, Array
...

▼ Vision

Imaging, transforms, optical flow
Foreground models
Blob tracking
...

▼ Speech

Voice activity detection
Speech recognition
Natural language processing
Natural language generation
Speech synthesis
...

...

▼ Human perception

Face tracking & identity
Gaze tracking
Body tracking
Affect recognition
Attention tracking
...

▼ Interaction

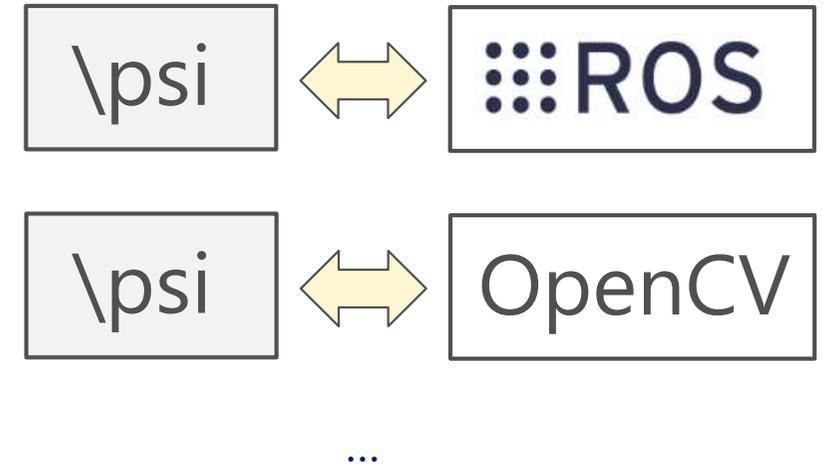
Engagement models
Turn-taking models
FSM-based controller
...

▼ Output

Speech synthesis
Avatar rendering
...

...

▶ Bridging & Interop



Situated Interaction Toolkit

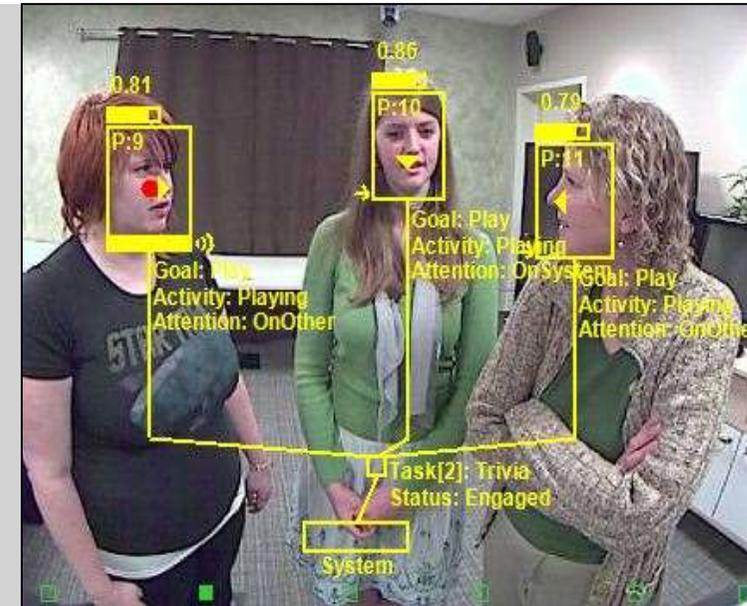
Programming against the “physics” of human activities

identity, attention and interruptability

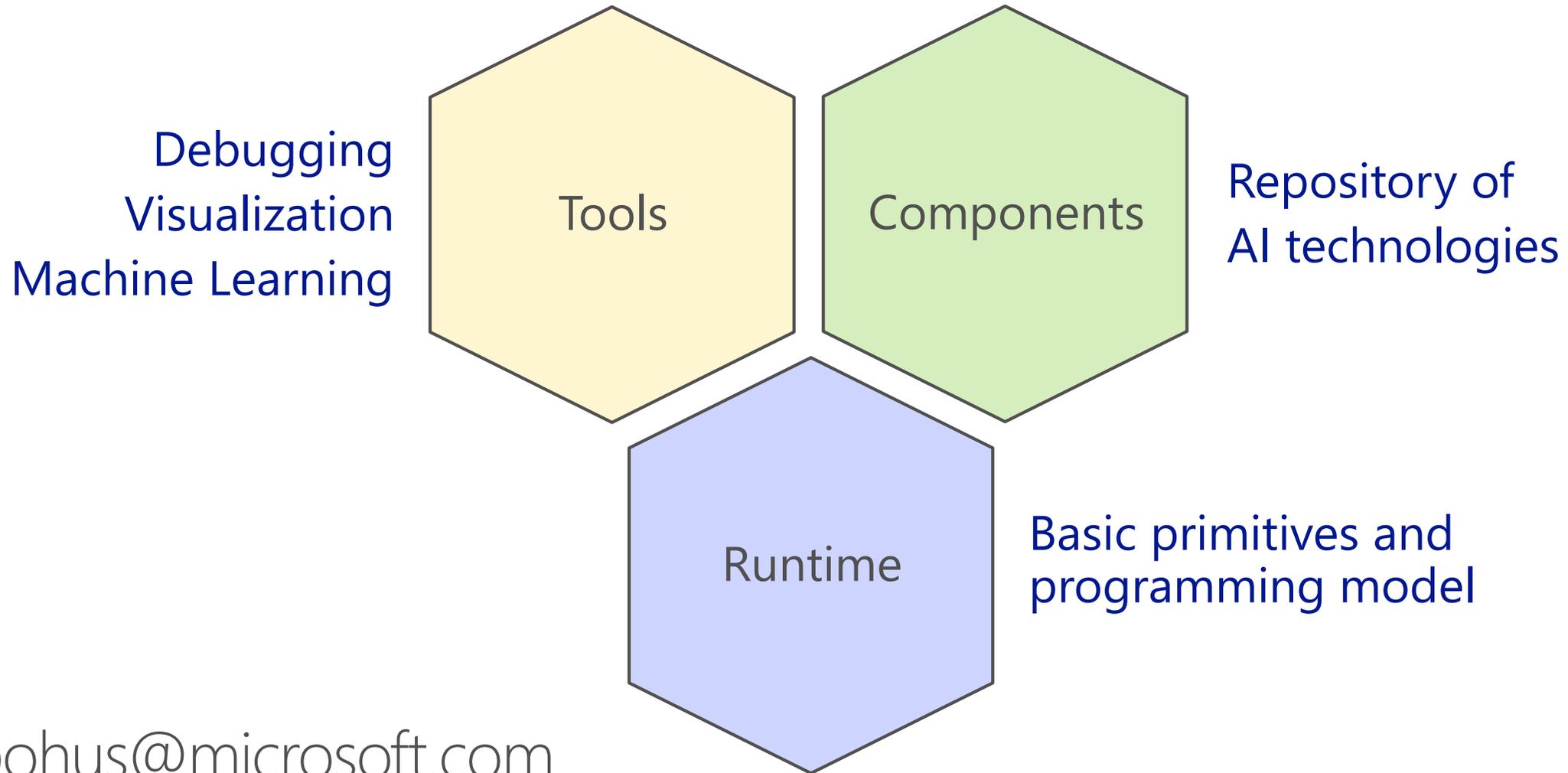
activities, plans and goals

space and time

situated language



Platform for Situated Intelligence



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